

Advanced
LIGO UK

OSEM Development UK Advanced LIGO project

Stuart Aston

University of Birmingham for the UK Advanced LIGO Team

LSC Livingston, March 2004

LIGO-G040064-00-K

- **Requirements:**
 - Generic OSEM Requirements
 - OSEM Noise Performance Requirements
- **OSEM Development Concepts:**
 - Geometric based OSEMs
 - Interferometer based OSEM
 - Performance Summary
- **Conclusions:**
 - OSEM Recommendations

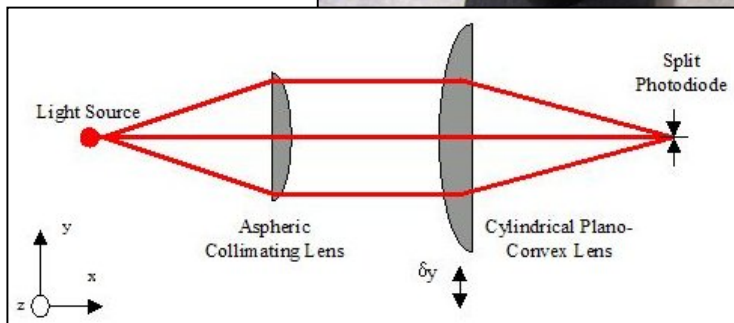
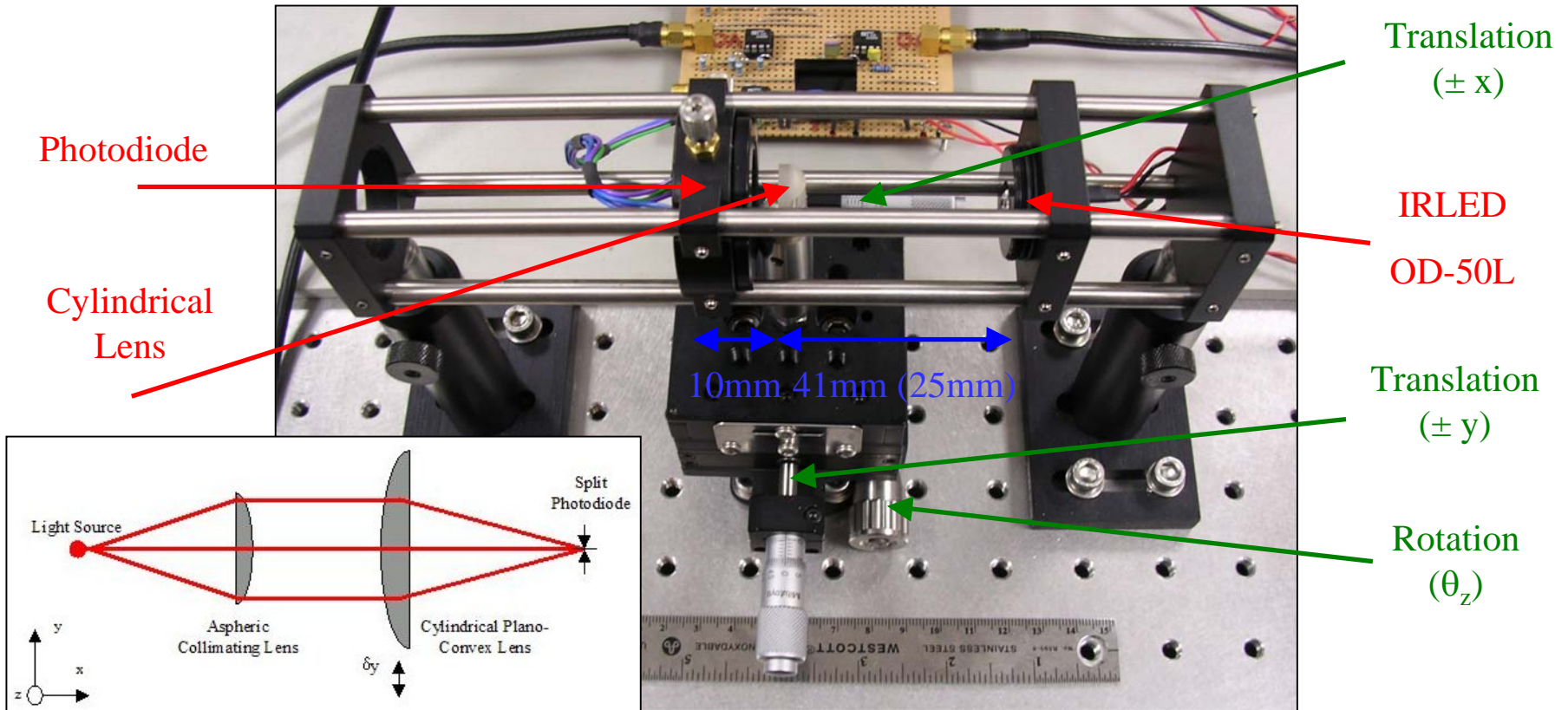
- **Range:**
 - 3mm (peak-peak) working range (1.06mm *rms*), incorporating:
 - ± 1 mm operating range
 - $\pm \frac{1}{2}$ mm tolerance for relative positioning of OSEM and sensed mass
- **Fit: (sensors must fit actuator)**
 - Sense motion of mass through bore hole of coil former
 - Constraints (for the case of the TM quad) restrict layout envelope to 40mm (diameter) x 70mm (length), including connectors and mounts
- **Vacuum Compatibility:**
 - Sensor components must meet the vacuum compatibility requirements appropriate to an Advanced LIGO vacuum chamber
- **Electrical Compatibility:**
 - Sensor drive and output must be compatible with the specification of cables passing through the SEI system (ideally using LIGO cables)

