



TDI Network Simulation

Jan Harms

Universität Hannover
Max-Planck-Institut für Gravitationsphysik

LSC meeting, Hannover

October 25, 2007



The Big Bang Observer

BBO

Big Bang Observer

Network.c (1)

Orbits.c

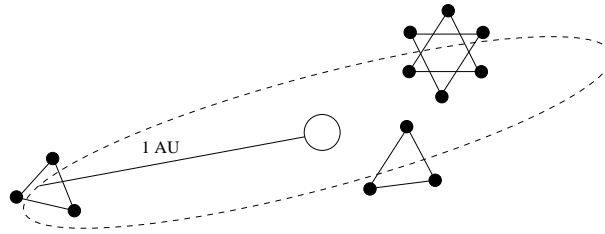
Detector.c

Response.c

Stochastic GW

Network.c (2)

Noise projection



- ✓ 4 LISA type space detectors
- ✓ Orbiting the sun at 1 AU
- ✓ Two collocated detectors

	Symbol	Value
Laser power	P_0	300 W
Received power	P_r	~ 9 W
Mirror diameter	D	2.5 m
Arm length	L	$5 \cdot 10^7$ m
Wavelength of laser light	λ	355 nm
Acceleration noise	$\sqrt{S_{\text{acc}}}$	$3 \cdot 10^{-17}$ m/(s ² √Hz)



Simple Pipeline

BBO

Network.c (1)

