

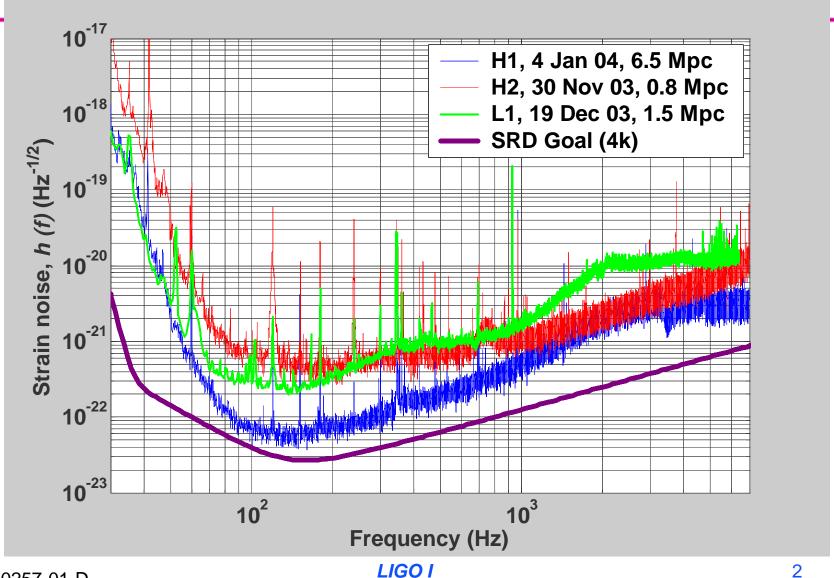
LIGO Commissioning Update

PAC Meeting, June 3, 2004 Dennis Coyne

[update of Peter Fritschel's LSC Talk, G040066-00, 3/16/2004]

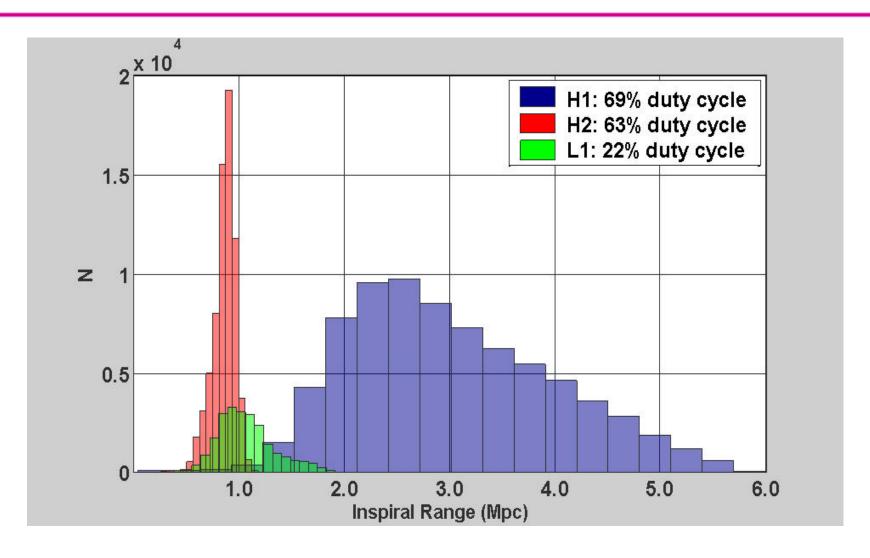


S3: peak sensitivities





S3: reliability & stability





Major Goals and Tasks After S3

Sensitivity

- Operate at high power: achieve designed optical gain
 - Laser
 - Thermal compensation system (TCS)
 - Improved anti-symmetric port detection efficiency (Output mode cleaner (OMC) or more RF photodetectors)
- ➤ Finish(?) environmental effects mitigation (acoustics, dust, HVAC pulsing, ...)
- Manage noise in auxiliary degrees-of-freedom
- Clean up electronics: RFI mitigation

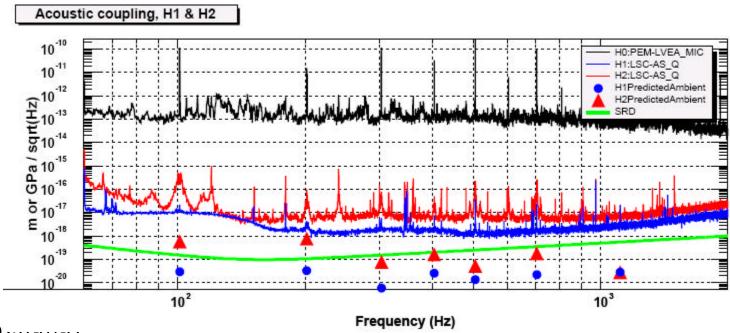
□ Reliability & Stability

- Seismic retrofit at LLO: HEPI
- > Auto-alignment system: all degrees-of-freedom, at full bandwidth
- Address causes of lock-loss



Acoustic Mitigation

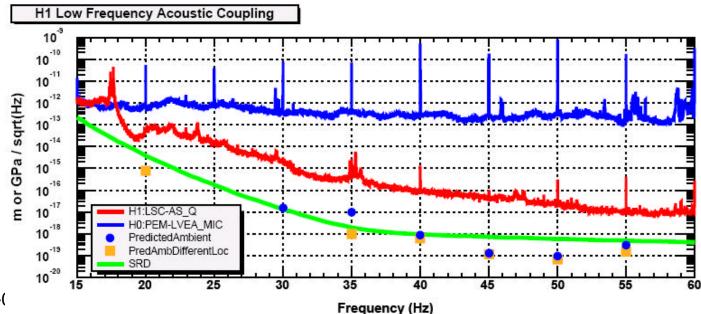
- □ Recall: significant improvements between S2 & S3
 - > Problem: acoustical vibrations of optical elements in the output beam path
 - No acoustic peaks left in S3 spectra
 - Acoustic enclosures around AS port sensing tables: ~10x reduction
 - Improvements and simplifications to beam sensing path: ~10x
- □ Original goals: 100x-1000x reduction, reached for H1





Acoustic Mitigation (2)

- □ Raise the bar at LHO: H1-H2 stochastic b.g. potential
 - ➤ H1 sensitivity now dominated by reflection port table: continue improvement/simplifications of this beam path
 - Reduce continuous sources: house or move electronics cabinets
 - Moving cabinets as part of the EMI retrofit at LLO, pre-S4
 - EMI retrofit is post-S4 for LHO; Investigating cost & "wisdom" of acoustically shielding racks in existing location
- New data on lower frequencies: seismic/acoustic
 - > HVAC the main source: no easy improvements
 - Investigating 'floating' the detection tables on low-frequency mounts



