Advanced LIGO Seismic Isolation Status

Rich Abbott, Graham Allen, Drew Baglino, Colin Campbell, Dennis Coyne, Daniel DeBra, Jeremy Faludi, Amit Ganguli, Joe Giaime, Marcel Hammond, Corwin Hardham, Jay Heefner, Wensheng Hua, Jonathan Kern, Joe LaCour, Brian Lantz, Ken Mailand, Ken Mason, Rich Mittleman, Jamie Nichol, David Ottaway, Joshua Phinney, Bill Rankin, Norna Robertson, Kyle Ryan, Pradeep Sarin, Ray Scheffler, David Shoemaker, Oddvar Spjeld, Joe van Niekerk, LIGO CDS, and the Livingston Staff

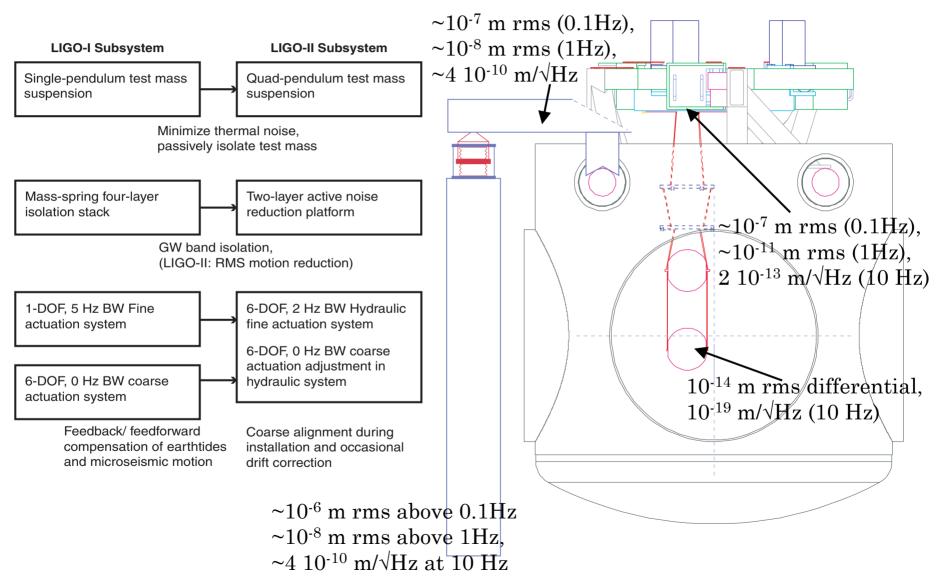




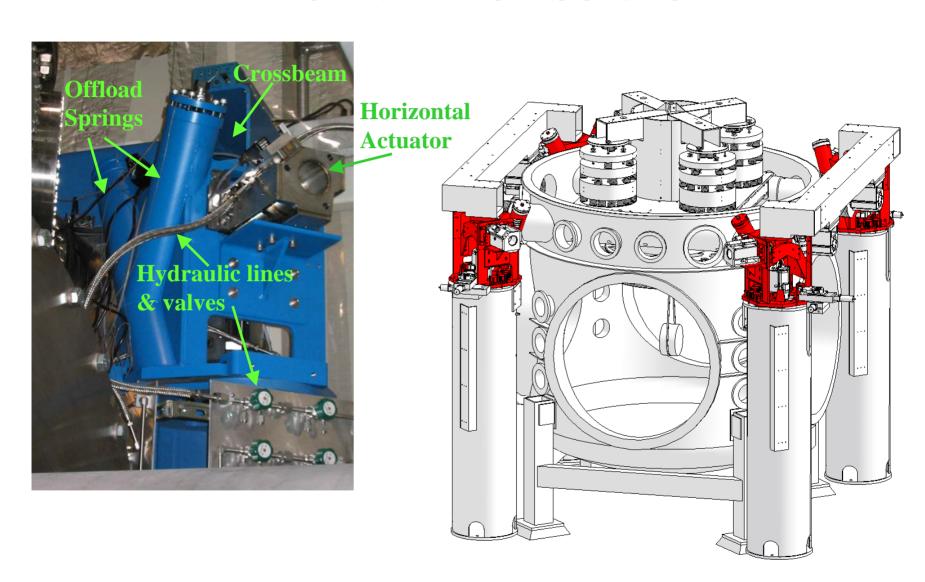




Seven Layers of Isolation and Alignment

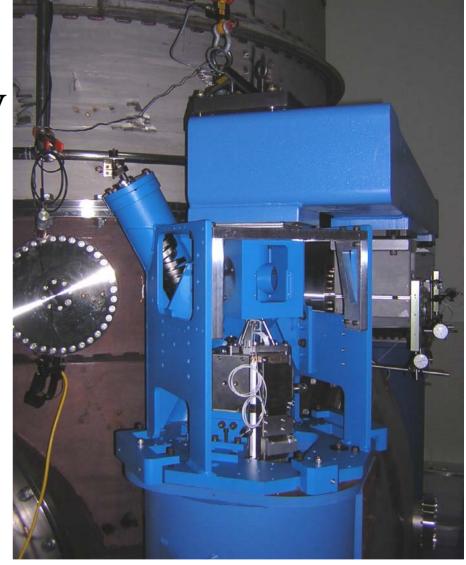


External Pre-Isolator



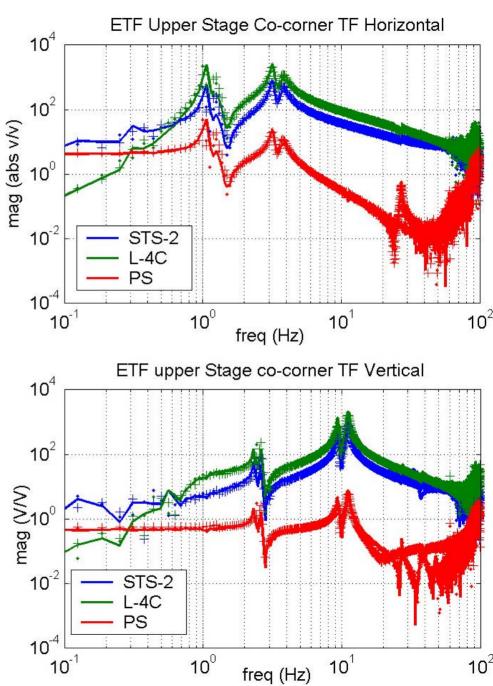
Pre-Isolator, finally getting a real job...