Simple Pipeline

Orbits.c

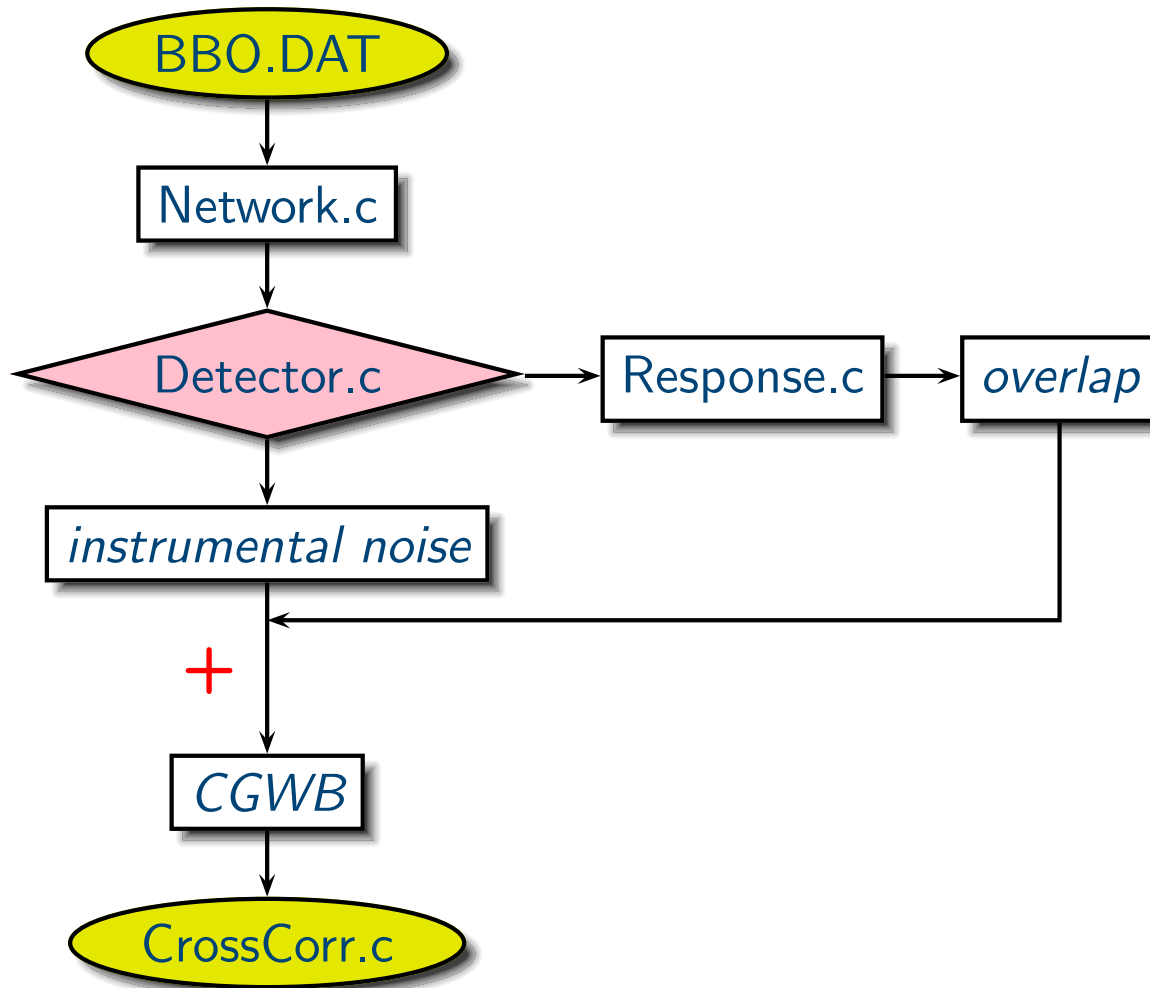
Detector.c

Response.c

Stochastic GW

Network.c (2)

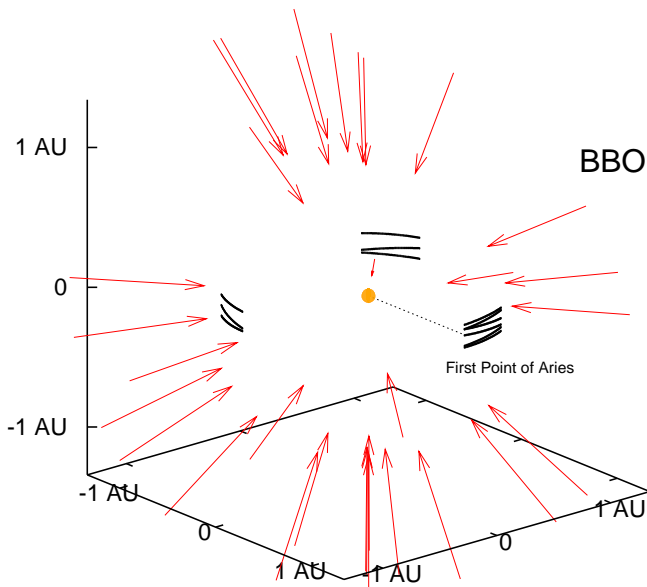
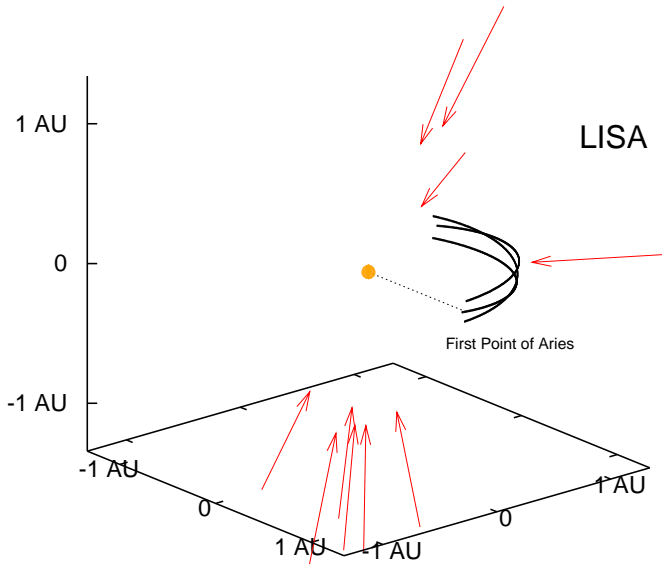
Noise projection





Moving detectors

- [BBO](#)
- [Network.c \(1\)](#)
- [Orbits.c](#)
- [Moving detectors](#)
- [Detector.c](#)
- [Response.c](#)
- [Stochastic GW](#)
- [Network.c \(2\)](#)
- [Noise projection](#)