- **Sensitivity Requirements for Local Control OSEMs:**
 - Assume Eddy current damping and ISC feedback, most stringent requirement is MC longitudinal = $1.72 \times 10^{-11} \text{m}/\sqrt{\text{Hz}}$ *
 - For more detail, see E040108-00-K
- **Sensitivity Requirements for Global Control OSEMs:**
 - Science mode noise requirement about 10Hz:
 $\approx 1 \times 10^{-10} \text{m}/\sqrt{\text{Hz}}$ *
 - This figure also encompasses:
 - Transverse horizontal sensors on all suspensions
 - Other, less critical, degrees of freedom on RM and MC
 - Note that almost half the OSEMs fit one or other of these categories

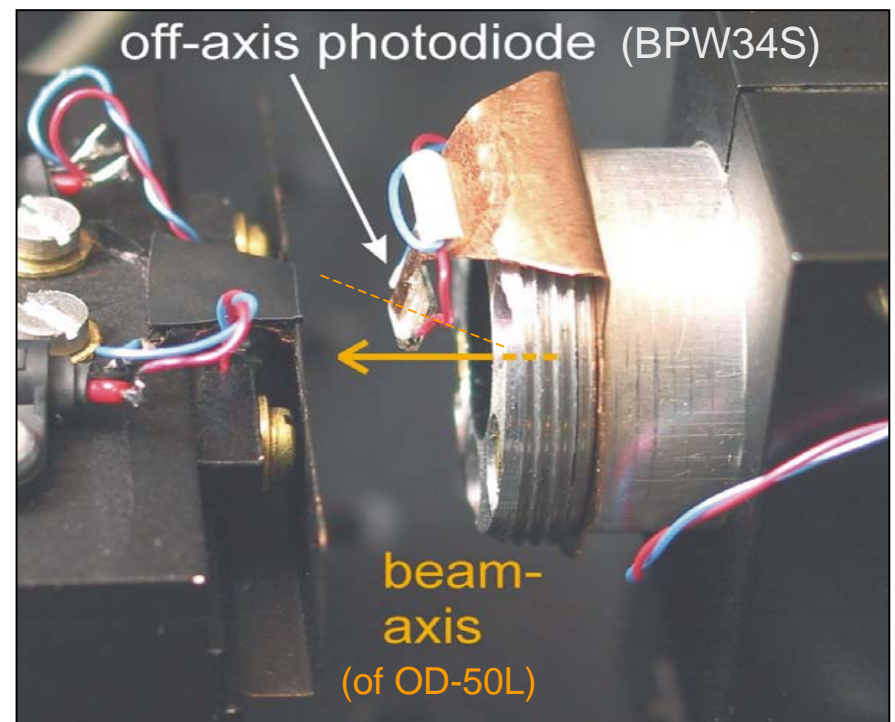
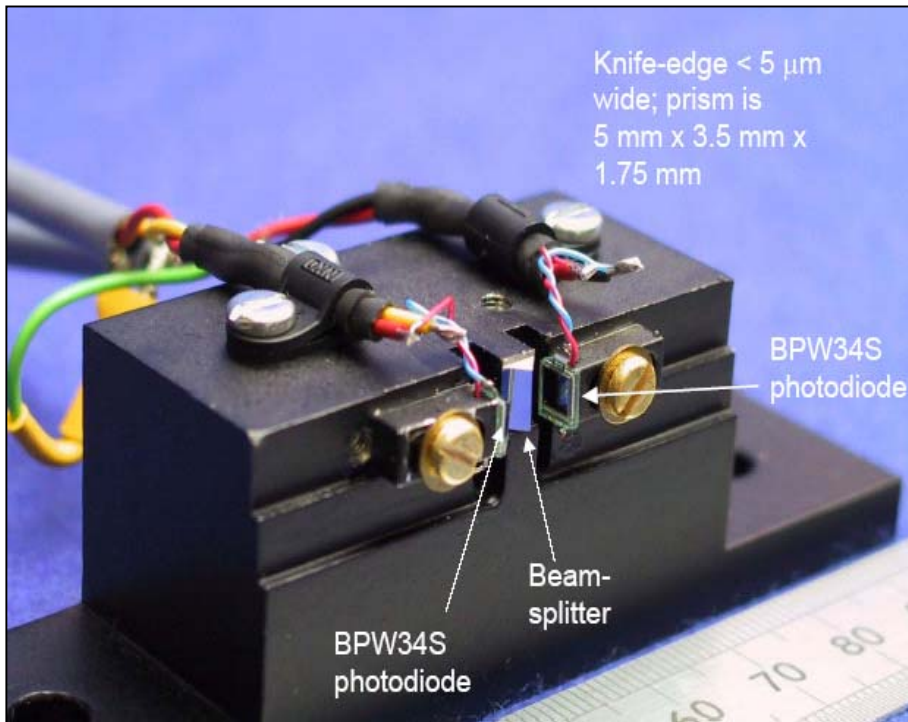
* Figures extracted from "Recommendation of a design for the OSEM sensors" document LIGO-E040108-00-K

