

# Status of the LIGO Interferometers circa 2005

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GWDAW-10  
Dec. 2005

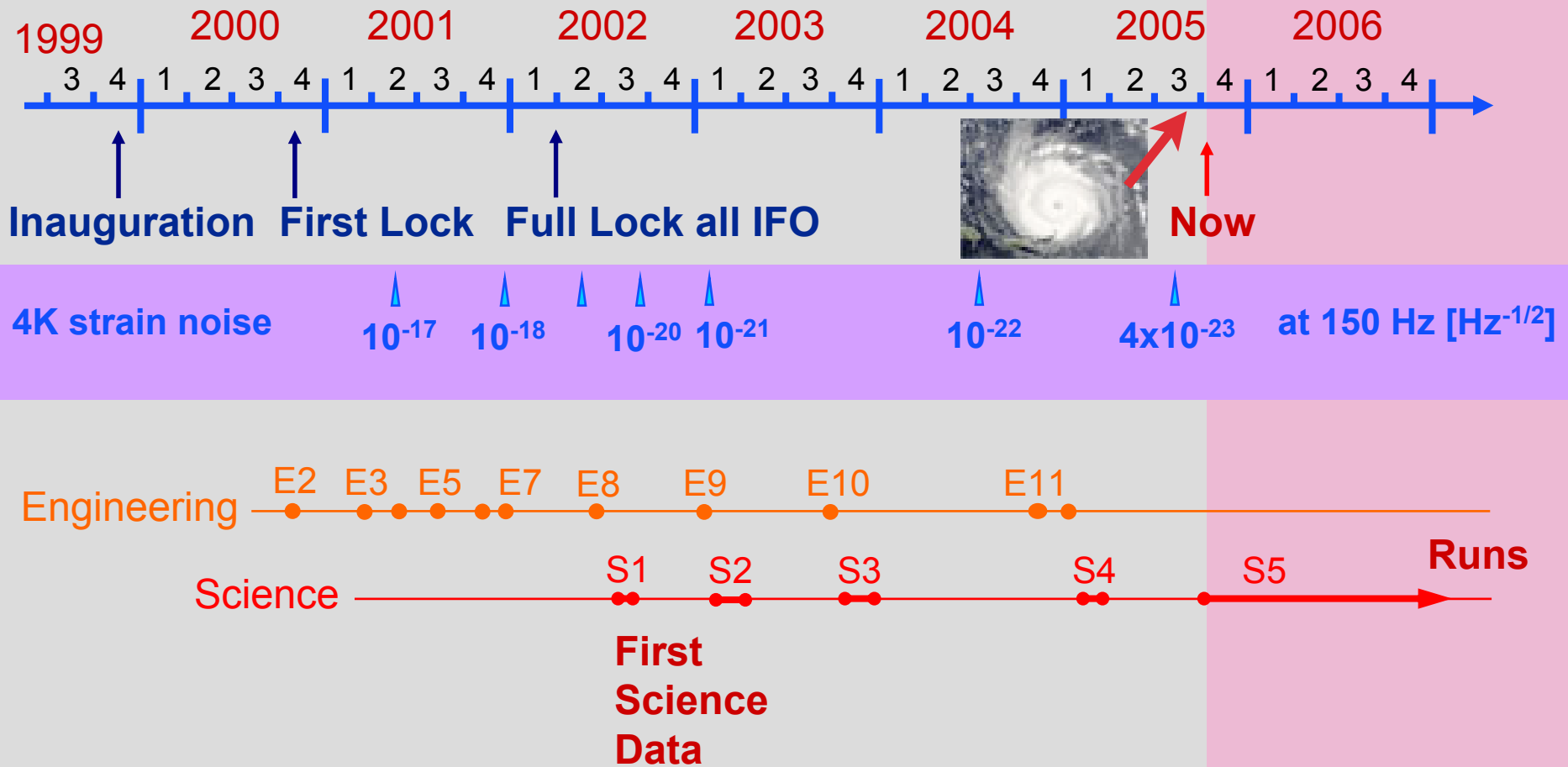
DCC: G050661-00-Z

# In brief

- from LIGO document E950015:  
*“initial LIGO detector strain sensitivity goal of  $10^{-21}$  RMS, integrated over a 100 Hz bandwidth”*
- 2005 NSF review panel agrees - **LIGO has reached design sensitivity**

