

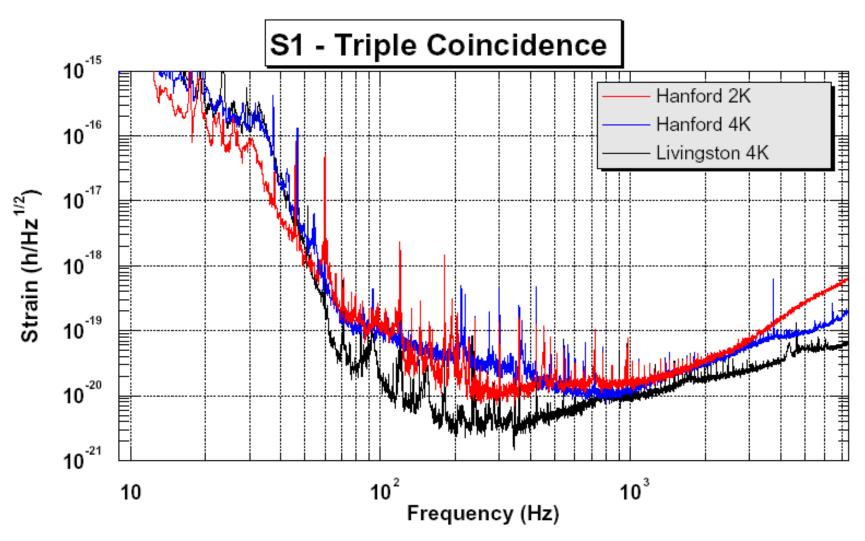
"First Science Run at Livingston LIGO Observatory: Data calibration and stability"

Gabriela González Louisiana State University

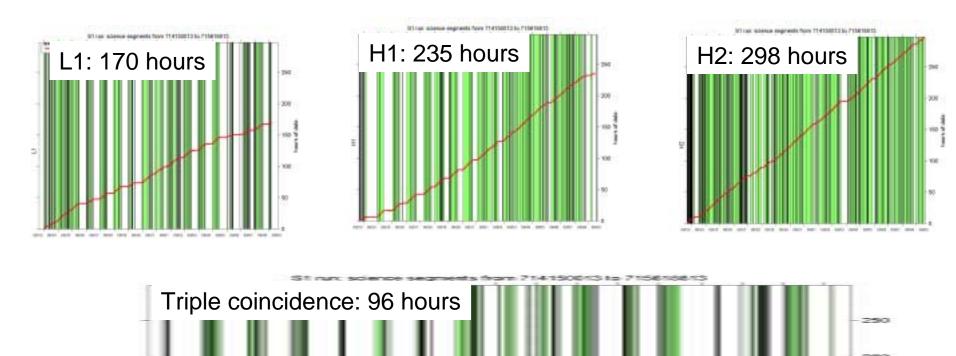




S1 run: Aug 23-Sept 9



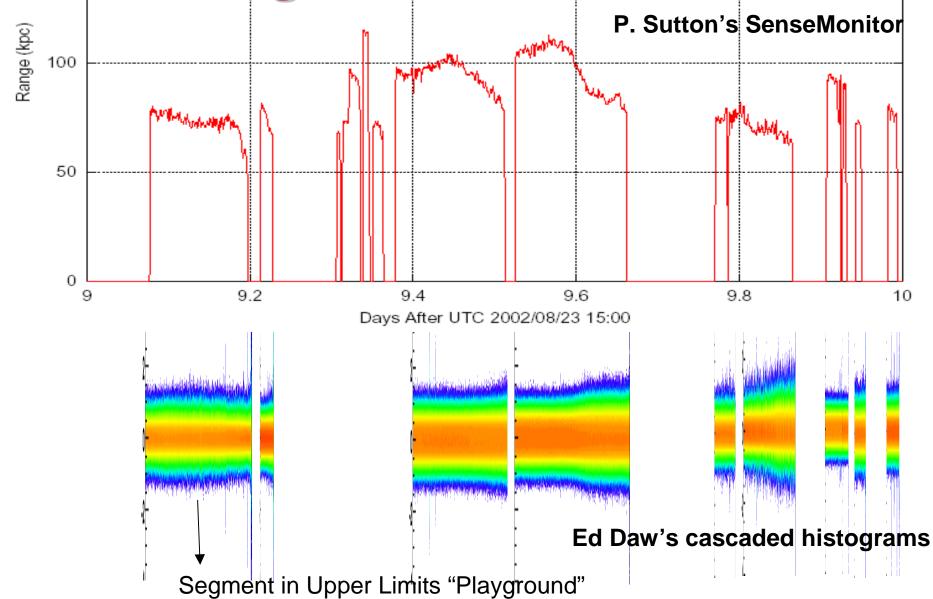
Lots of data...