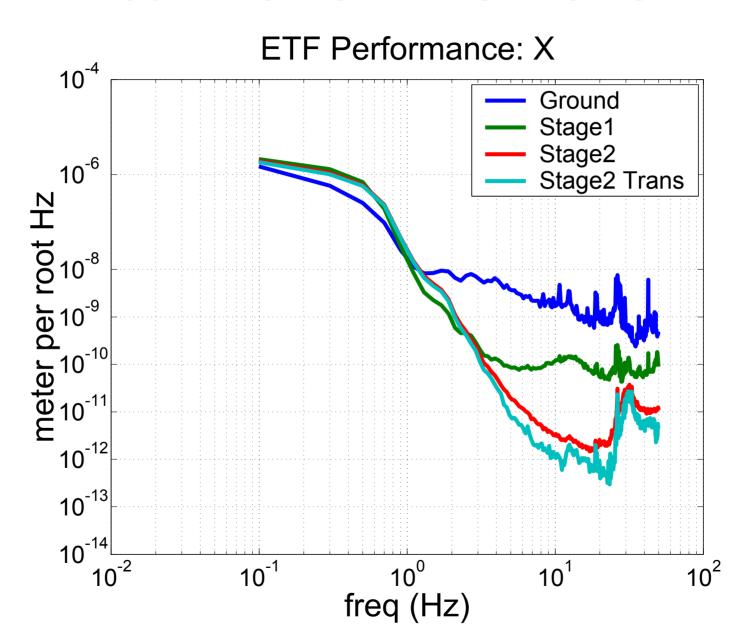


ETF Tech Demo Sys-ID

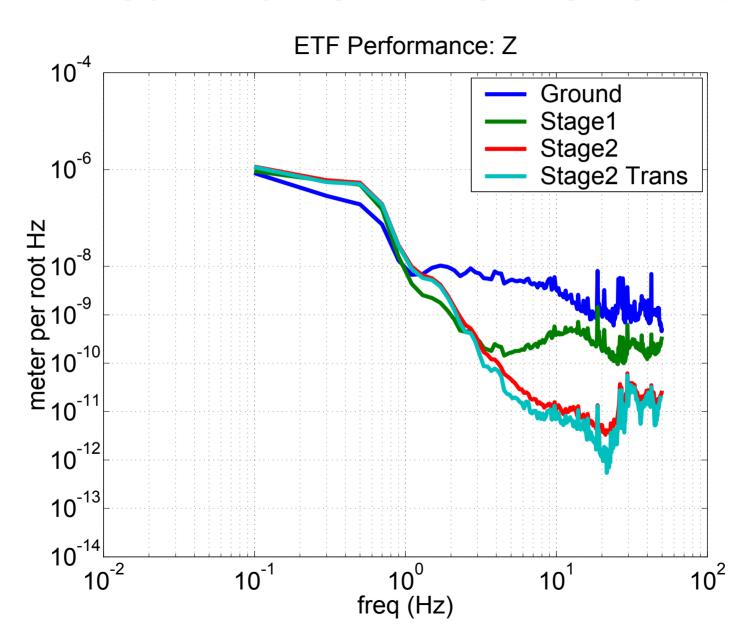




ETF Tech Demo - First Performance



ETF Tech Demo - First Performance





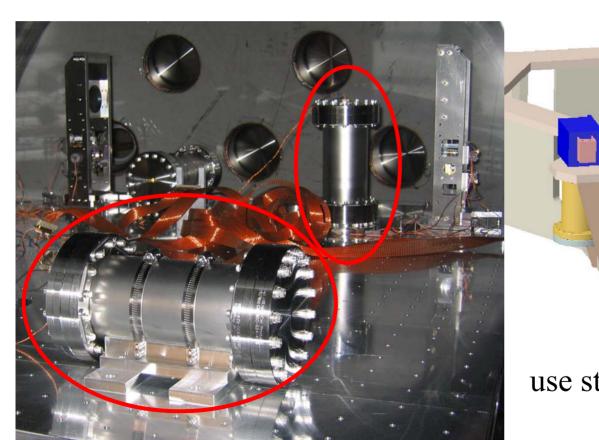
The LASTI prototype

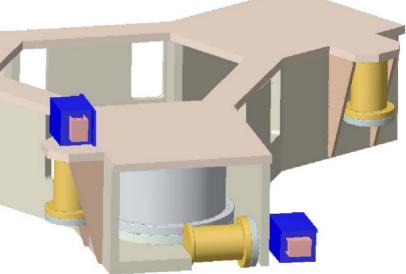
Compatible with LIGO-vacuum

Supports all of the optic payloads for Advanced LIGO, with good performance

LASTI Prototype - Sensors

working to make the sensors LIGO-vacuum compatible

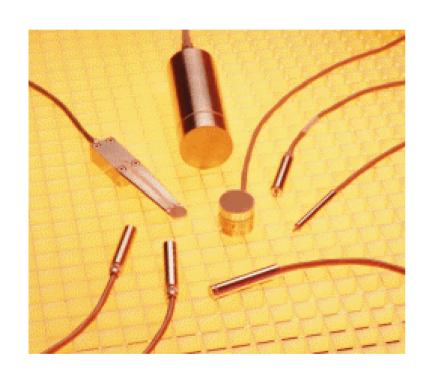




use standard conflat hardware

