SEI

Seismic Isolation and Alignment for Advanced LIGO

Brian Lantz, for the Seismic Team Nov. 10, 2005

Summary

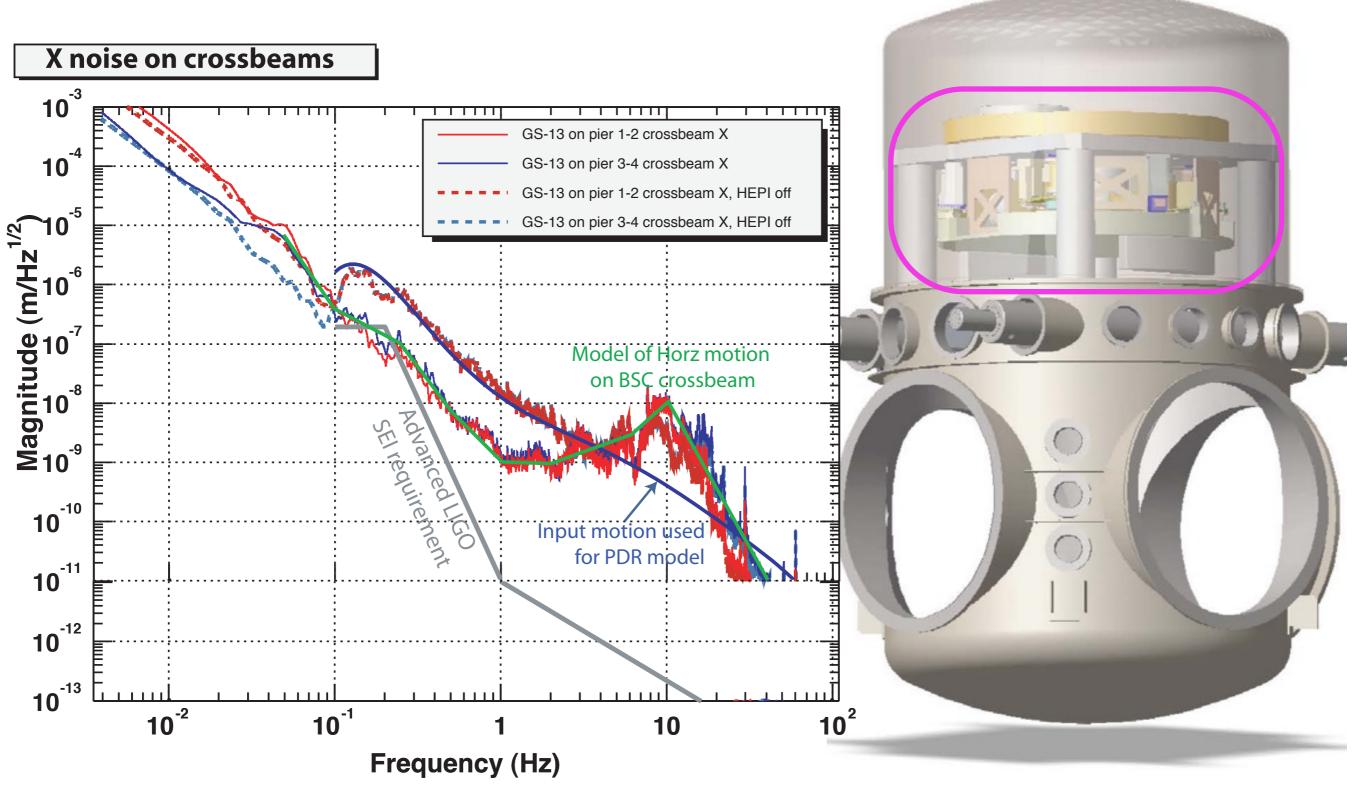
Based on

- I) Experimental results at the Stanford Engineering Test Facility,
- 2) Performance models of the system designed for the BSC by ASI, and
- 3) Experience with HEPI,

LIGO has decided to proceed with the manufacture of the next prototype.