**LIGO**

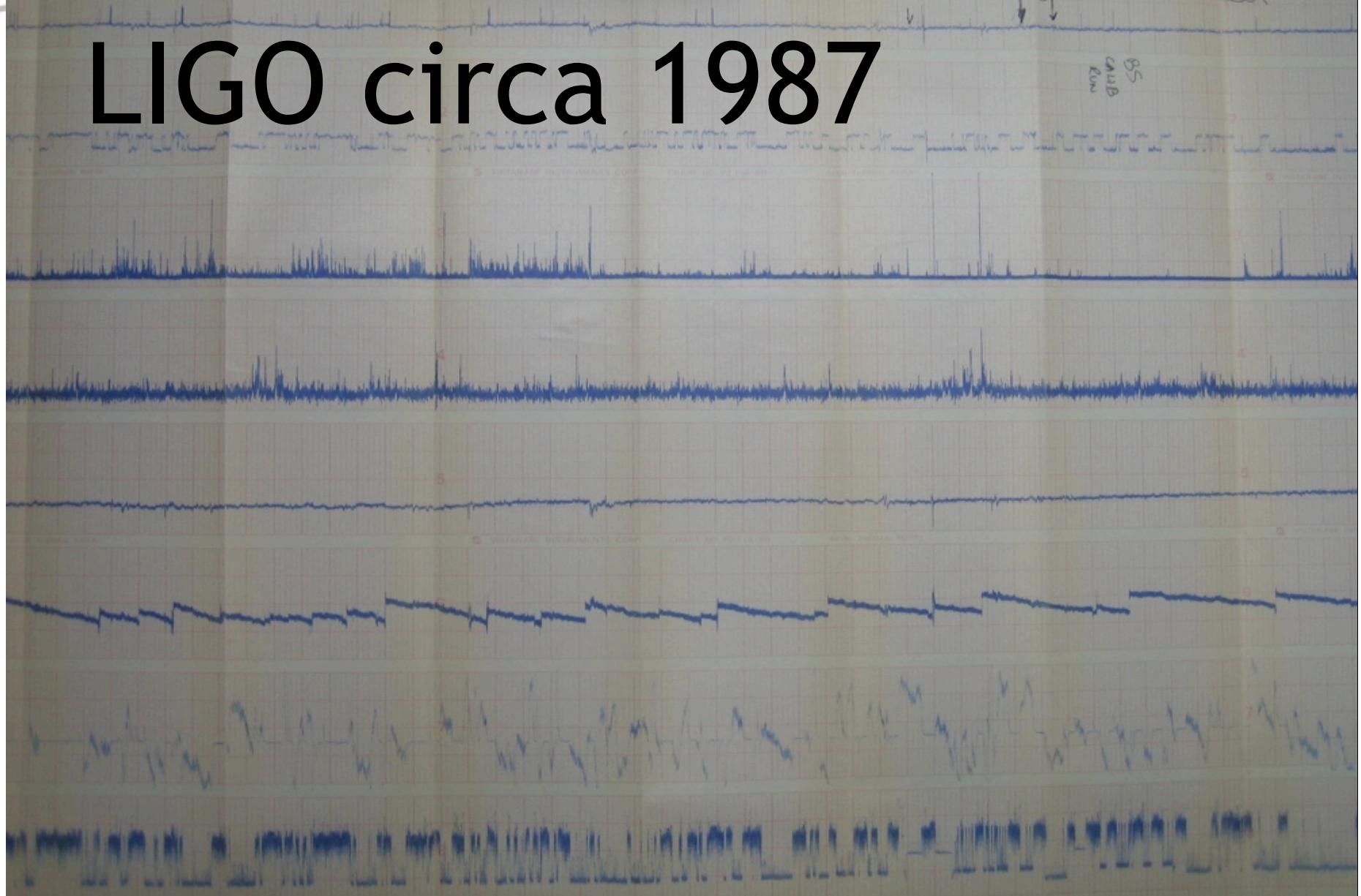
# A brief history of LIGO



# LIGO circa 1987

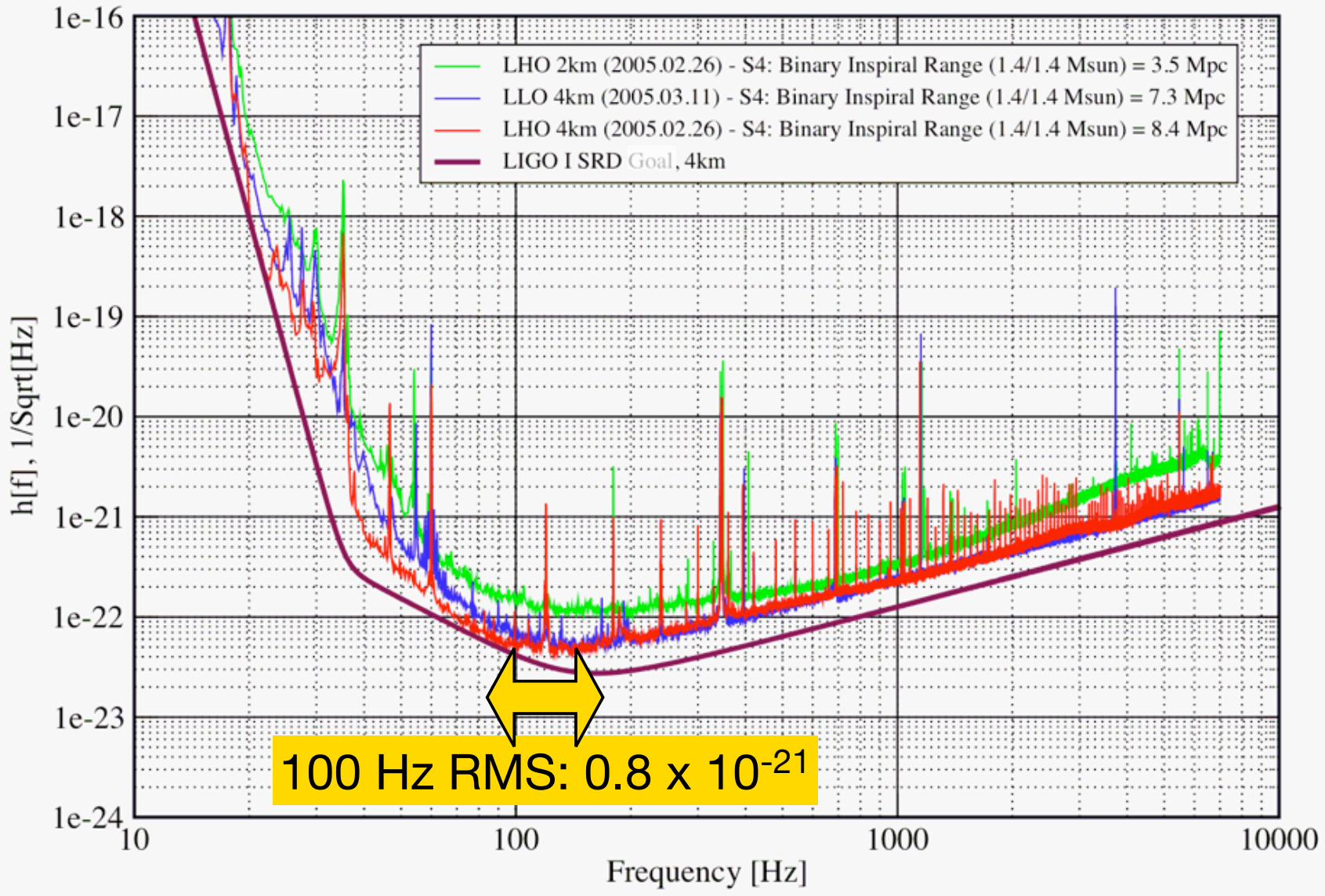


Handwritten annotations on the top strip of the tape include:  
- "Taper 71" with an arrow pointing to the right.  
- "Taper 71 (original)" with an arrow pointing to the right.  
- "Taper 71" with an arrow pointing to the left.  
- "AC" with an arrow pointing to the right.  