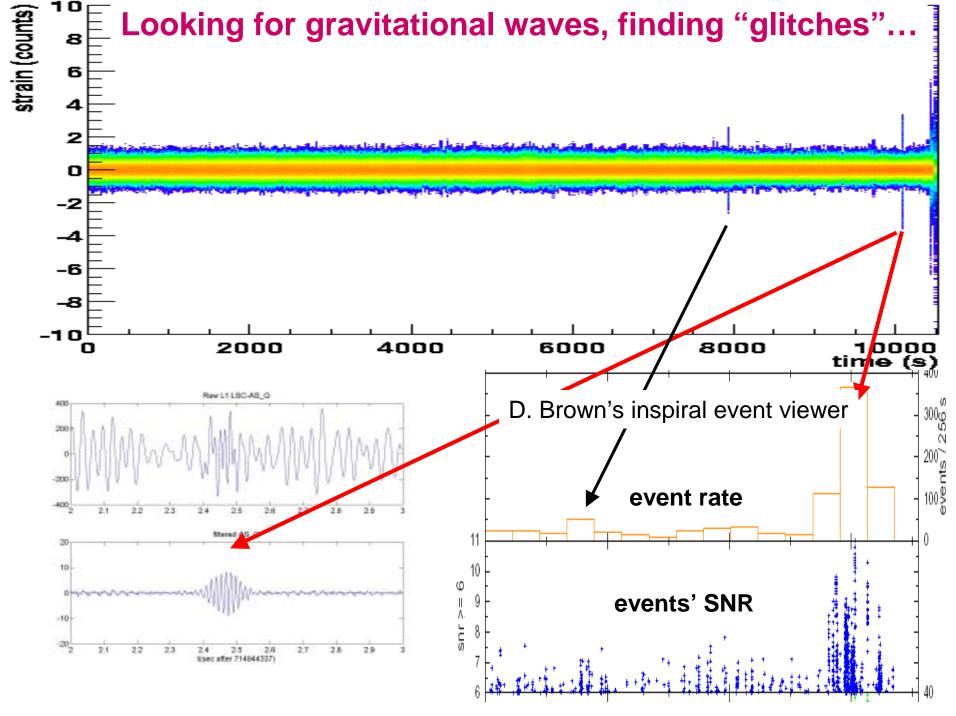


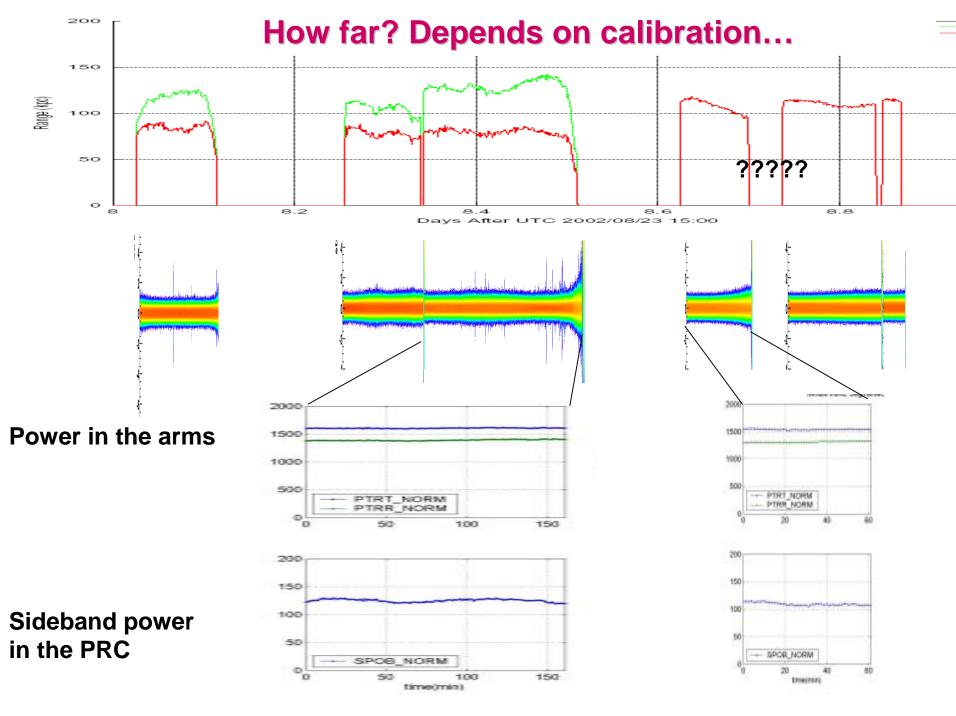
http://www.phys.lsu.edu/faculty/gonzalez/S1LockStats/