More environmental effects

Dust in table enclosures

Gets stirred up by entries, takes a while to settle down

Causes glitches when it falls through the beam

➤ To be addressed with HEPA filters, and/or covers over the beam path

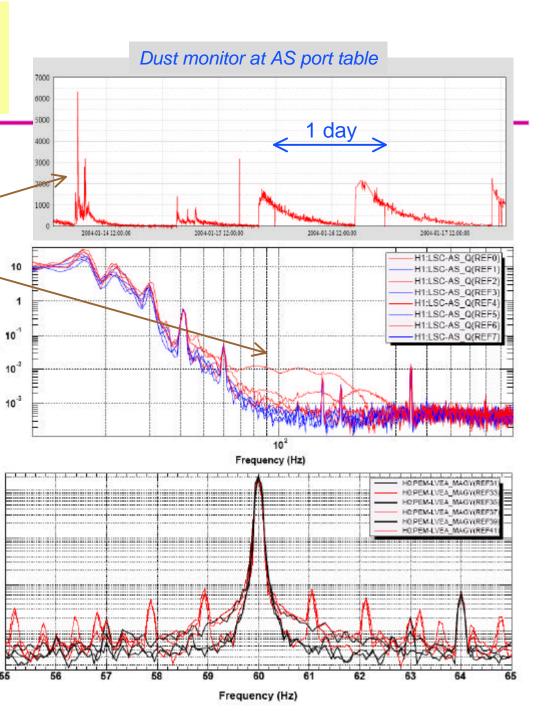
Magnitude

Magnitude

■ HVAC in-duct heaters

- Pulsing produces ~1 Hz sidebands around 60 Hz; couples magnetically to AS_Q
- Purchasing new heater controls to mitigate the effect (from SCR to staged heating)

G040257-01-D





Optical gain: "10 W" laser

□ Current input power levels:

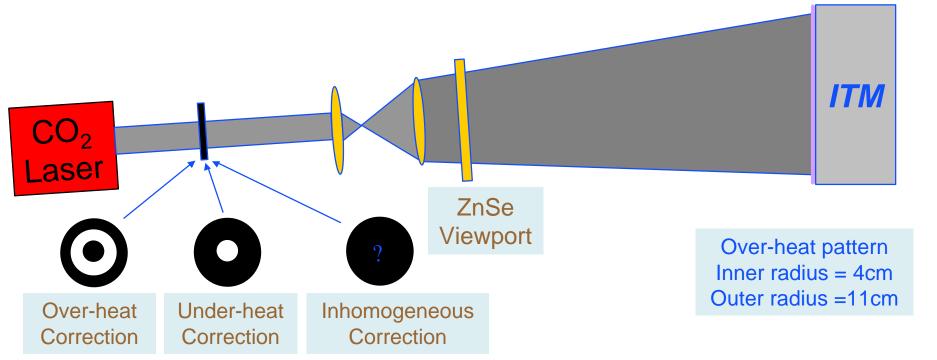
	H1	H1 Reworked	H2	L1	Design
Laser output	4.9 W	11.0 W			
Mode cleaner input	3.6 W	7.6 W	3.7 W	6 W	8 W
Recycling mirror input	2.3 W		2.6 W	3.6 W	6 W

Plan

- Get H2, L1 LWE lasers back up to spec, including 1 spare before S4
- ➤ Improve PMC transmission (H1 increased from 67% to 82%)
- Diagnose suspended mode cleaner loss (20-30% lost)
- ➤ Input electro-optic modulators: reduce number from 3 to 1 wideband with multiple modulation



Thermal Compensation

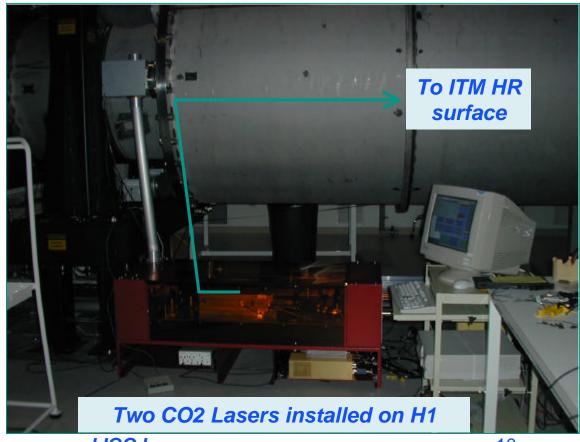


- ➤ Cold power recycling cavity is unstable: poor buildup and mode shape for the RF sidebands
- ➤ ITM thermal lens power of ~0.00003 diopters needed to achieve a stable, mode-matched cavity



TCS Installation

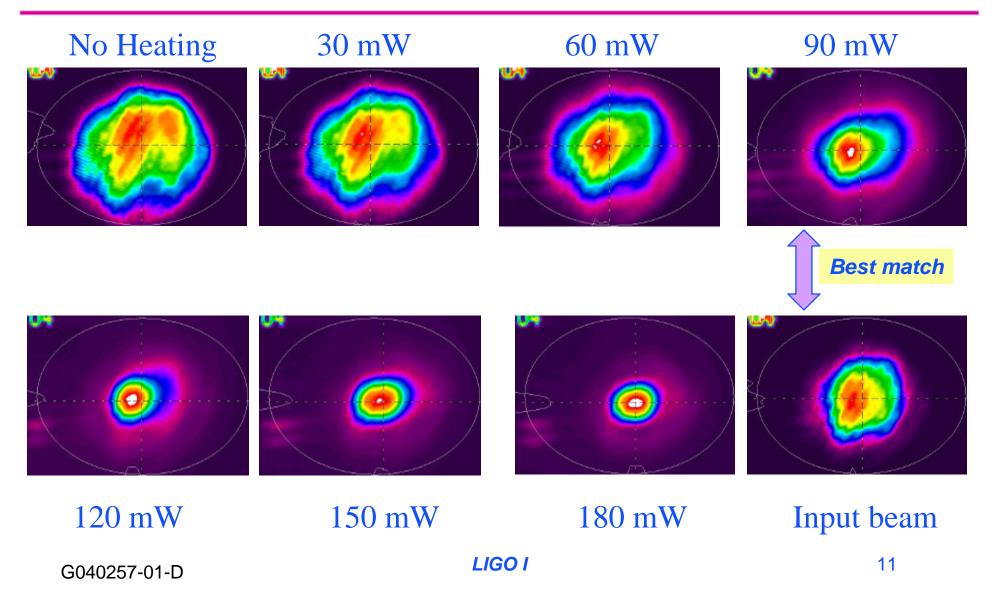
- □ Two CO2 Lasers are installed on H1
- ☐ Two more TCS systems (4 lasers) are being procured/fabricated for H2 and L1
- □ Assembly & Installation will start 6/7
- Commissioning expected to be completed ~8/1 on H2 and L1