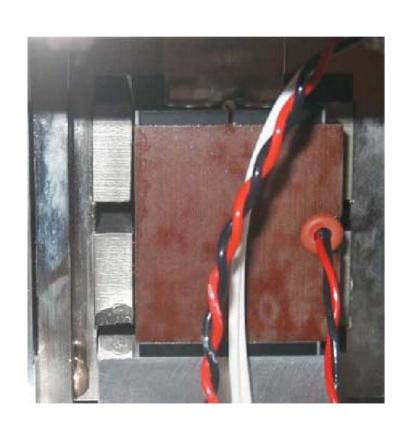
example of technique, at LASTI

LASTI prototype - Sensors



Capacitive sensor ought to be vacuum compatible — "just" wires and plates
Larry, Kyle, LIGO ringdown ovens working to OK the coax cables, epoxies

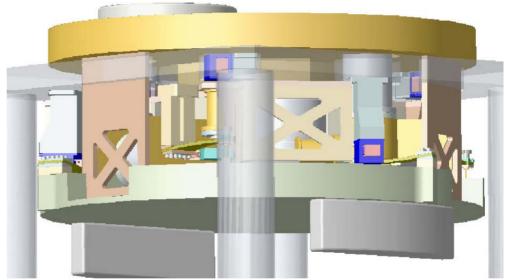
LASTI Prototype - Actuators



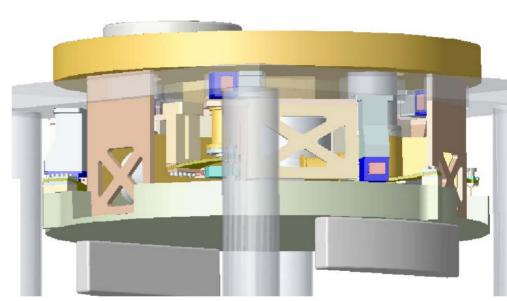
ongoing contract talks with vendors to make an Advanced LIGO version.

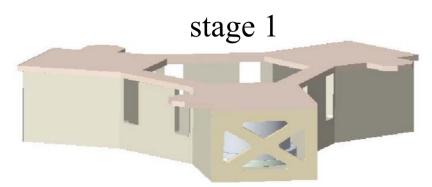
LIGO-compatible materials, good thermal properties, good magnet field geometry.