1. H ING H2

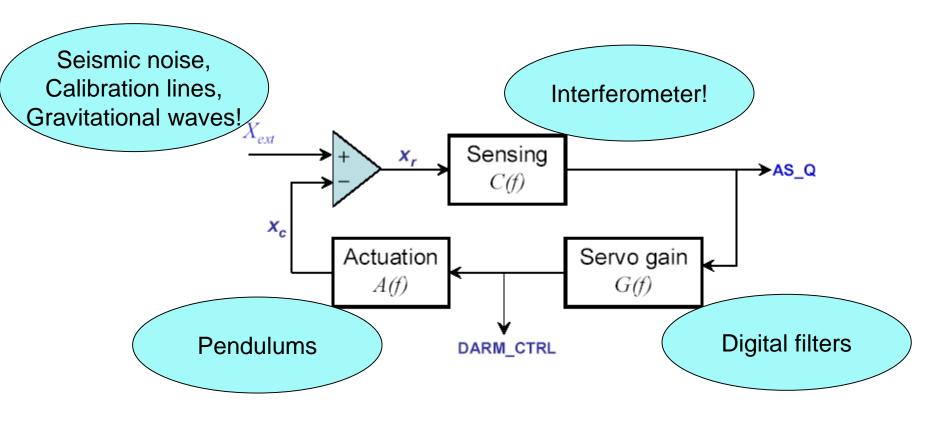
Looking farther than ever before







Calibration? What calibration?