- **Geometric Sensors:**
 - Prototype developed by C.C. Speake and S.M. Aston at the University of Birmingham
 - Parallel independent development undertaken by our collaborator N.A. Lockerbie at the University of Strathclyde
- **Basic Operation:**
 - Use a reasonably collimated and strongly modulated light source
 - High power IRLED (880nm) emitter (OP-50L)
 - Beam passes through optical system which is partly mounted on an extension of the sensed mass
 - Beam is incident on a split photodiode detector
 - Detected photocurrents are demodulated to produce sum and difference signals:
 - Difference output provides useful displacement measurement read-out
 - Sum signal enables active intensity stabilisation of emitter output

- Geometric Sensor Prototype (University of Birmingham):

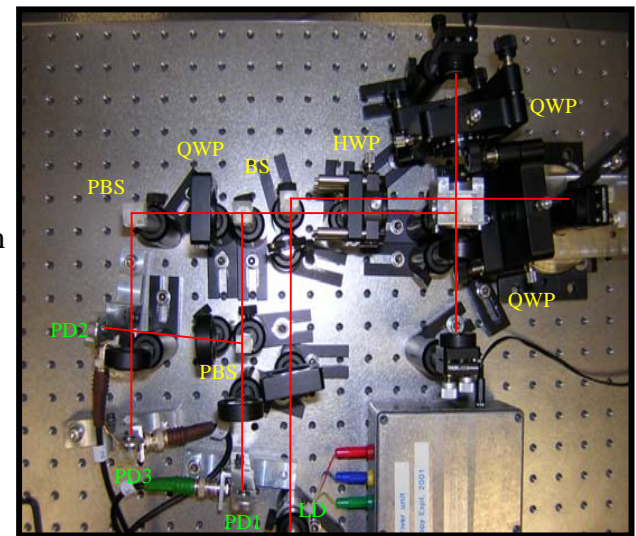
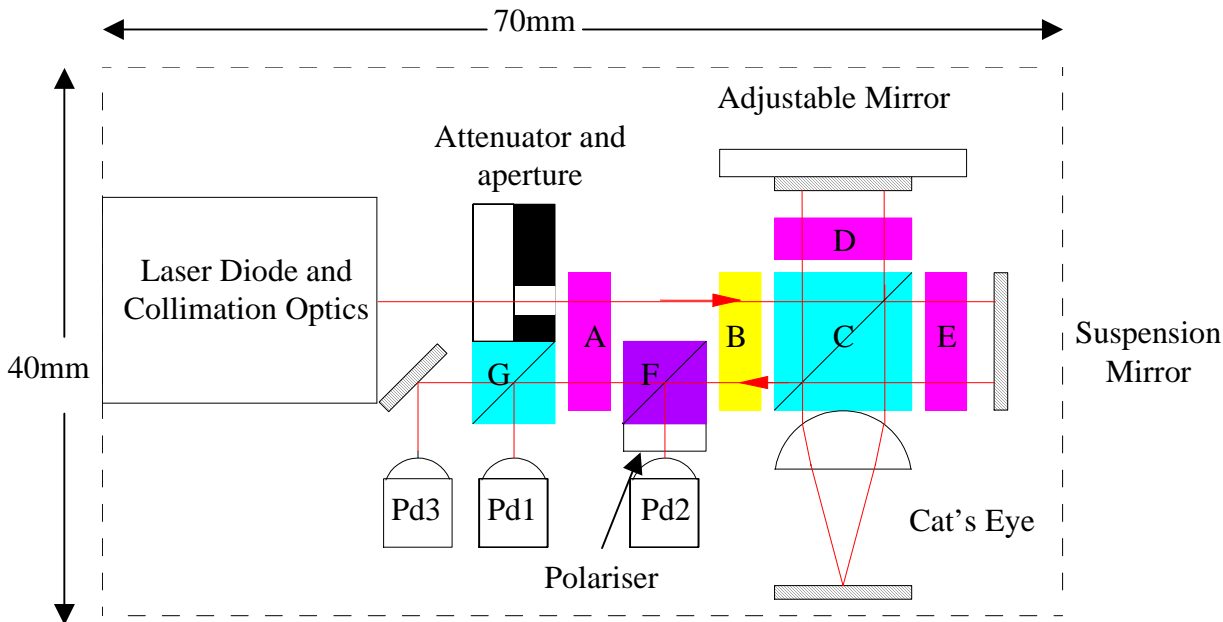







- Geometric Sensor Prototype (University of Strathclyde):



- **Interferometric Sensor:**
 - Development by C. Speake and S. Aston at the University of Birmingham
- **Basic Operation:**
 - Use a collimated laser diode light source
 - Low power (3mW) emitter (HL6314MG) at 635nm
 - 3 output interferometer has single element “bug-eye” pd’s at each output
 - Polarising beam-splitter gives quadrature outputs for 2 ports
 - 3rd port output is 180⁰ out of phase (allows subtraction of dc offsets)
 - 3 outputs are subtracted in pairs (via 2 difference amplifiers) resulting in 2 dc corrected channels to be read-out
 - Signal processing allows the fringes to be counted as well as fractional fringe measurements to be made