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BSC System for Advanced LIGO



original plot from J. Giaime

CAD drawing from ASI

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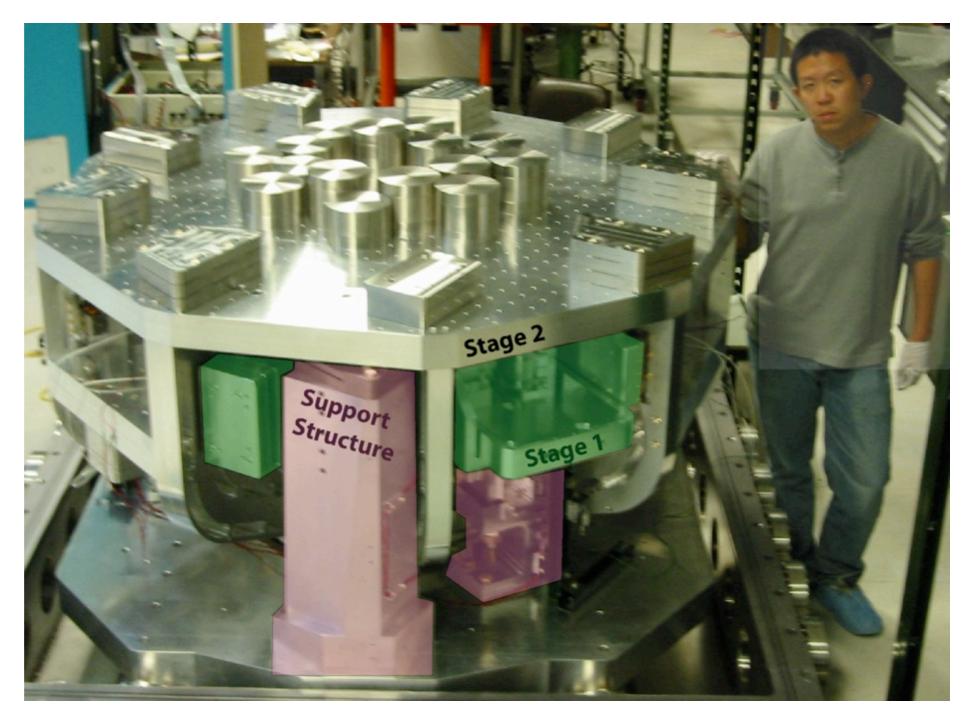
ETF Technology Demonstrator

2 stage isolation and alignment system.

Each stage aligned and isolated in 6 DOF.

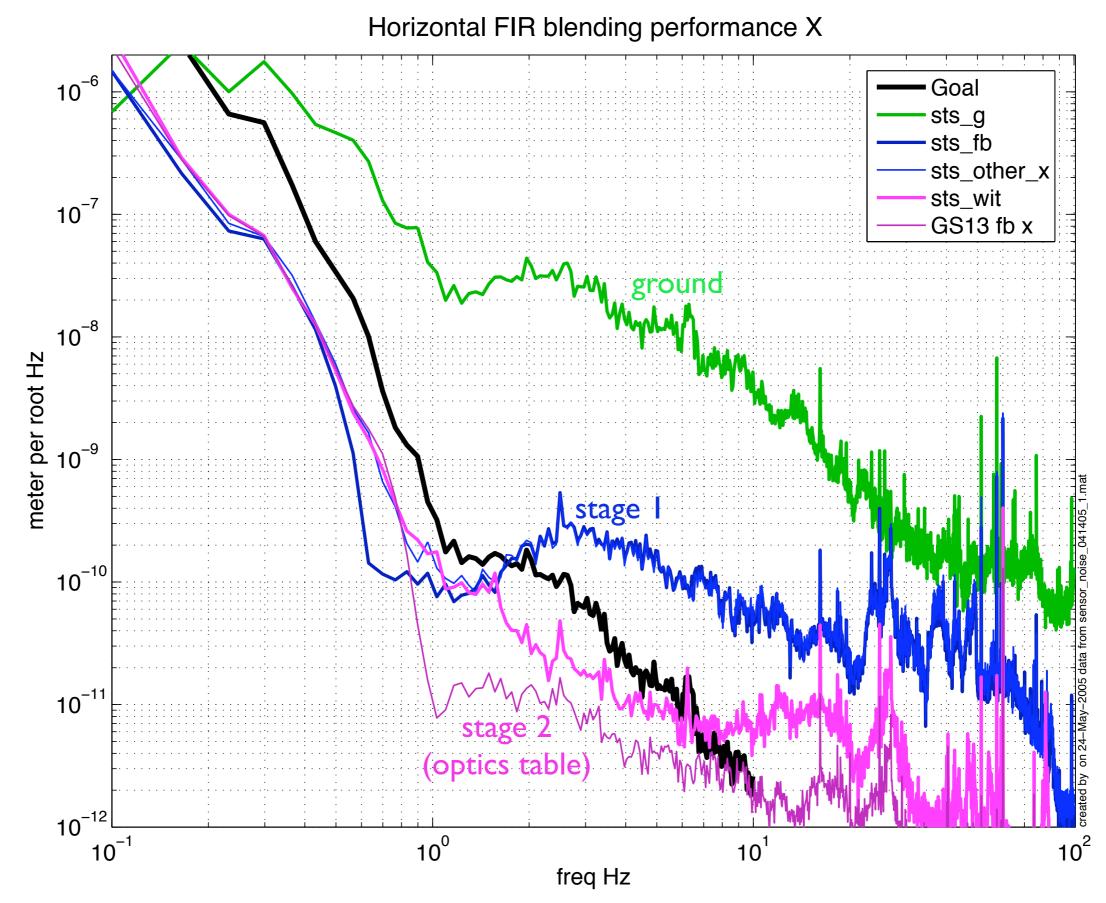
Passive isolation above I Hz horz, 3 Hz vert