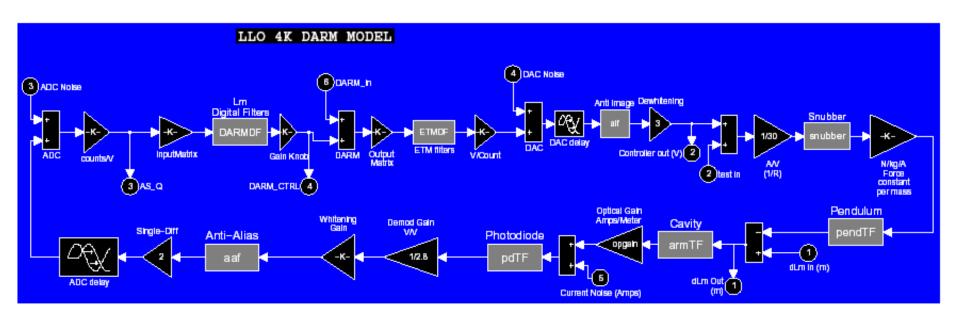
$$H(f) = A(f)C(f)G(f)$$

Open Loop Gain

$$AS_Q = X_{ext} \frac{C(f)}{1 + H(f)}$$

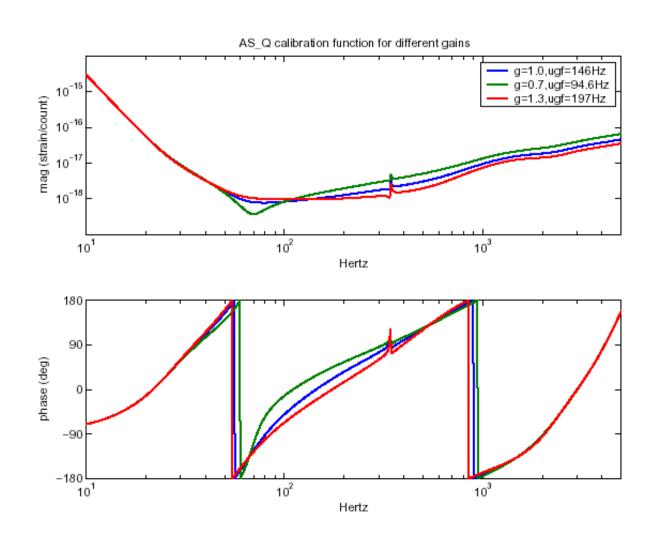
Calibration of AS_Q

A "simple" DARN model

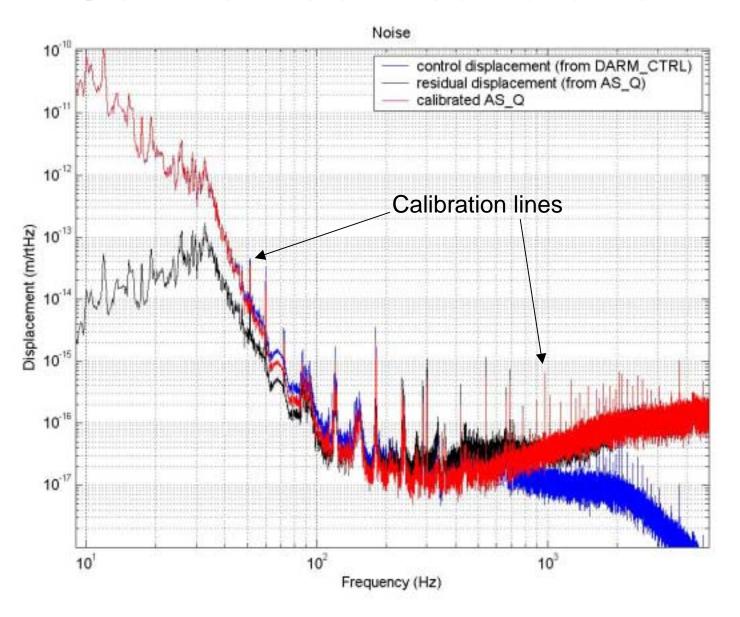


Rana Adhikari's Simulink model

Why does calibration matter?



Control room calibration

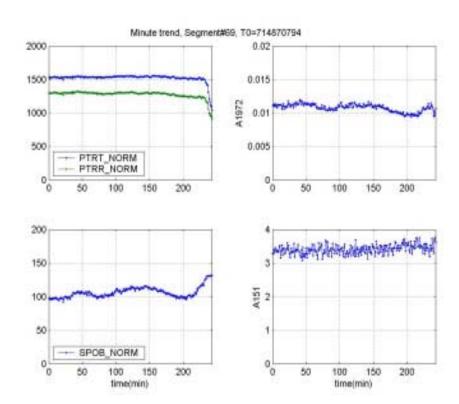


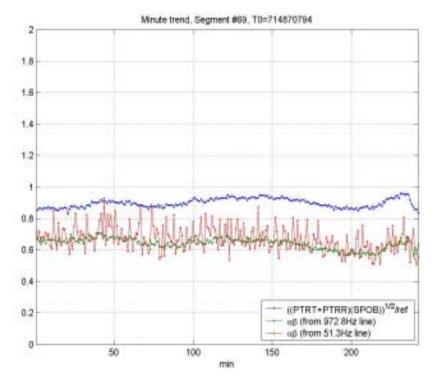
Why would calibration change?

If
$$C(f) \to \alpha C(f)$$
, $AS_{-}Q \to X_{ext} \frac{\alpha C(f)}{1 + \alpha H(f)}$.

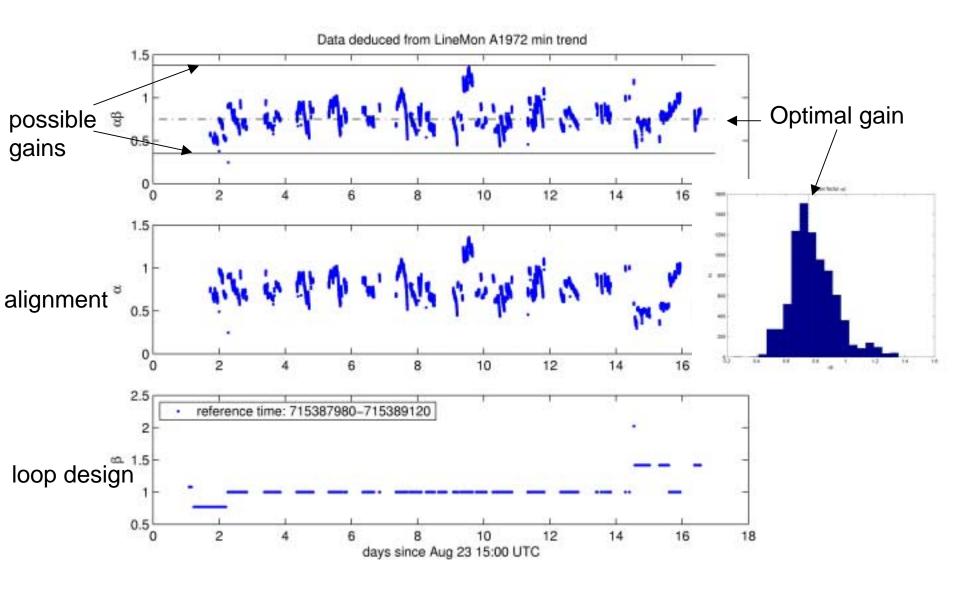
$$G(f) \to \beta G(f)$$
 $AS_Q \to X_{ext} \frac{\alpha C(f)}{1 + \alpha \beta H(f)}.$

We can get information about a from changes in the amplitude of known displacements: we push the mirrors with sine waves, or "calibration lines".