 - Dynamic range limited by the coherence length of the laser diode

- Interferometric Sensor Prototype (University of Birmingham):



- | | | | |
|-------------------------------------------------------------------------------------|--------------------------|-------------------------------------------------------------------------------------|------------------------------|
|  | Quarter-wave plate |  | Non-polarising beam-splitter |
|  | Polarising beam-splitter |  | Half-wave plate |
|  | Mirror | | |

- **Geometric Sensors:**

- Shot noise limited performance of $\leq 1.5 \times 10^{-11} \text{m}/\sqrt{\text{Hz}}$ about 10Hz and essentially flat down to 1Hz.
- But this result was not achievable over the whole working range!
- Common suspect component of excess noise is the IRLED emitter
- Significant risk that there are no other alternative high power, low noise and good beam quality devices available

- **Interferometric Sensor:**

- Performance of $\leq 5 \times 10^{-13} \text{m}/\sqrt{\text{Hz}}$ about 10Hz is achievable without a high power source or any modulation scheme
- Perceived risk in complexity of construction and laser diode noise performance and MTBF (device screening maybe required)

- **OSEM Recommendations:**
 - We recommend the use of the interferometric design wherever high sensitivity is required together with basic (modified) initial LIGO OSEMs for global control and certain other locations
- **Summary of Rationale:**
 - Interferometric concept is the most secure approach to reaching the sensitivity requirement
 - Higher component cost partly offset by possible elimination of eddy current dampers