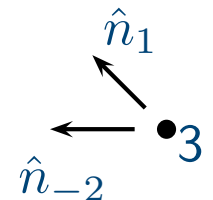
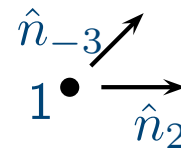
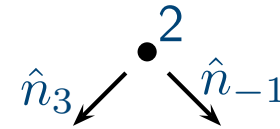


Time-dependent distance between spacecrafts:

$$L_l(t) = |\vec{p}_r(t) - \vec{p}_s(t - L_l(t)/c)|$$

Time-dependent light propagation direction:

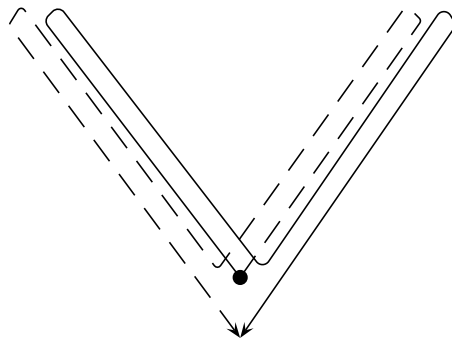
$$\hat{n}_l(t) = \frac{1}{L_l(t)} (\vec{p}_r(t) - \vec{p}_s(t - L_l(t)/c))$$





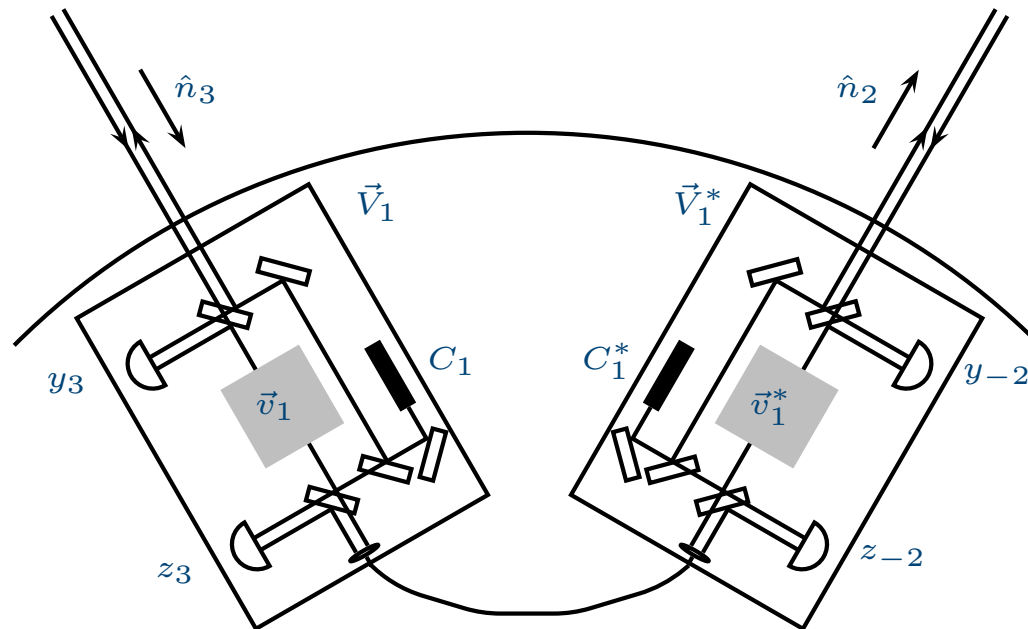
TDI

- [BBO](#)
- [Network.c \(1\)](#)
- [Orbits.c](#)
- [Detector.c](#)
- [TDI](#)**
- [GW Doppler signal](#)
- [Response.c](#)
- [Stochastic GW](#)
- [Network.c \(2\)](#)
- [Noise projection](#)



Unequal-arm Michelson

$$\begin{aligned}
 X(t) = & [y_{-3,32-2} + y_{3,2-2} + y_{2,-2} + y_{-2}] \\
 & - [y_{2,-2-33} + y_{-2,-33} + y_{-3,3} + y_3] \\
 & - 0.5 \cdot (z_{-2,2-2-33} - z_{3,-332-2}) - 0.5 \cdot (z_{-2} - z_3) \\
 & + 0.5 \cdot (z_{-2,2-2} - z_{3,2-2}) + 0.5 \cdot (z_{-2,-33} - z_{3,-33})
 \end{aligned}$$