G040257-01-D LIGO I



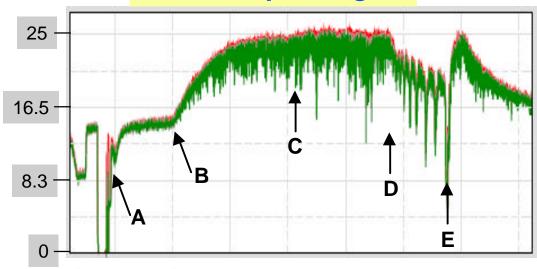
TCS on the power recycled Michelson: beam images at AS port



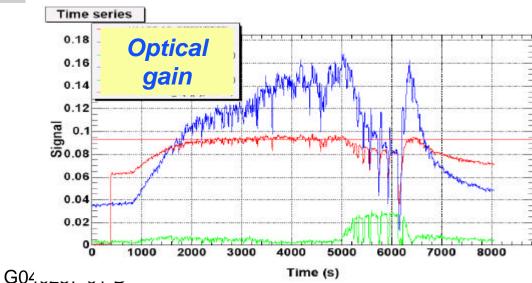


Full Interferometer Results

Sideband power gain



- A. Lock interferometer at 1 Watt
- B. Apply 45 mW Common central heating
- C. Increase to 60 mW
- D. Increase to 90 mW
- E. Turn off TCS



- ➤ AS_Q gain: increases by 40%
 - doesn't increase as fast as expected
- ➤ PRC & MICH (pick-off) gains increase by factor of 4
 - ❖ gain scales as (G_{SB})²



Summary of TCS Results

State	GSB
State 2 cold	7.0
State 2 hot (90 mW CO ₂)	12.5
State 2 max $(tRM/(1 - rRM rM rITM))^2$	<i>14</i>
State 4 cold	13
State 4 warm (0.8W input)	16
State 4 hot (2.3W input, no TCS)	20
State 4 hot (0.8W input, 45mW CO2)	26.5
State 4 max $(tRM/(1 - rRM rM))^2$	<i>30</i>

G040257-01-D LIGO I 13



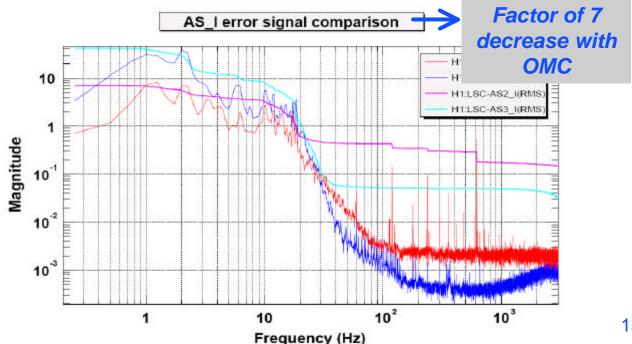
Output mode cleaner: motivation

- □ Reduction of AS_I signal
 - Power in orthogonal phase limits the amount of power per AS port photodetector & AS_I servo is noisy
 - Produced by alignment fluctuations: TEM_{01/10} modes would be removed by an OMC
- Improvement in shot noise sensitivity
 - Reduction of noise-producing (higher-order mode) power
- □ Potential saturation at 2f_m at higher power



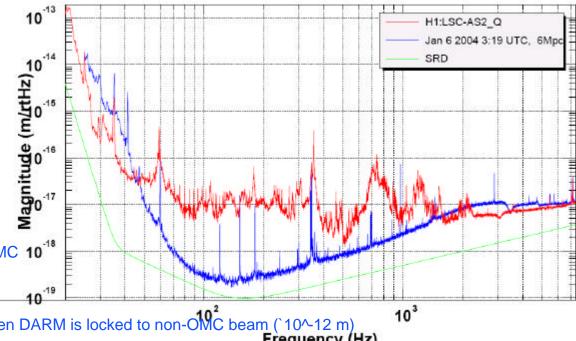
Output Mode Cleaner (OMC) (2)

- GEO output mode cleaner a good fit for initial testing
 - > On loan from GEO for several months
 - Finesse is ~40
 - **Transmission:**
 - Michelson bright fringe: 70% (30% reflected)
 - ❖ Full IFO dark port: T/(R+T) = 23%





Output Mode Cleaner (OMC) (3)



- Installation and testing on H1
 - Began mid-April & continues
 - > AS port spectrum:
 - ❖ Carrier is ~50% of total before OMC 10⁻¹⁸
 - Carrier is ~2% of total after OMC
 - Locked OMC using AS_I signal
 - ❖ Observe offset in OMC signal when DARM is locked to non-OMC beam (`10^-12 m)
 - ❖ Laser amplitude noise sensitivity is reduced at high frequencies (>100 Hz)
 - * AS I signal reduced by a factor of 7 with the OMC
 - Noise observations:
 - ❖ Noise of post-PMC signal > pre-OMC signal
 - * Extremely sensitive to tapping mounts or any added acoustic energy (in vacuum or not, suspended or not)
 - Next?
 - Continue to understand noise source/sensitivity
 - Unlikely to reduce noise by factor of ~1000
 - Pursue vacuum & seismically isolated optical train thru OMC
 - Pursue multiple RFPDs on the AS port