- "Off" with an arrow pointing to the right.  
- "End of Taper" with a bracket on the right side.  
- "BS" with an arrow pointing to the right.  
- "AMB" with an arrow pointing to the right.  
- "EUN" with an arrow pointing to the right.



# Strain Sensivities for the LIGO Interferometers

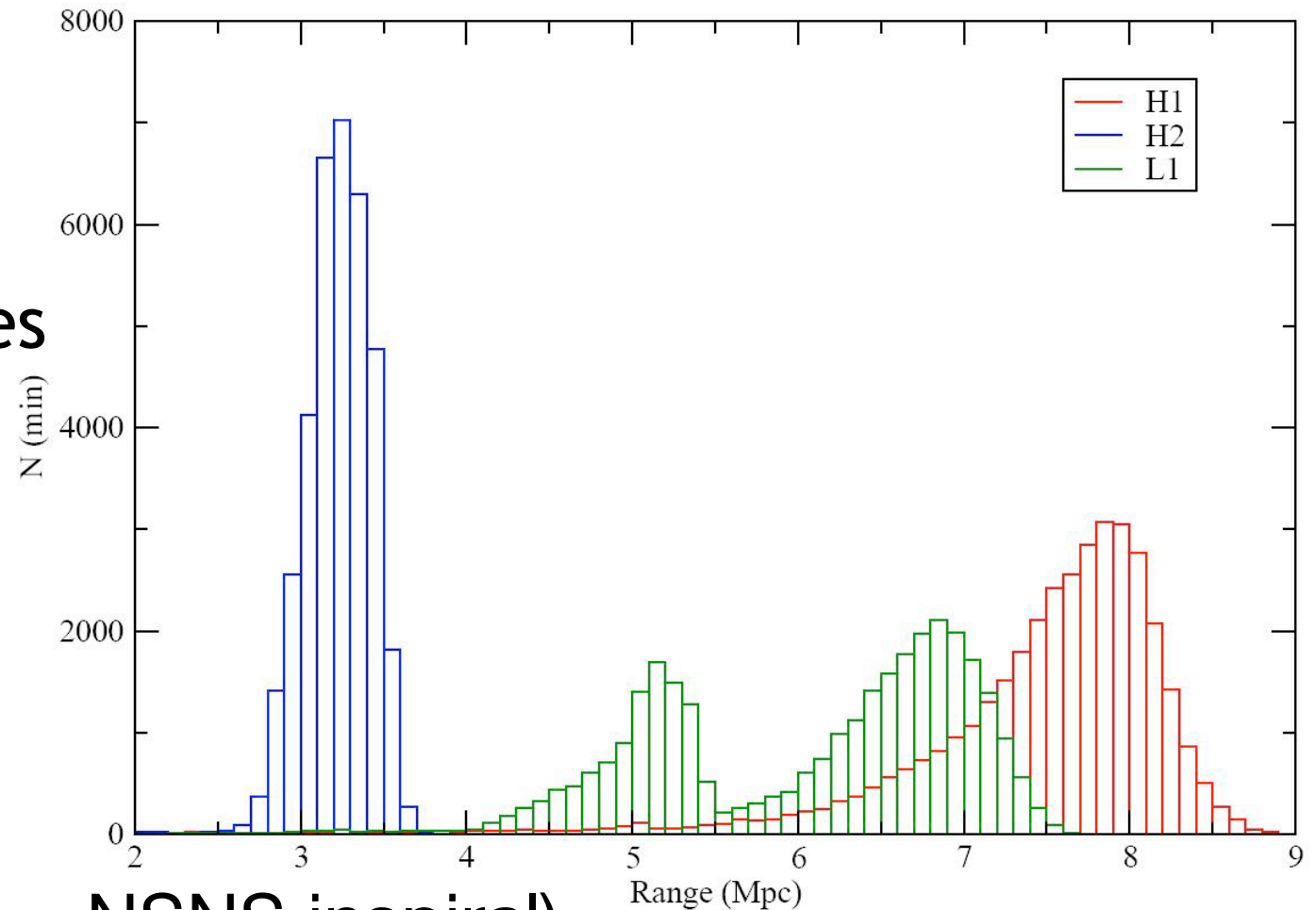
Best Performance for S4 LIGO-G050230-02-E