GW Doppler signal

BBO

Network.c (1)

Orbits.c

Detector.c

TDI

GW Doppler signal

Response.c

Stochastic GW

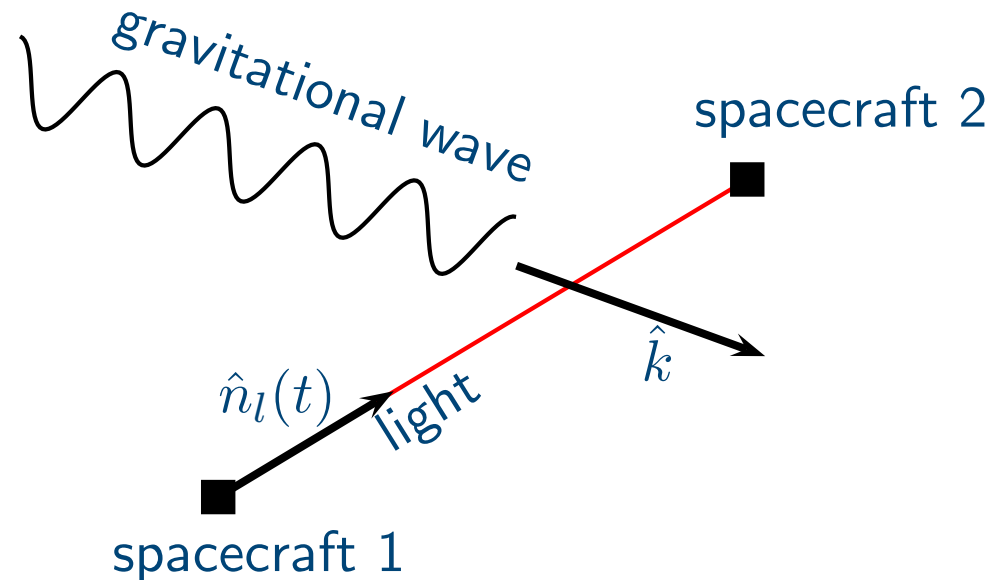
Network.c (2)

Noise projection

Projected GW Doppler signal:

$$y^{\text{GW}}(t) = \frac{1}{2(1 - \hat{k} \cdot \hat{n}_l(t))}$$

$$\hat{n}_l(t) \cdot \left(h(t_s - \hat{k} \cdot \vec{p}_s(t_s)) - h(t - \hat{k} \cdot \vec{p}_r(t)) \right) \cdot \hat{n}_l(t)$$





FD properties from dynamical models

BBO

Network.c (1)

Orbits.c

Detector.c

Response.c

FD properties

Transfer functions

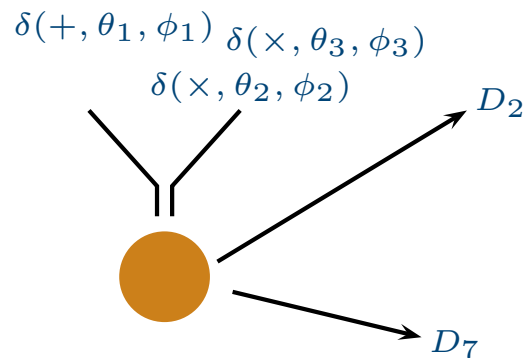
ORF

Response functions

Stochastic GW

Network.c (2)

Noise projection



1. Inject δ -peaks at the origin of a master coordinate system
2. Use retarded time to calculate GW signal at each detector
3. Calculate a detector output
4. Obtain FD functions via FFT

Example:

$$\gamma_{jk}(f_i) = \frac{1}{A} \sum_{\theta, \phi} \frac{\tilde{y}_j^+(f_i) [\tilde{y}_k^+(f_i)]^* + \tilde{y}_j^\times(f_i) [\tilde{y}_k^\times(f_i)]^*}{T}$$



Transfer functions

BBO

Network.c (1)