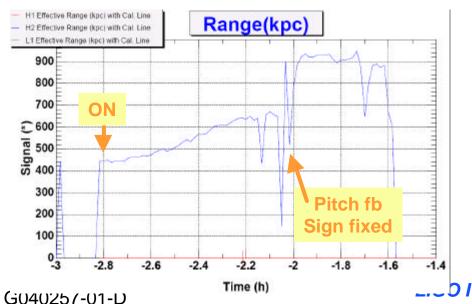
Alignment Control

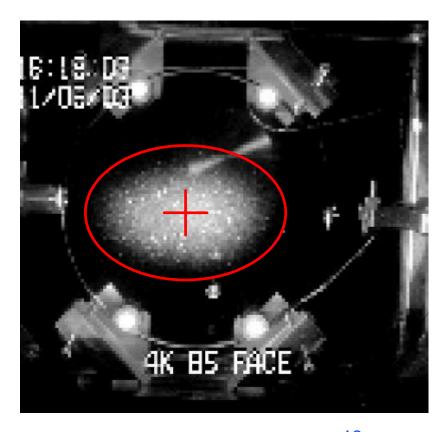
- ☐ Continued incremental progress on WFS/QPDs ...
 - Goals:
 - ❖ Sufficient gain/bandwidth to reduce power fluctuations to ~1%
 - ❖ Turn off optical lever angular control: too noisy
 - Manage WFS/QPD noise coupling to AS_Q
 - Status, H1 (post-S3 progress)
 - ❖ Bandwidth now at 2.2 Hz for all but one WFS: effect not fully characterized
 - Some noise reductions made, still an active issue
 - Initial alignment steps now fully automated
 - Controls software upgrade: sensor input matrix; compensate radiation torques; compensate for optical gain change; not yet fully characterized
 - WFS feedback to mode cleaner mirrors; not yet fully characterized



Beam centering

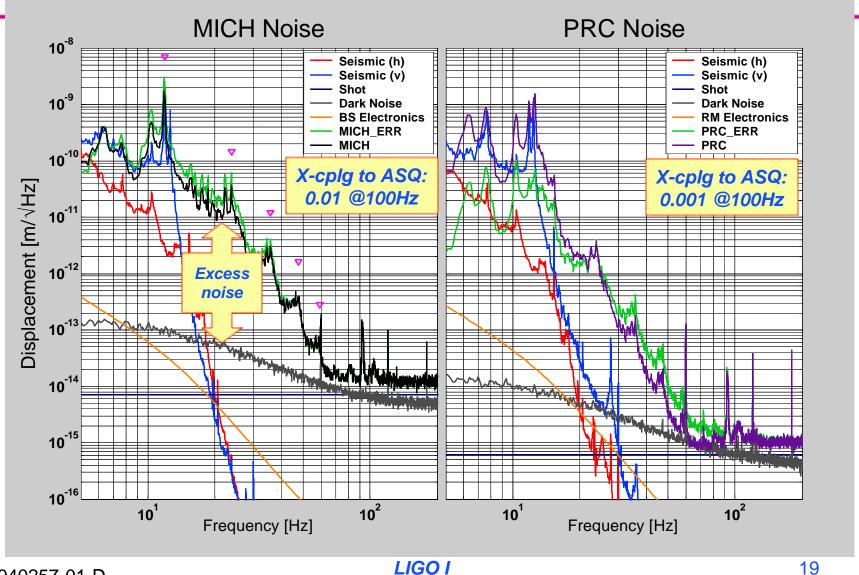
- ☐ Transmission QPDs hold the beam position fixed at the ETMs
 - Need to independently find the right spot (w/in 1mm of center)
- WFS control all mirror angles: only DOF left is the beam position in the corner
- New servo:
 - Capture image of beam scatter from BS face
 - Image processing to determine position of beam center
 - Slow feedback to input telescope to fix BS beam position