# S4 performance

## S4 Range Histogram

- Feb 22 to Mar 23
- Duty Cycles
  - H1: 80%
  - H2: 81%
  - L1: 74%
  - 3x: 57%



(1.4  $M_{\odot}$  NSNS inspiral)

The LIGO logo consists of the word "LIGO" in a bold, blue, sans-serif font. To the left of the text are several concentric, light gray circles of varying radii, resembling a ripple effect or a stylized representation of gravitational waves.

**LIGO**

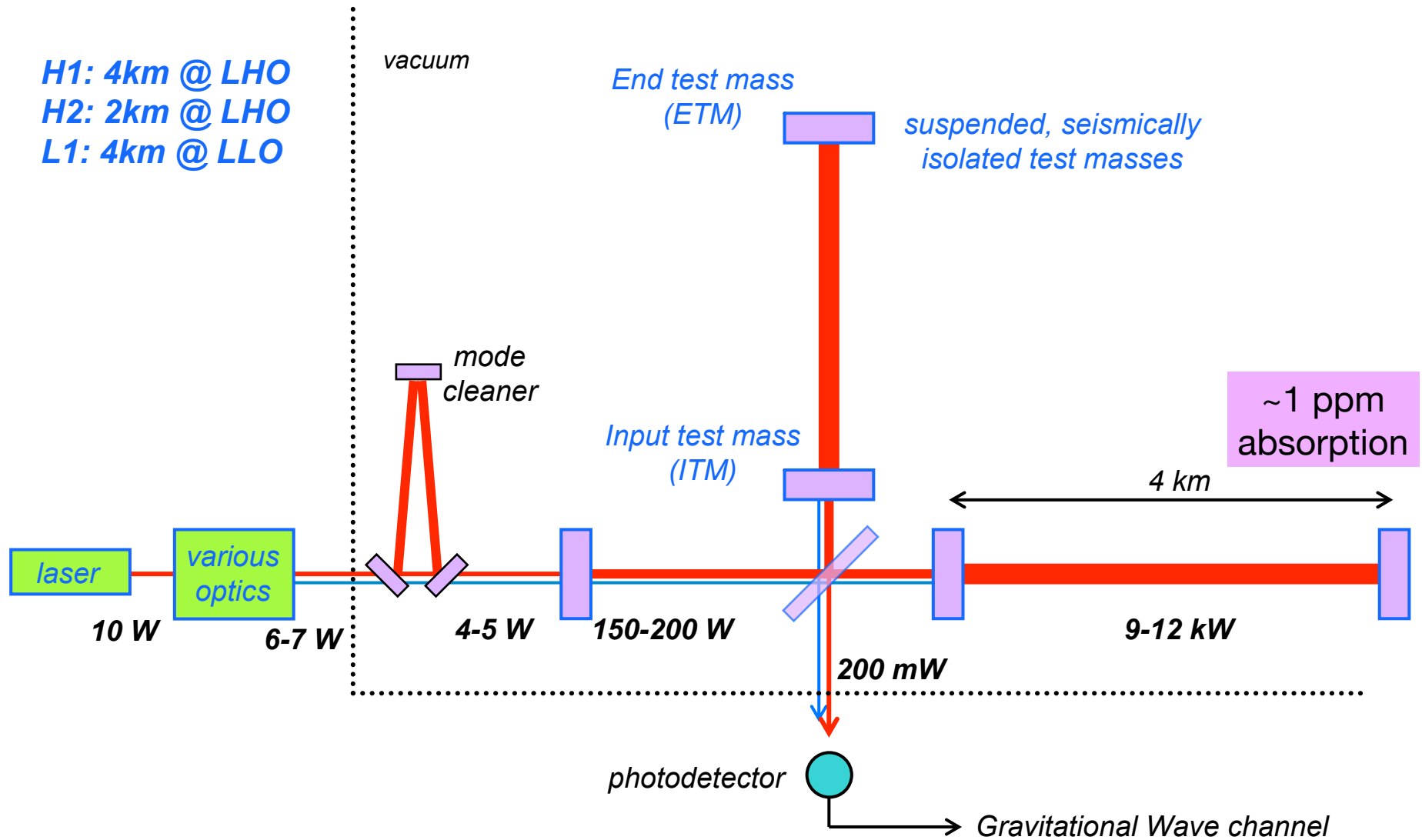
# Post-S4 improvements

- Thermal Compensation System (TCS)
- Fixed H1 ITM absorption
- Improved Angular Sensing & Control (WFS)