Orbits.c

Detector.c

Response.c

FD properties

Transfer functions

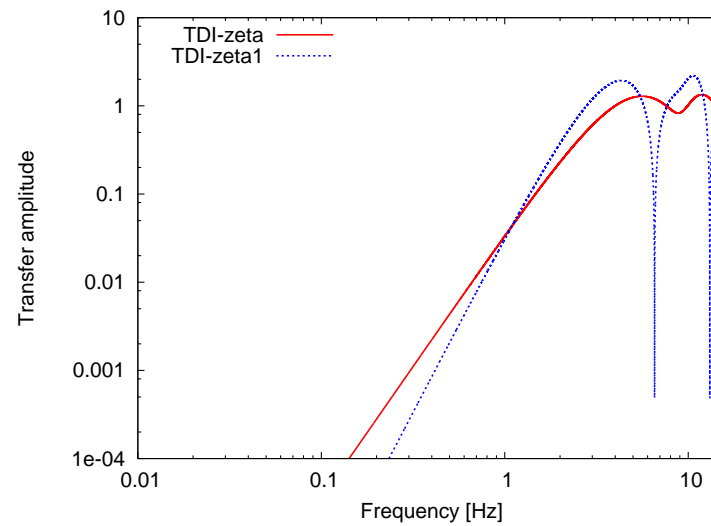
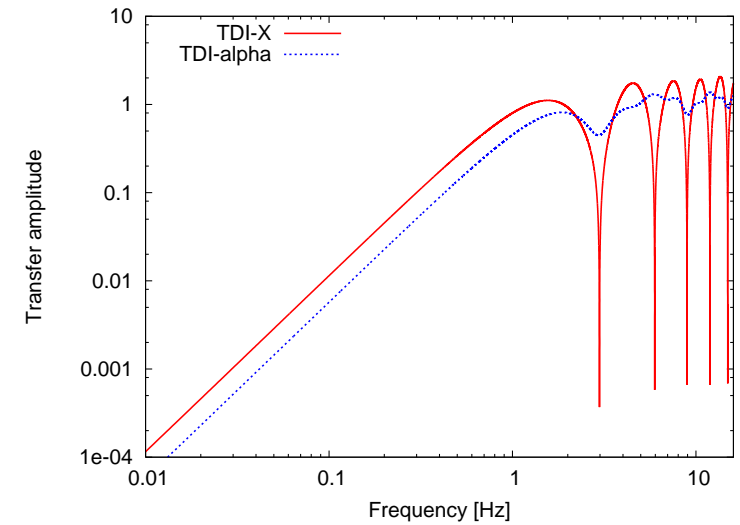
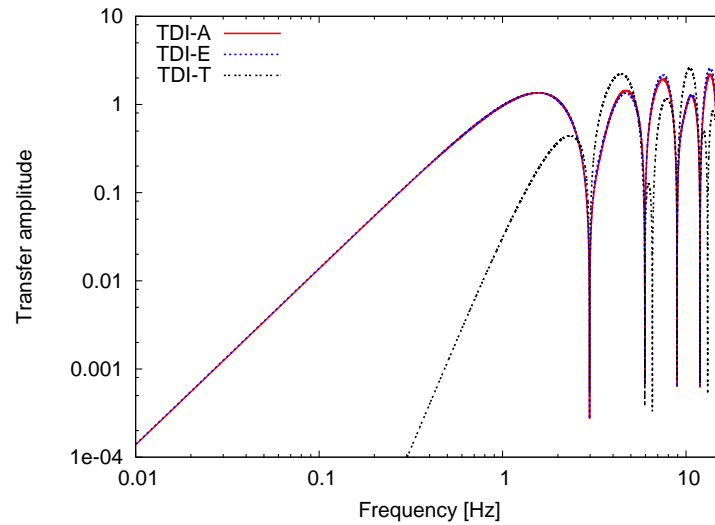
ORF

Response functions

Stochastic GW

Network.c (2)

Noise projection





Overlap-reduction functions

BBO

Network.c (1)