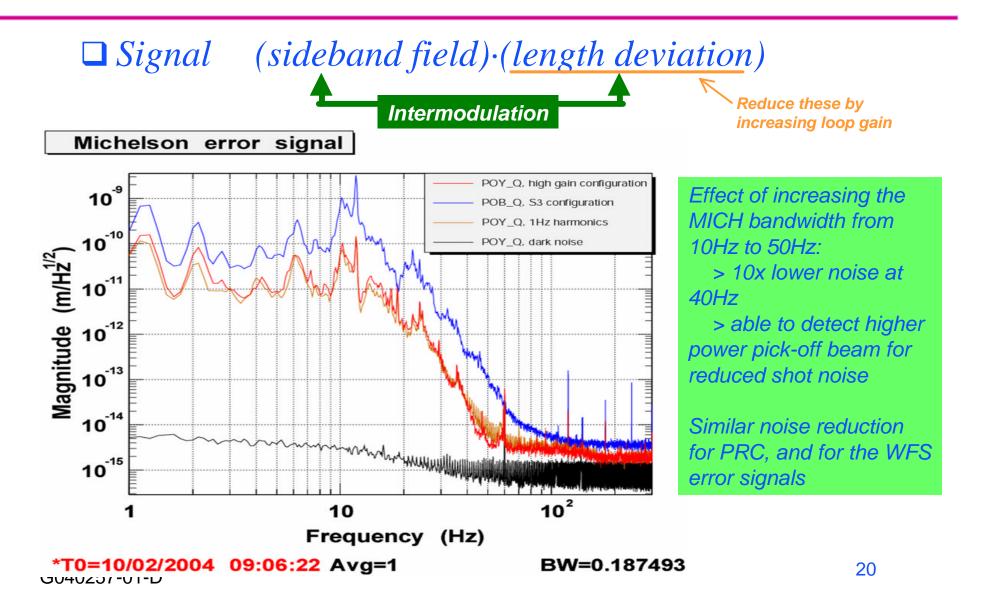


Auxiliary degrees-of-freedom: small coupling, but very noisy



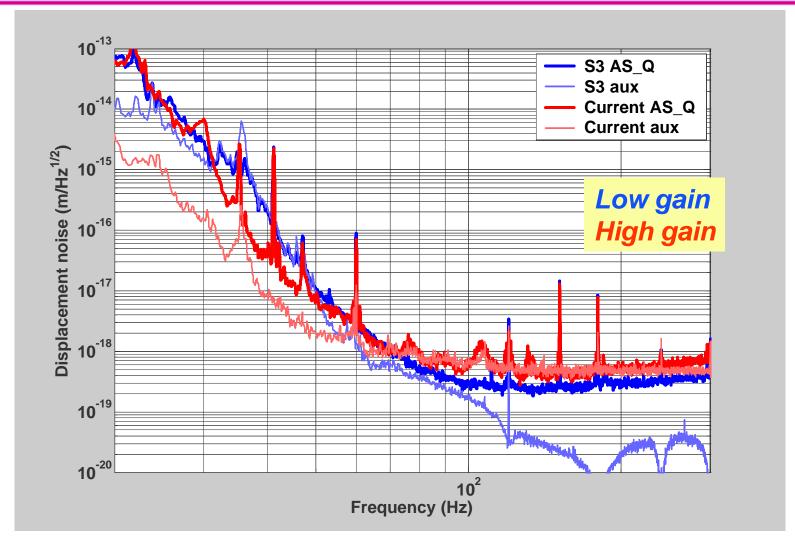


Excess noise: optical gain modulation





Impact on noise



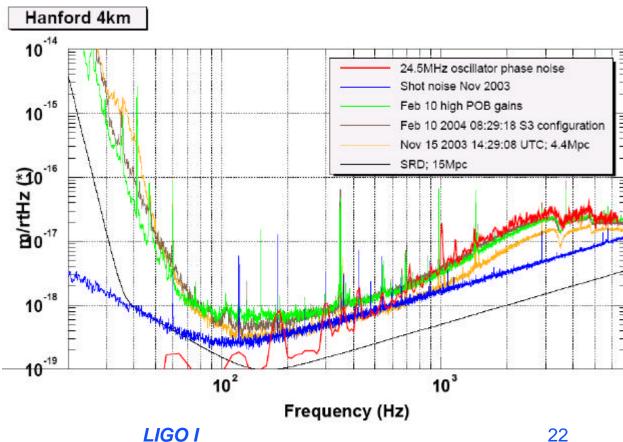


High-f noise bump: mystery solved

RF Oscillator phase noise

Mechanism: possibly coupling through the DC AS_I signal

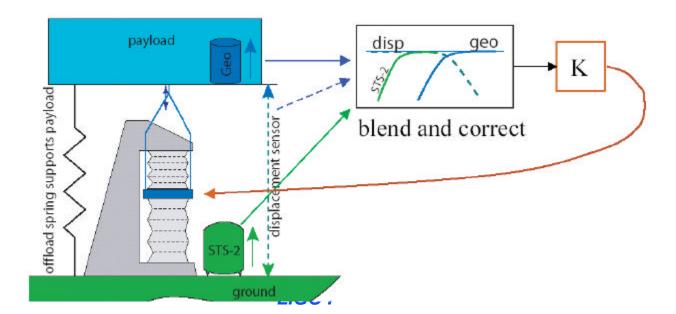
- Modulation phase noise appears on demodulation signal (LO) too
- ➤ True at low frequencies, but perhaps mode cleaner pole shifts phase of modulation fields – doesn't cancel out at higher frequencies?
 - Pass LO through an electronic filter to equalize paths – failed to work; coupling path not understood
- Solution:
 - Low phase noise crystal oscillator – received new osc. – being characterized





Hydraulic External Pre-Isolator (HEPI)

- □ Stanford's proposed Adv. LIGO approach for the first stage of active isolation and high range, position/alignment control was accelerated & adapted for use in initial LIGO
 - At each tank corner pier, there is a sensor/actuator set, vertical and horizontal.
 - · Each DOF controlled with respect to HEPI displacement sensors and geophones.
 - Displacement sensor corrected for floor motion as measured by Streckeisen STS-2., in x, y, z DOF's.

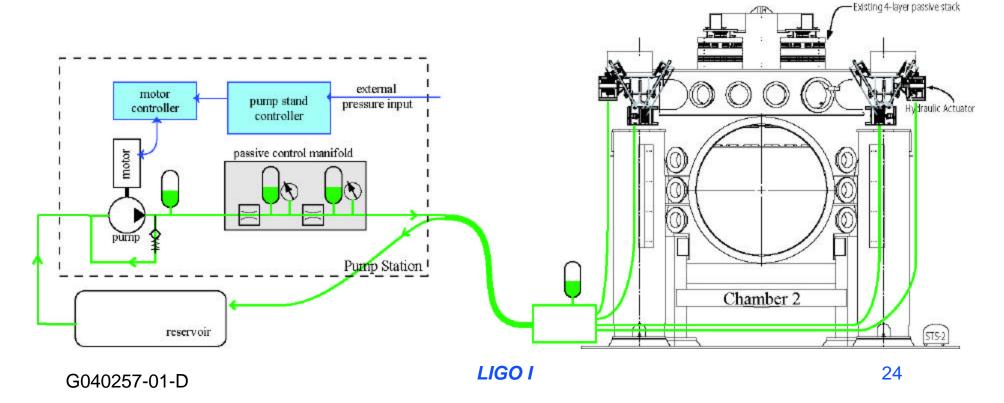


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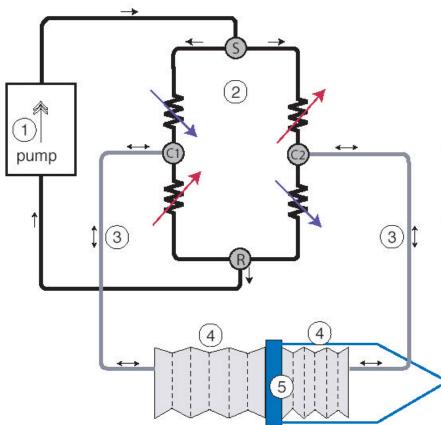
HEPI

- □ Pressure regulation point is at the load manifold
- In the corner station the output of 3 pump stations are ganged together
- ☐ High bandwidth pressure regulation was found to be unnecessary





Hydraulic Bridge Actuation

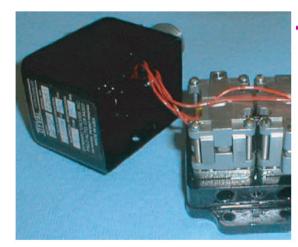


- I. Pressure-stabilized pump.
- 2. four-valve flow-resistance bridge.
- 3. pipes connect bridge to actuator.
- 4. Stiction-free bellows on each side of actuated plate.
- Actuated plate connected to payload through I-DOF linkage.

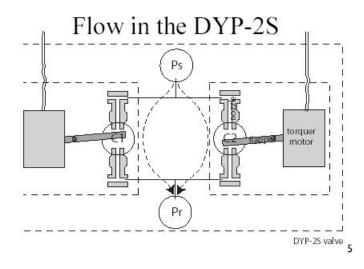


Valve Modification

- Hardham, Lantz, DeBra designed new nozzles for valve, to allow laminar flow and large linear bridge response.
- New nozzles procured, but need to be installed and adjusted by hand.