- Hydraulic External Pre-Isolator (HEPI) fine-tuning

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# IFO Layout

H1: 4km @ LHO  
H2: 2km @ LHO  
L1: 4km @ LLO

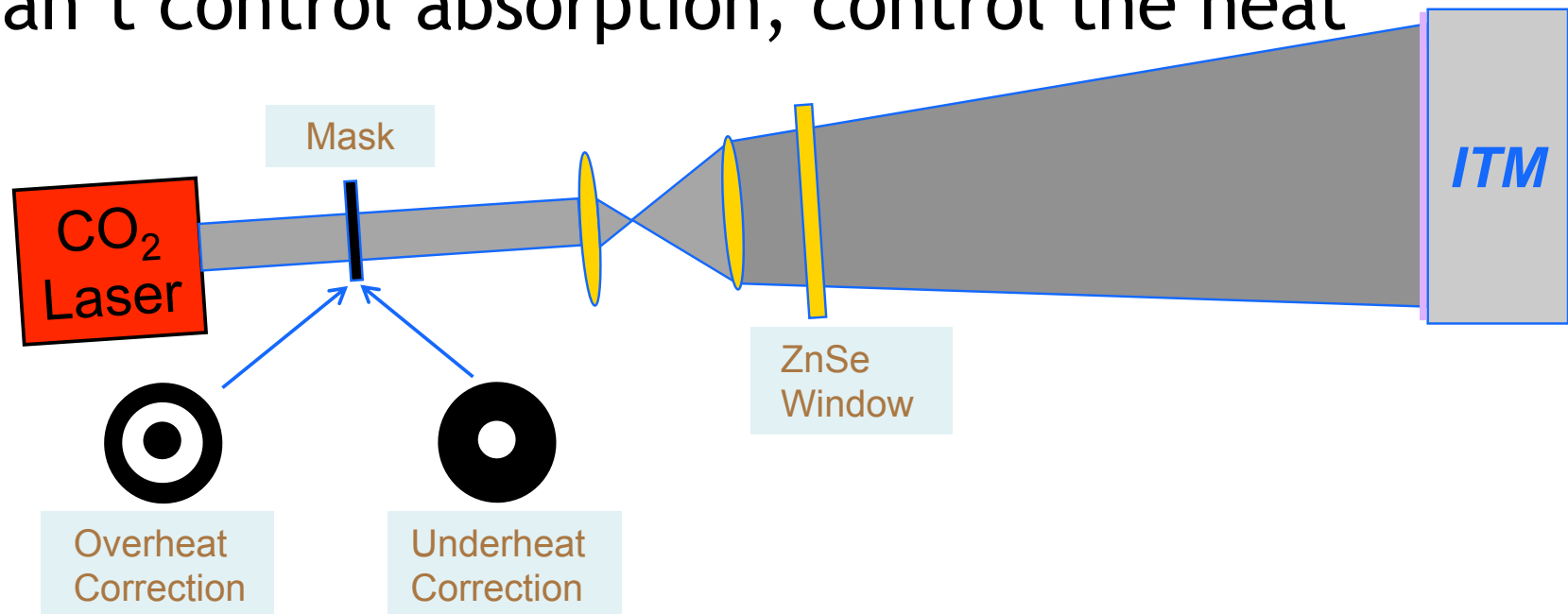




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# Thermal Compensation

- Cold power recycling cavity is unstable
- Requires 10's of mW absorption for optimal thermal lensing
- Can't control absorption, control the heat



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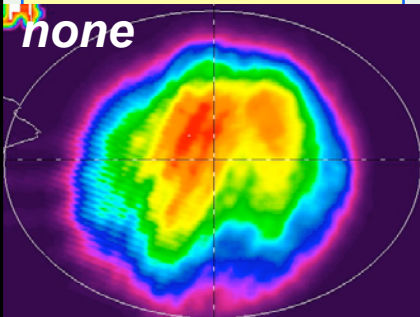
# AS port modes