Orbits.c

Detector.c

Response.c

FD properties

Transfer functions

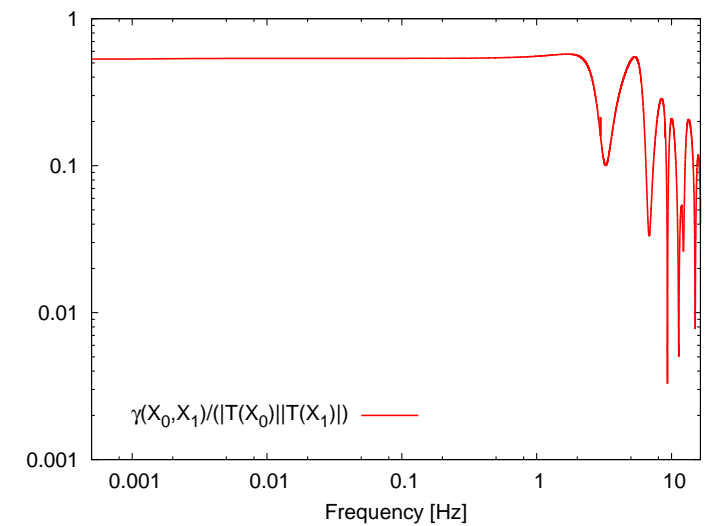
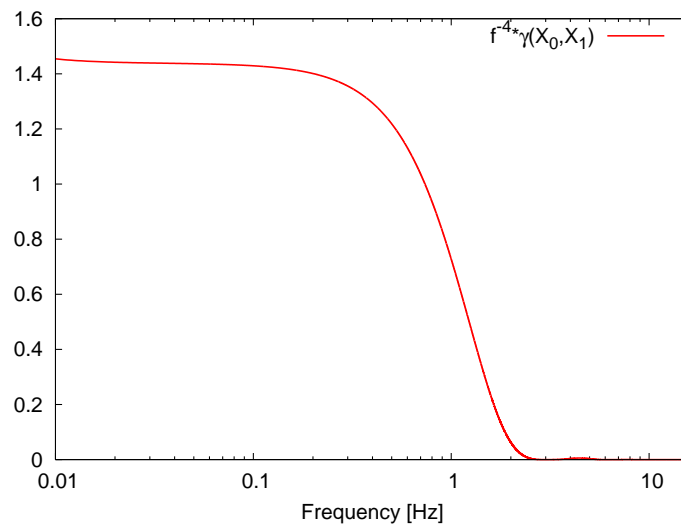
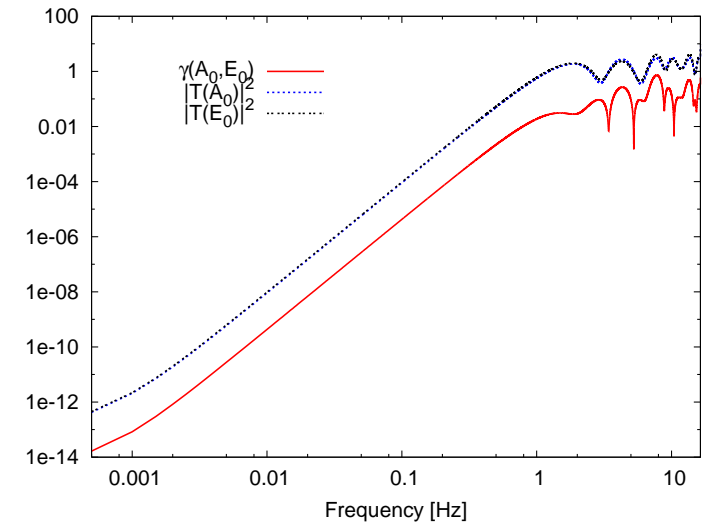
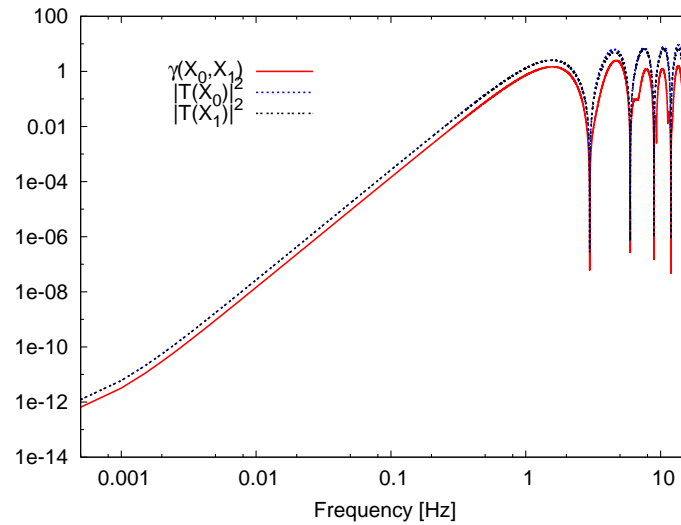
ORF