Parker DYP-2S valve



The new nozzle





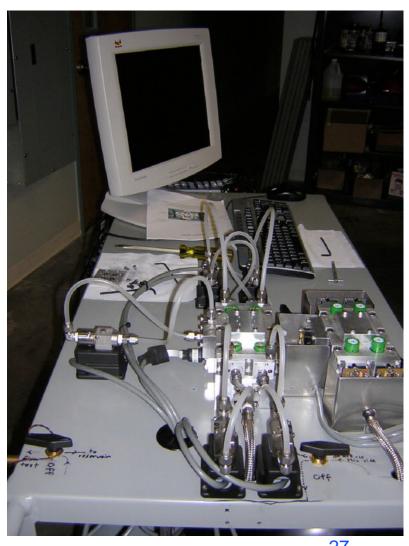
Valve Calibration Stand

□ Purpose:

- Check function
- Check for leaks
- > Set orifice position
- Check linearity & hysteresis

■ All 96 valves checked

- ~20 returned to manufacturer under warranty (Parker) for leaks or nonlinearity
- 2 of 16 valves on systems tests show low authority and nonlinearity, not observed on test stand
 - Under investigation





Pump Station

□ All 7 test stands completed

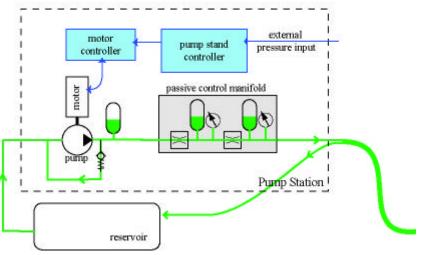
- > 1 for each end station
- > 3 for the corner station
- 1 replacement for LASTI prototype
- > 1 spare at LLO

Reliability

- The LASTI pump station has been running ~continuously for ~14 months
- ➤ The 2 pump stations at the end buildings have been running continuously for several months
- Stanford is performing forensics on a LASTI servo-valve exposed to the hydraulic fluid for ~1 yr and looking at long term compatibility, corrosion









Mass Production



G040257-01-D

- All part fabrication completed
- All Assembly& Test inhouse
 - Essentially completed

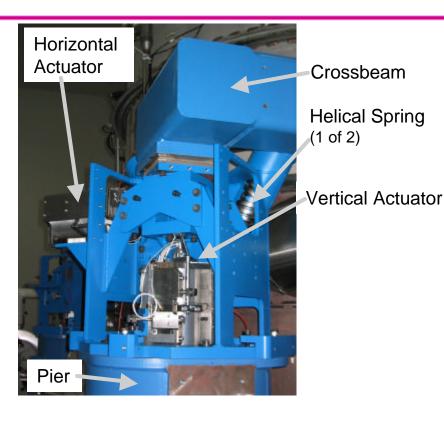


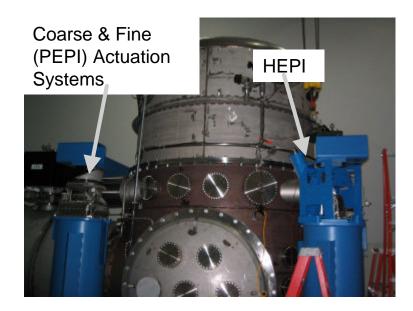




Installation

□ Replacing the fine & coarse actuation systems on all BSC chambers – the coarse actuation and piers on all HAM chambers





LIGO I 30



Installation (2)

- □ Payload is instrumented & freely suspended:
 - 12 dial gauges at the support tube/crossbeam connections
 - 2 optical lever signals (where available)
 - SUS OSEM shadow sensors
- Each corner is supported from directly above the spring attachment point
 - ➤ Load is transferred with a worm gear drive and load cell such that the load is never more that +/- 0.15 mm from initial posiiton
- □ After all 4 mechanical assemblies are in place on each of the 4 piers, the springs tension is adjusted (read out by load cells) and the payload returned to the initial position & alignment
- □ Have locked the X-arm after HEPI mechanical installation





Piping

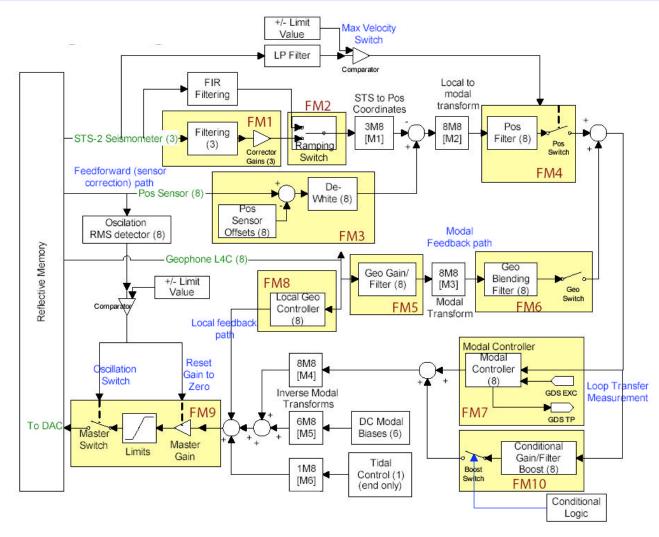


- Piping is stainless steel, food grade, seamless, welded
- ☐ Installation to be completed 6/4
- Testing to be completed 6/11



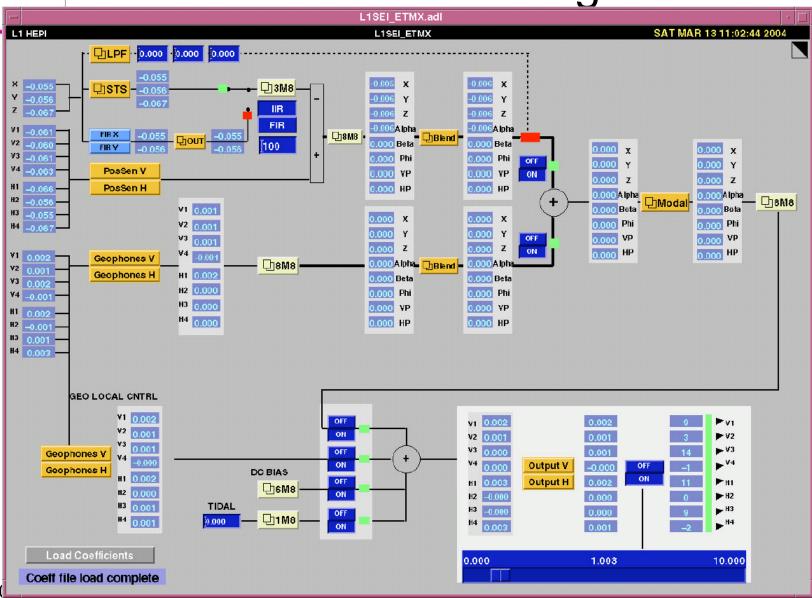
Design Control Diagram

- Modal and/or local feedback plus feedforward (sensor correction) control
- Watchdogs are in place & verified to work