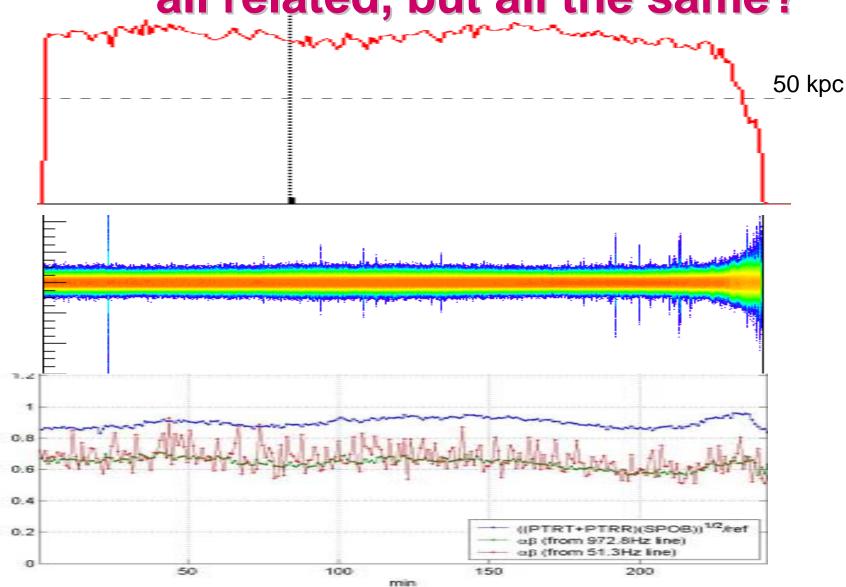




How much did the calibration change?

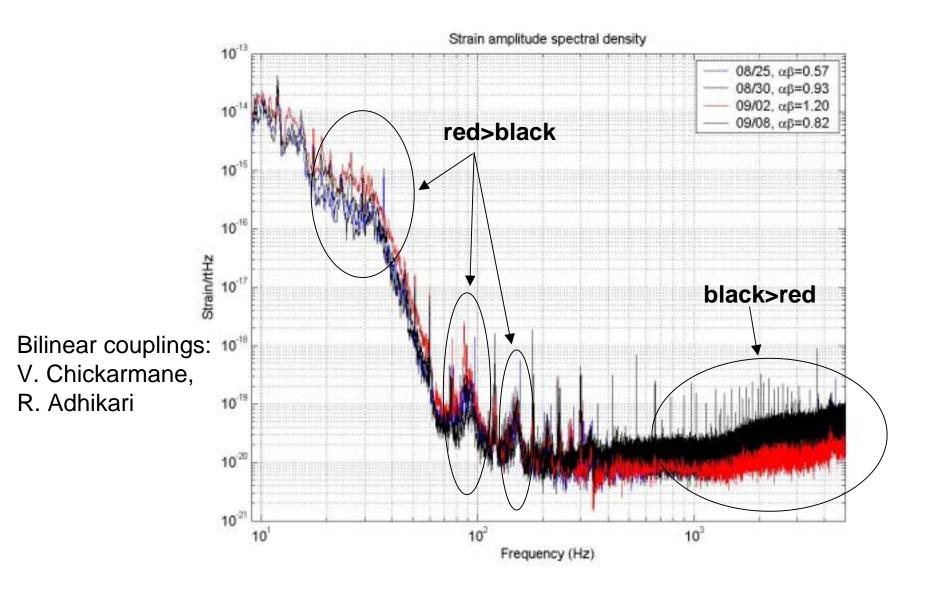


Range, histograms, calibration: all related, but all the same?



Not really:

gain is not the only indicator of noise (or even a good one)



Conclusions

There's a lot of work to do!

- Understand the noise:
 - Dominant sources
 - Not-so-dominant sources
 - Model comparison
 - ...
- Find out a good tracking calibration method
- Keep the alignment controlled so that the calibration does not change!
- Find good criteria to evaluate performance in REAL TIME