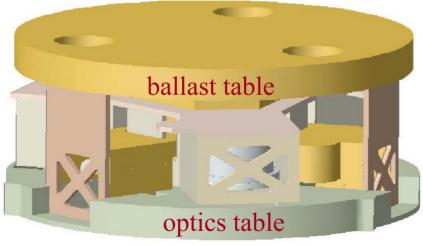


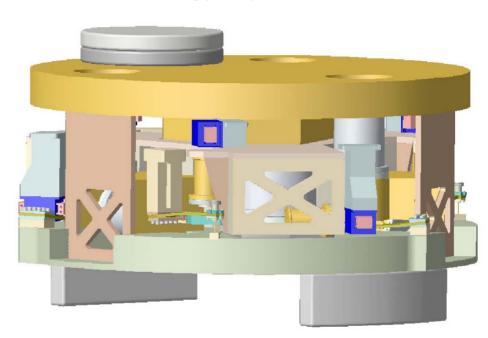
design by Alliance Space-systems Inc. (ASI)

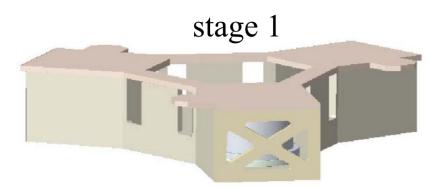




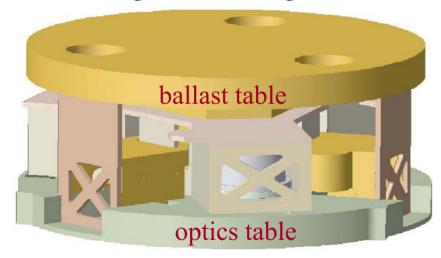
stage 1 and stage 2

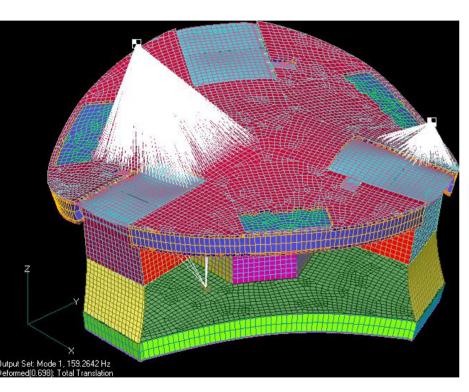


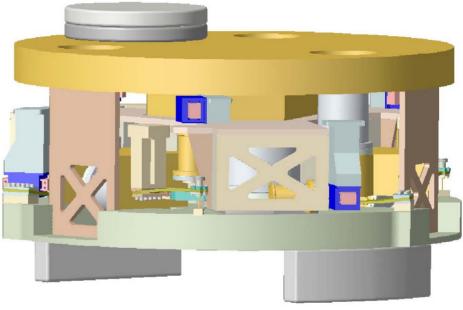




stage 1 and stage 2

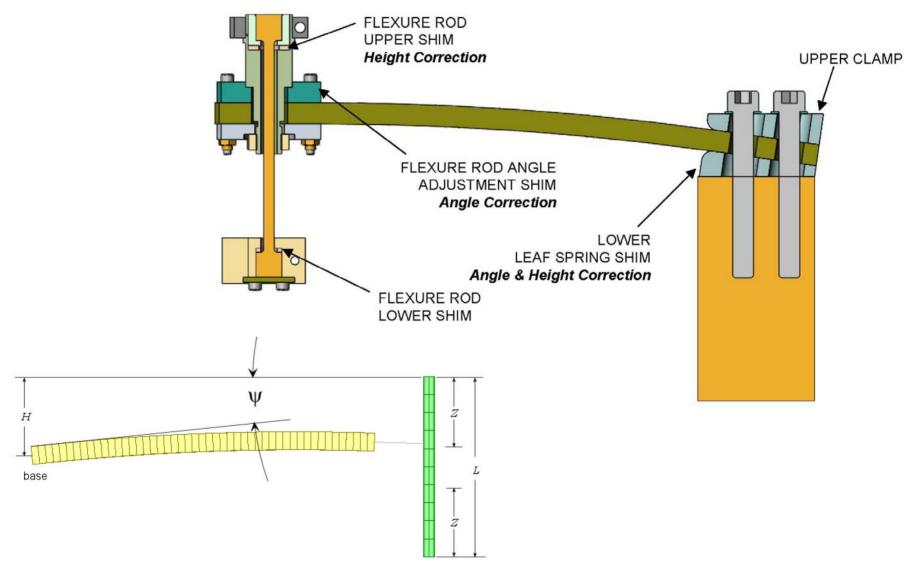






modal analysis with reasonable models of sample payloads look good

Spring redesign



The Plan...

External Pre-Isolator commissioning goes forward Internal two-stage prototype coming together

- Control development should make great progress over the next 6 months.
- Sensors and Actuators making progress.
- Mechanical Design going forward very quickly.

BSC review ~ April 20

HAM review ~ May 5

Delivery to LASTI end of October 2004