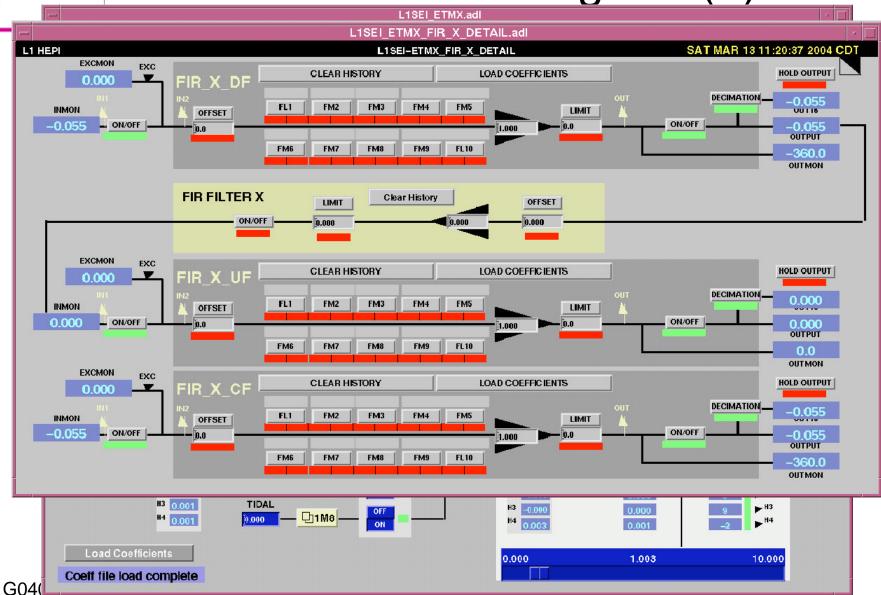
EPICS Control Diagram



G04(



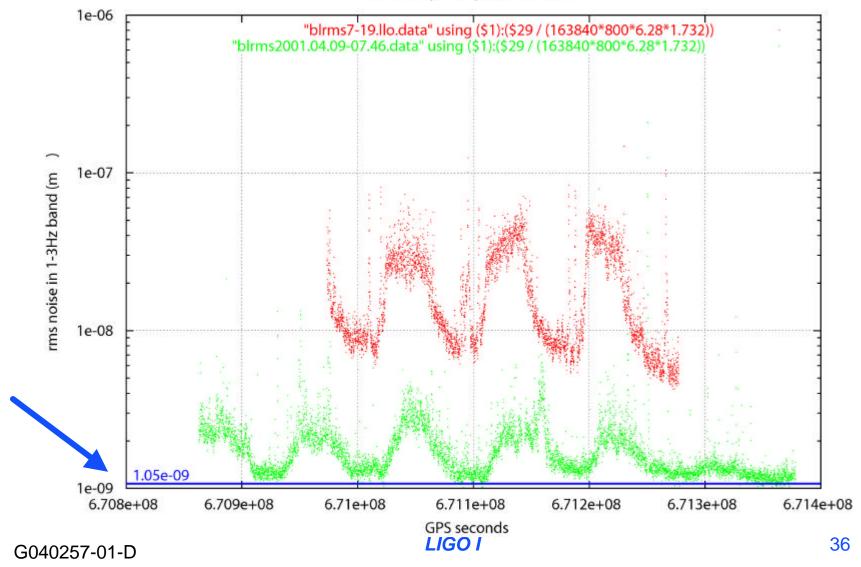
EPICS Control Diagram (2)





Daily variability – and requirement

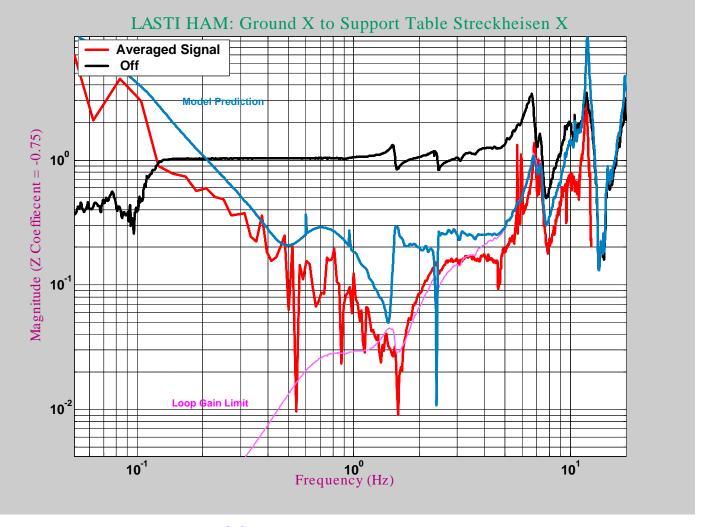
red=livingston, green=hanford





Seismic isolation performance

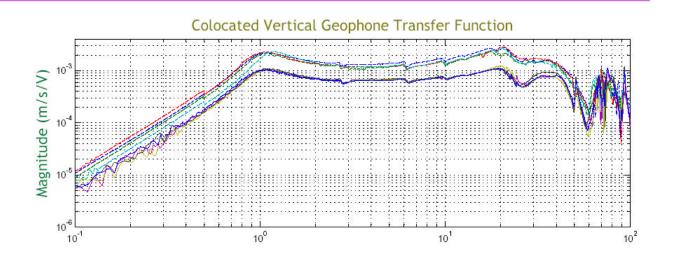
- Best performance data from LASTI, on a HAM chamber – similar results for a BSC
- Expect first LLO isolation results in ~1 week (witness on support table, plus OSEMs on ETMx)

