#### Frequency corrections to antenna-patterns: forward detector transfer function

#### LSC Burst Group Telecon. Sept. 26, 2006 Malik Rakhmanov

LSC documents regarding the frequency dependence of the antenna patterns and its implication for calibration:

- T970101-B, D. Sigg, Strain calibration in LIGO,
- T030296, D. Sigg and R. Savage, Analysis proposal to search for gravitational waves at multiples of the LIGO arm cavity free-spectral-range frequency,
- T030186, J. Markowicz, R.L. Savage, and P. Schwinberg, *Development of a readout scheme for high-frequency gravitational waves*,
- G050205, M. Rakhmanov and R. Savage, LIGO detector response at high frequencies and its implications for calibration above 1kHz,
- T050136, Hunter Elliott, Analysis of the frequency dependence of the LIGO directional sensitivity (Antenna Pattern) and implications for detector calibration,
- T060xxx, Jeffrey Parker, Development of a high-frequency burst pipeline.

### High-frequency antenna patterns

Antenna patterns at FSR: response to +polarization ( $\psi = 0^{\circ}$ ), response ×polarization ( $\psi = 90^{\circ}$ ), averaged response.



from T970101-B, D.Sigg, Strain calibration in LIGO.

Polarization tensor in the wave frame  $E_{gw}$  and the vector pointing to the source  $\vec{n}$ :

$$E_{gw} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 0 \end{pmatrix}, \qquad n_x = \sin \theta \cos \phi \\ n_y = \sin \theta \sin \phi \\ n_z = \cos \theta.$$

Transformation from the wave frame to the detector frame,  $R = R_z(\psi)R_y(\theta)R_z(\phi)$ , induces the transformation of the polarization tensor:  $E_{det} = R^T E_{gw} R$ .

$$A_i = \frac{1 - e^{-(1 - n_i)sT}}{1 - n_i}, \qquad B_i = \frac{1 - e^{-(1 + n_i)sT}}{1 + n_i}.$$

Introduce the equivalent phase response and the cavity field response:

$$\phi_i = \frac{A_i - B_i e^{-2sT}}{2sT}, \qquad \qquad H_{cav}(s) = \frac{1 - r_a r_b}{1 - r_a r_b e^{-2sT}},$$

and two polarization components in detector frame:  $E_{xx} = E_{det}(1,1), E_{yy} = E_{det}(2,2)$ . Then response to gravitational waves is

$$H_{gw}(s) = \frac{1}{2} H_{cav}(s) (E_{xx}\phi_x - E_{yy}\phi_y).$$



Detector response = convolution:

$$x(t) = \int_0^T \left[ H_+(t - t', \Omega) \ h_+(t') + H_\times(t - t', \Omega) \ h_\times(t') \right] \ dt'$$

In Fourier domain

$$\tilde{x}(f) = H_+(f,\Omega) \ \tilde{h}_+(f) + H_\times(f,\Omega) \ \tilde{h}_\times(f).$$

The characteristic time scale T = L/c (photon transit time) and the characteristic frequency scale: FSR = 1/(2T) (free spectral range).

At low frequencies ( $f \ll {\rm FSR})$  the response functions factorize:

$$H_i(f,\Omega) \approx F_i(\Omega) * C(f).$$

where  $F_{+,\times}(\Omega)$  are static antenna-patterns,  $\Omega = (\phi, \theta, \psi)$ .

C(f) is an approximate frequency response for optimal orientation:

$$C(f) = \frac{1}{1 + if/f_{cav}}, \qquad f_{cav} \approx 86$$
 Hz.

## $H_{gw}(s)$ : exact and approximate forms (1)

Source coordinates:  $\phi = 0, \ \theta = 0, \ \psi = 0.$ 



## $H_{gw}(s)$ : exact and approximate forms (2)

Source coordinates:  $\phi = 0, \ \theta = 20^{\circ}, \ \psi = 0.$ 



# Comparison of $H_{gw}(s)$ and $H_L(s)$ (1)

**Calibration:** provides  $H_L(f)$  not  $H_{gw}(f)$ . The sensing function in the inverse calibration, C(f), is the response to length. This is transferred to the h(t)-channel.



At low frequencies the magnitude of the length response and that of the gravitational-wave response are almost the same. The phase is slightly different though.



Plot the ratio:  $H_{gw}(s)/H_L(s)$ : error in the magnitude < 0.5%, error in the phase < 10 degrees.



#### **Conclusions:**

- The frequency dependence of the antenna patterns does not introduce a significant error.
- The small difference in the phase (for  $f \leq 2000 \text{ Hz}$ ) due to the approximation of the GW-response with the length response needs to be taken into account.
- Static antenna patterns combined with the single-pole well approximate the true response.