Matching SB & carrier modes

CO<sub>2</sub> heating

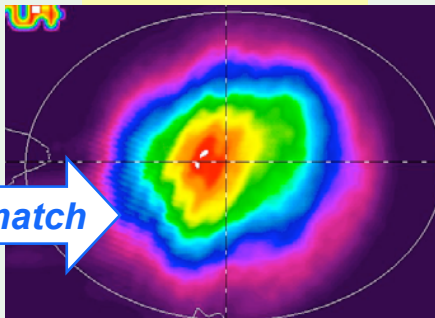
Sideband images

none



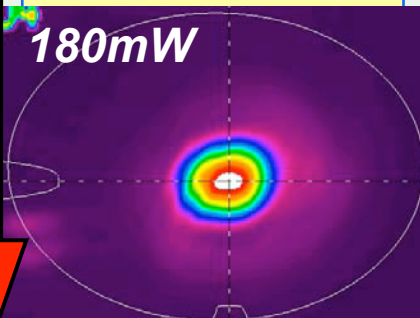
Common heating

carrier



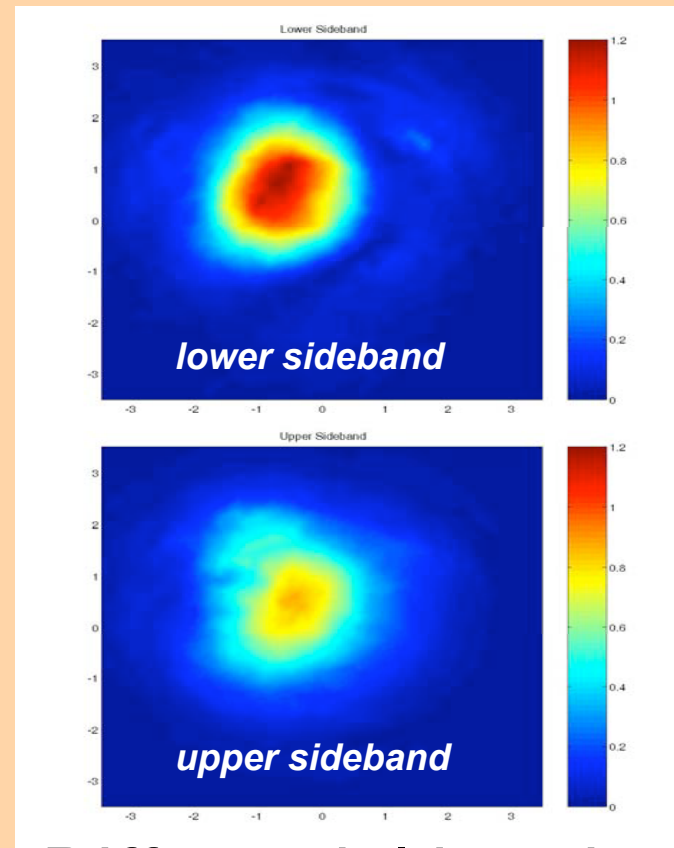
Best match

180mW



Servo controlled

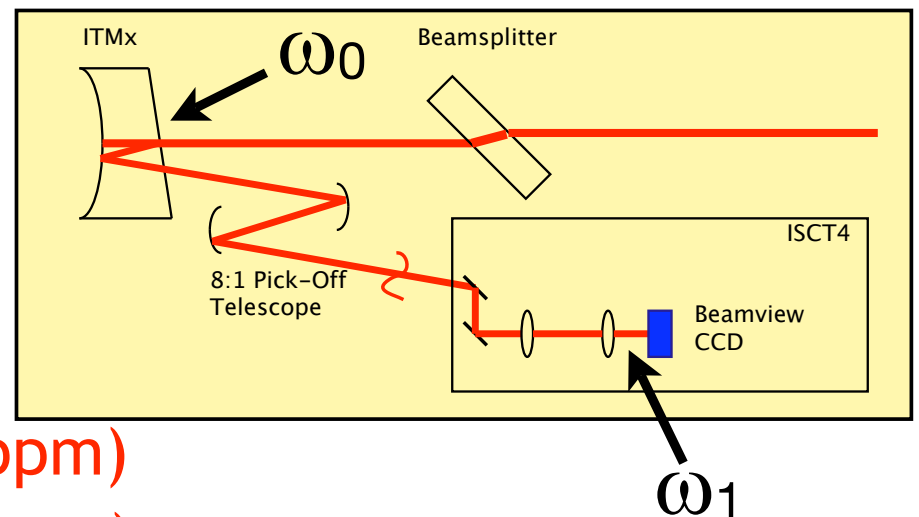
Symmetrizing the SBs to minimize the orthogonal-phase signal: controlling RF saturation