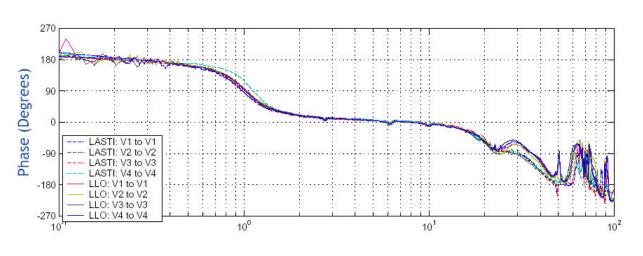




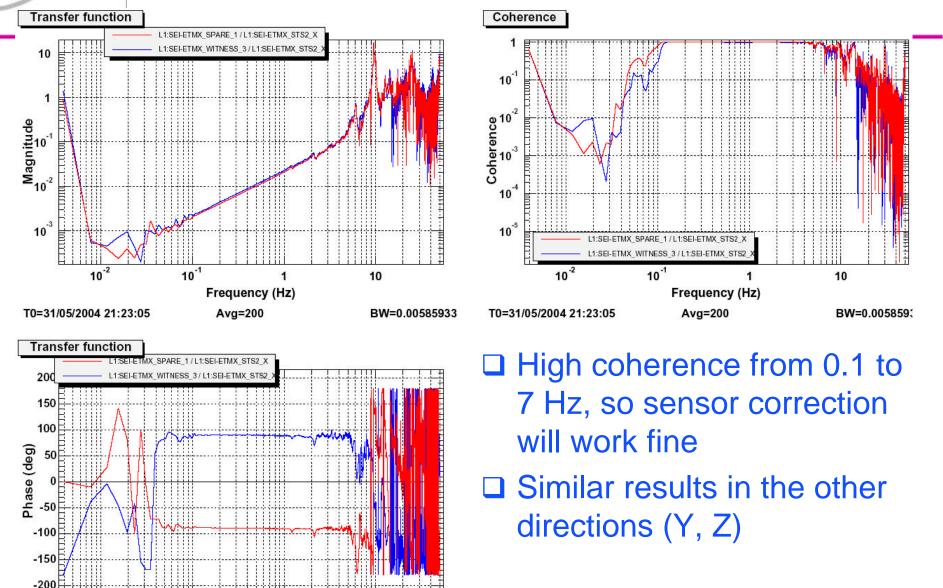
HEPI ETMX Transfer Functions

- LLO ETMX and LASTI BSC transfer functions are similar
- Supports upper unity gain of ~10 to 25 Hz
- □ Isolation at vertical bounce mode (16 Hz) may be possible with a resonant gain stage





Ground to Support Platform Transfer Functions



10⁻¹

1



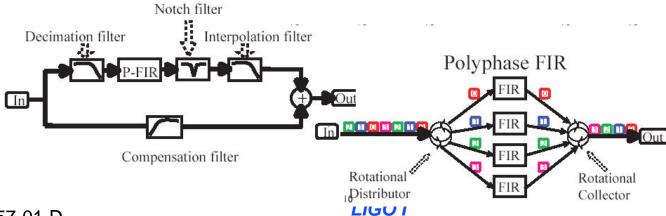
Continued HEPI R&D

□ LASTI HAM Testing/development:

- Working on a LASTI HAM chamber
- HAM stiffening beam found unnecessary
- Verified SOS are OK on HAM table during excitation for system identification
- Adapted GDS for HEPI Sys ID

Stanford Efficient Polyphase FIR

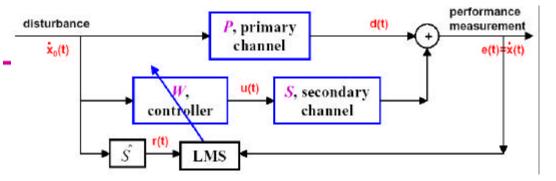
- Eliminates low-frequency noise and artifacts form sensor correction signal
- Avoids excessive phase and amplitude mismatch in band
- Computationally efficient
- Incorporated into LIGO VME software

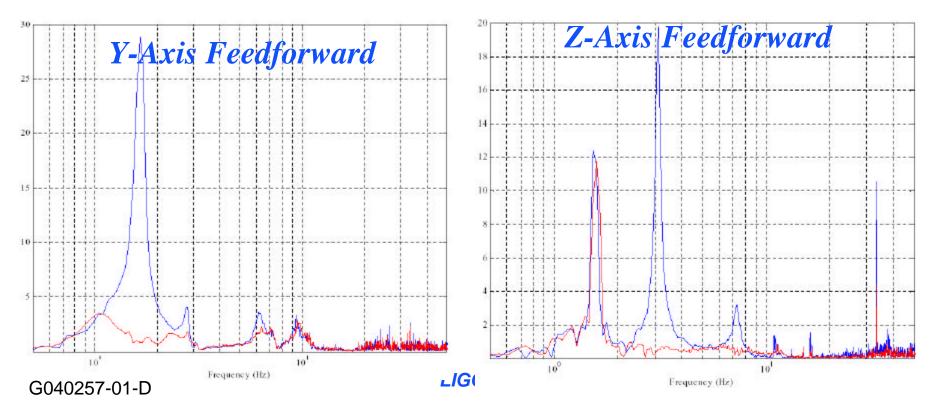




Continued HEPI R&D (2)

- LASTI Adaptive Feedforward
- Control
 - Combined SISO loops tried on HAM HEPI System
 - 1024 point FIR filter, 500 Hz sampling & innovation rate
 - Suppression of ~20x observed
 - Computationally prohibitive for MIMO control







Miscellaneous

- New low-noise D-A converters from Freq. Devices Inc.
 - > 30-40 dB lower noise
 - Several installed on H1; Improved Anti-image filter being built to take full advantage
 - New Faraday isolator for H2
 - > Larger aperture to reduce clipping
 - Lower absorption for higher power operation
 - ➤ To be installed late-June/early-July
 - Photon calibrators
 - Reproducing first-article: in place for S4
 - □ Phase cameras on all interferometers
 - Introducing a reference field so that any field component can be mapped
 - Dual ETM transmission photodetectors
 - > To handle larger dynamic range with higher power
 - Installed and operating on H1
 - Upgraded DAQ reflective memory network: higher capacity
 - Micro-seismic feedforward system at LHO likely
 - ☐ Improved design/electronics for ISS, FSS, RFPD, ASI-servo



Major Post-S3 Steps

First ~6 months after S3				
L1	 Thermal lens studies Seismic upgrade: HEPI installation & commiss. Electronics rack relocation Thermal comp. 			
H1	 ▶ Manage noise in auxiliary degrees-of-freedom ▶ Thermal compensation trial ▶ Wideband WFS control ▶ Laser power increase ▶ Output mode cleaner ▶ Duty cycle 			
H2	► Wideband WFS control			