Active isolation below 30 Hz



ETF: X Performance

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Improvements

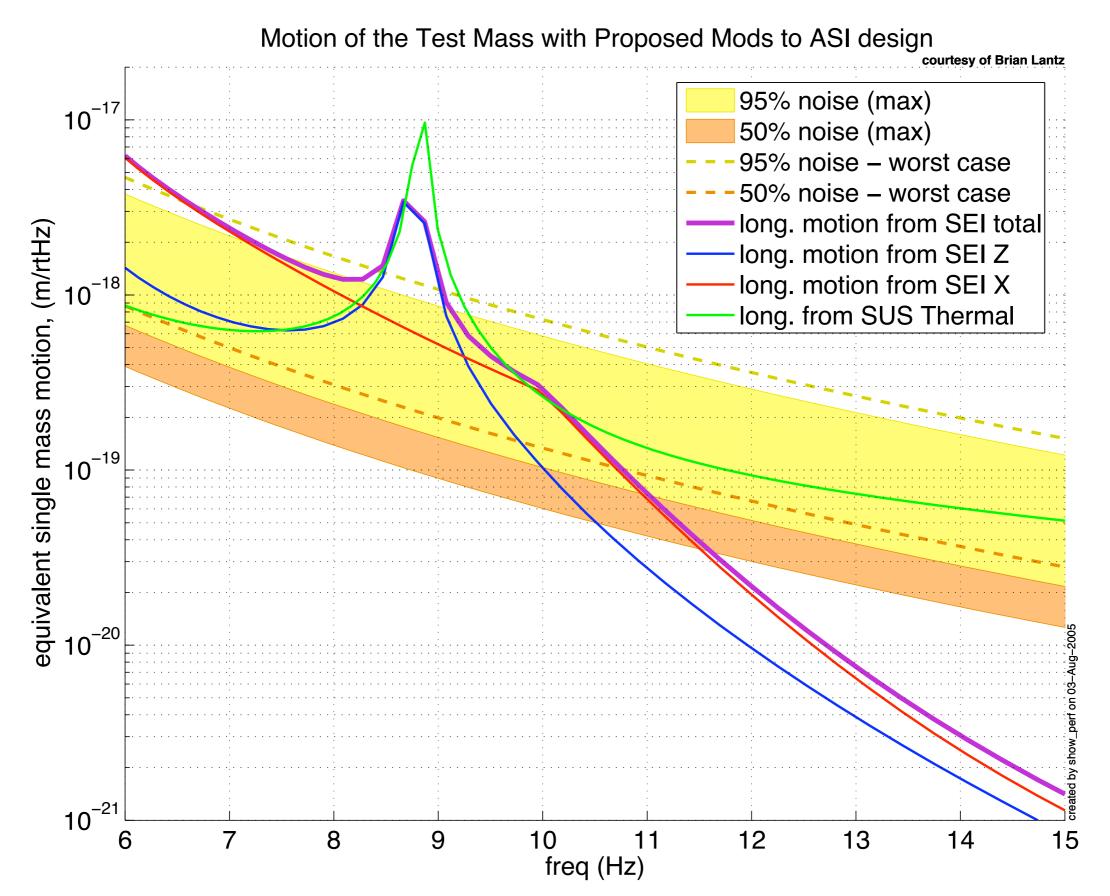
Better readout electronics for stage 2 sensors (GS-13) We have demonstrated noise <1e-11 m/rtHz at 1 Hz.

Improve the BSC system tip/ tilt isolation at 10 Hz.

Then:

Make a big model of the system w/ a quad pendulum. Seismic crosses thermal noise at 10.3 Hz.

GOSOSAS Predicted Performance w/ Pendulum



We are building the BSC prototype, the plan is:

LIGO (Ken Mason) managing the production May 2006: "Dirty Assembly" at MIT - LASTI Modal testing in air, disassemble, s clean Sept 2006: reassemble, continue air testing Dec 2006: Install in BSC at MIT 2007: In vacuum testing and control development