Differential heating

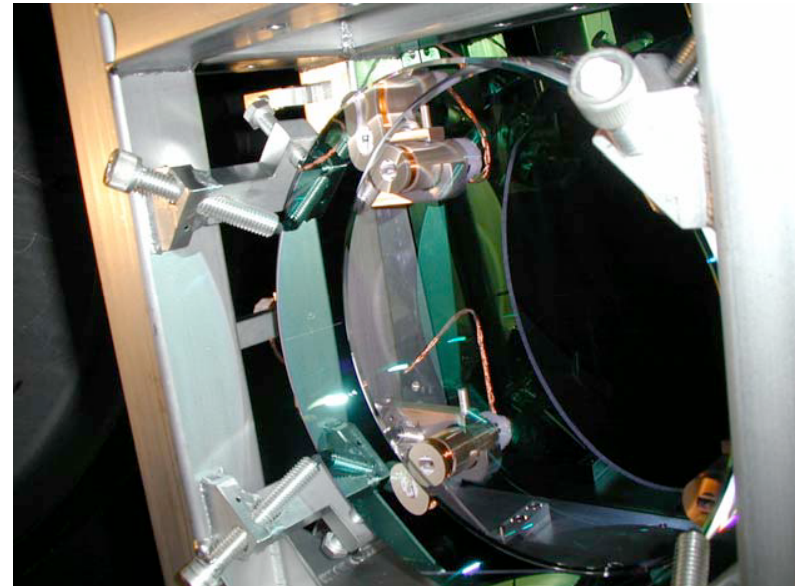
# H1 characterization

- S4: 3W input required 1.5W CO<sub>2</sub> annulus compensation
- Post-S4: *in situ* measurements of the ITMs
- Arm cavity g-factor
- Beam size changes
- Results:
  - ITMX = 35 mW/W (20 ppm)
  - ITMY = 13.5 mW/W (6 ppm)
- High power attempts failed



# H1 replacement

- Couldn't run at high power
- In mid-June decided to replace ITMX
  - Fully characterized spare
  - *In situ* cleaning of ITMY
  - Vent on June 29, 4 wks pump
- Dragwipe ITMY

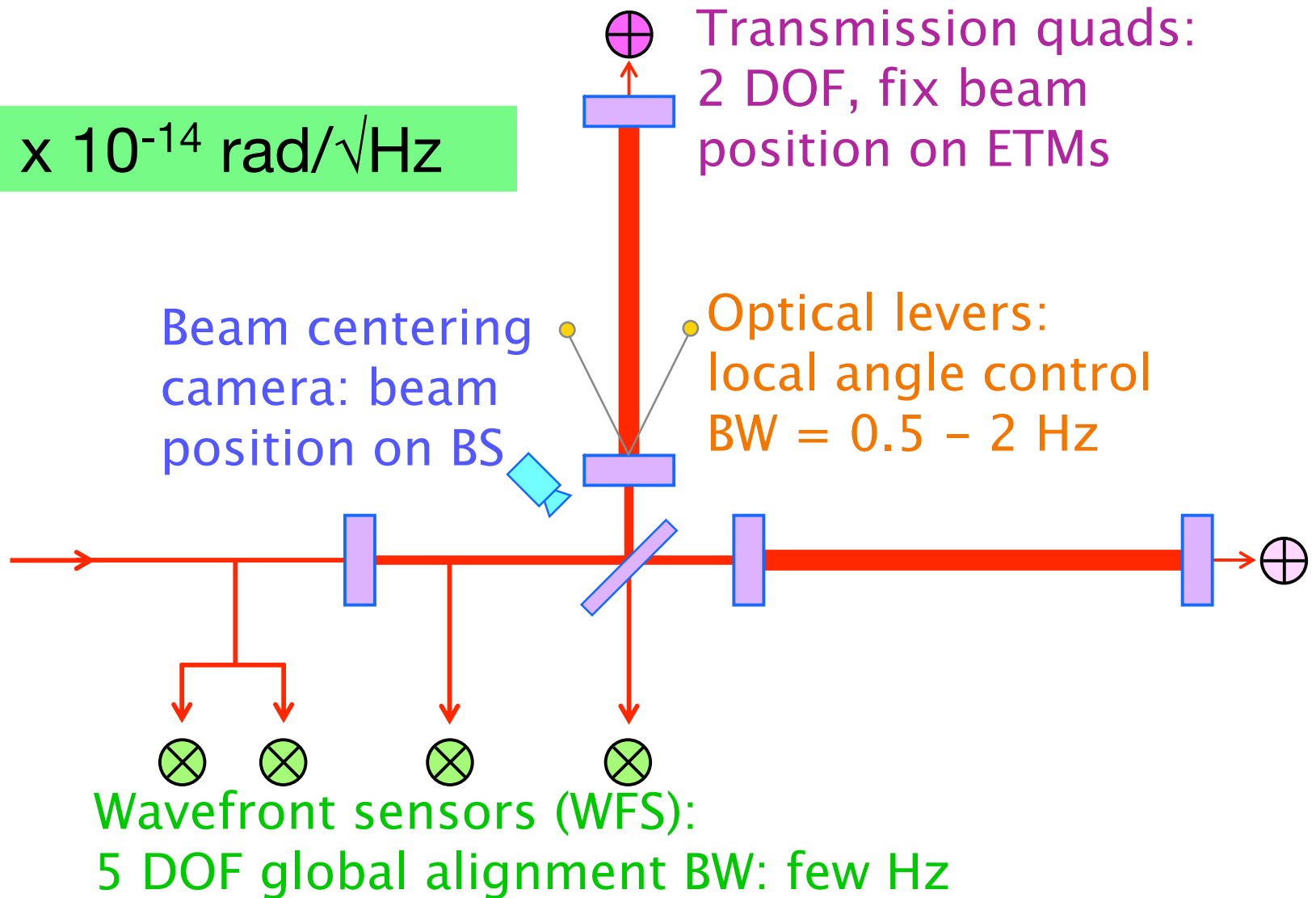


4k IFOs at full power

	ITMX	ITMY
Before	35 mW/W	14 mW/W
After	< 3 mW/W	3 mW/W

# Angular Sensing

$\sim 1 \times 10^{-14} \text{ rad}/\sqrt{\text{Hz}}$



# WFS diagonalization

- Each sensor detects multiple optics
- Previously, stabilized w/ gain heirarchy
- Now, output matrix diagonalized

	WFS1	WFS2a	WFS2b	WFS3	WFS4
ETMX	1.0	0.35	0.50	-0.50	-1.0
ETMY	-1.0	0.35	-0.50	-0.50	-1.0
ITMX		-1.0	-1.0	1.0	0.35
ITMY		-1.0	1.0	1.0	0.35
RM		-0.25		0.75	0.25

Loop BW  $\lesssim 5$  Hz

Decrease orthogonal phase AS signal

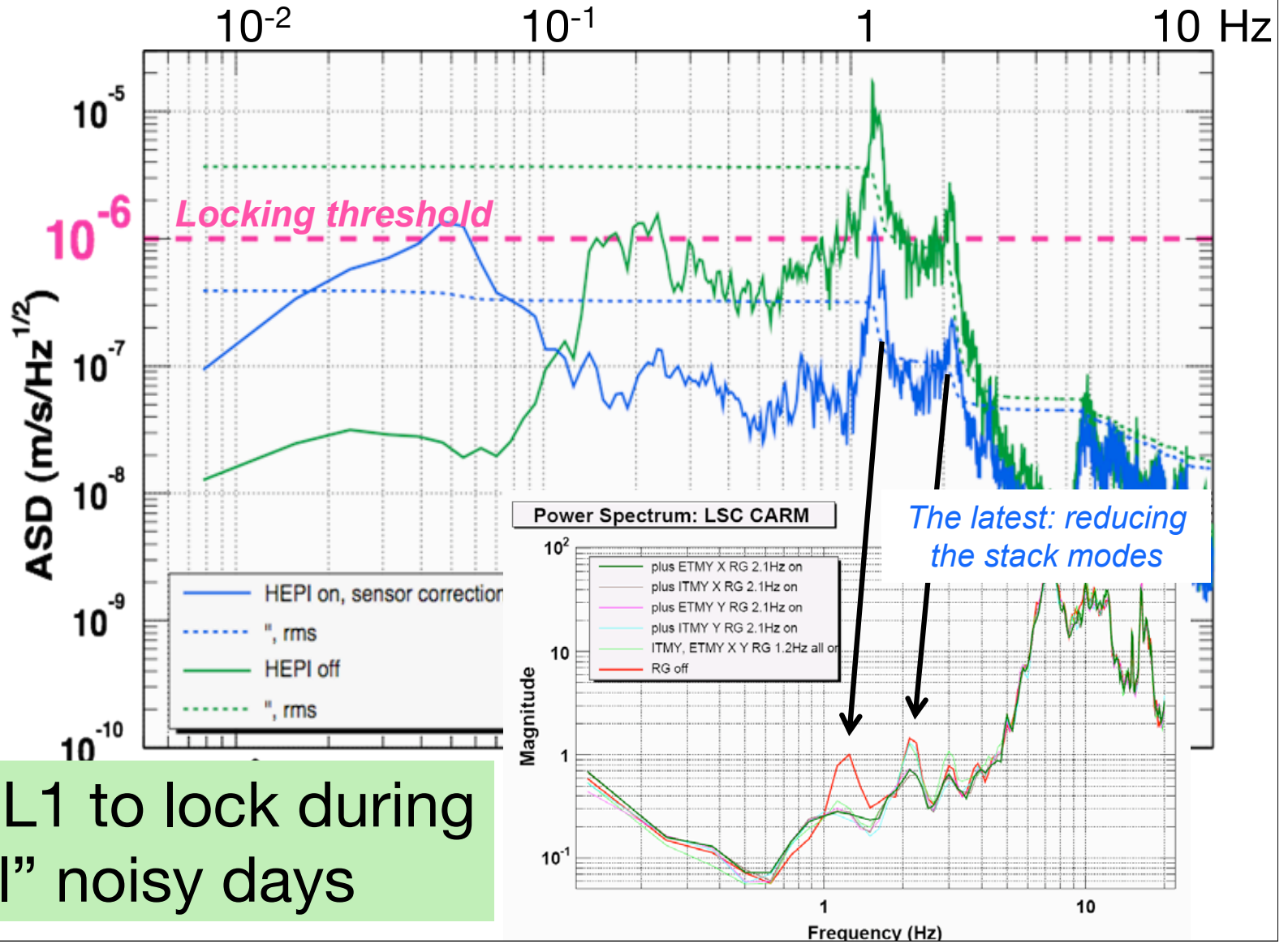
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# Hydraulic External Pre-Isolator

- Spring-supported payload
- High force, low noise hydraulic bridges
- Sensor blending
- ~10x vel. reduction

# HEPI results



Allows L1 to lock during "typical" noisy days



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# Into S5