Response functions

Stochastic GW

Network.c (2)

Noise projection





Response functions

BBO

Network.c (1)

Orbits.c

Detector.c

Response.c

FD properties

Transfer functions

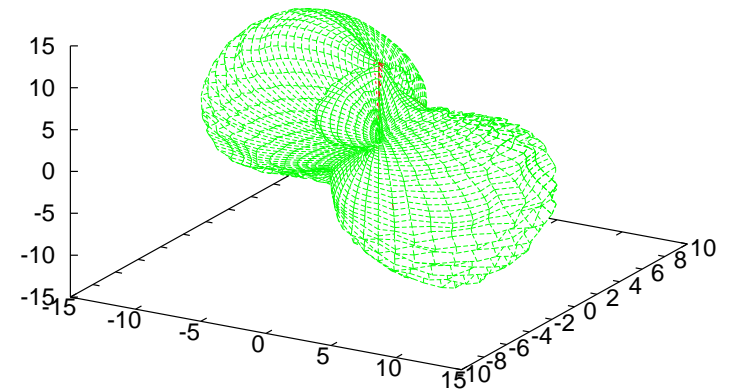
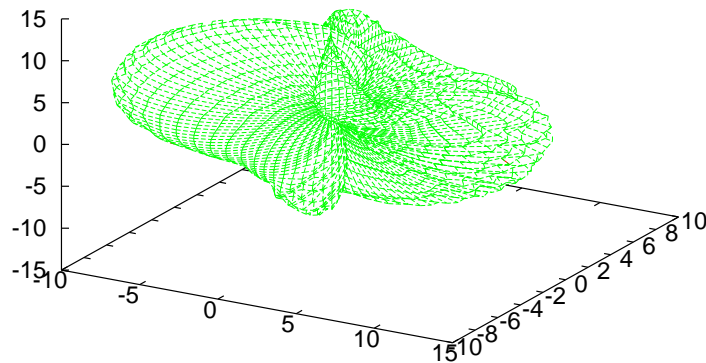
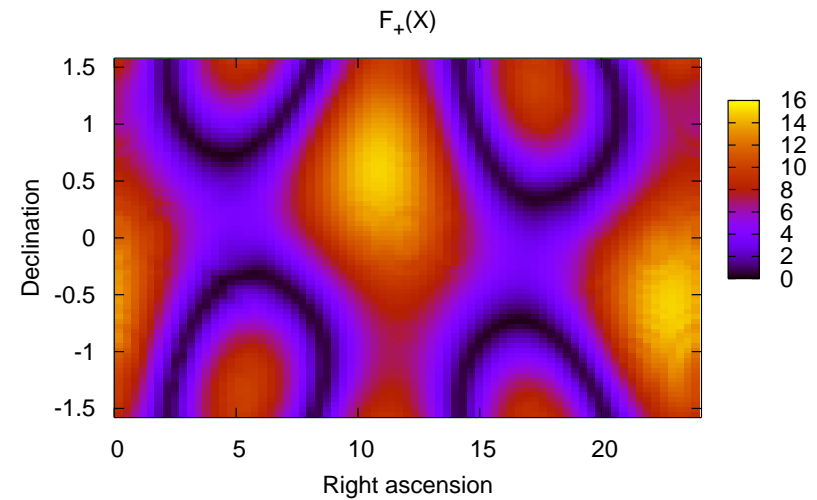
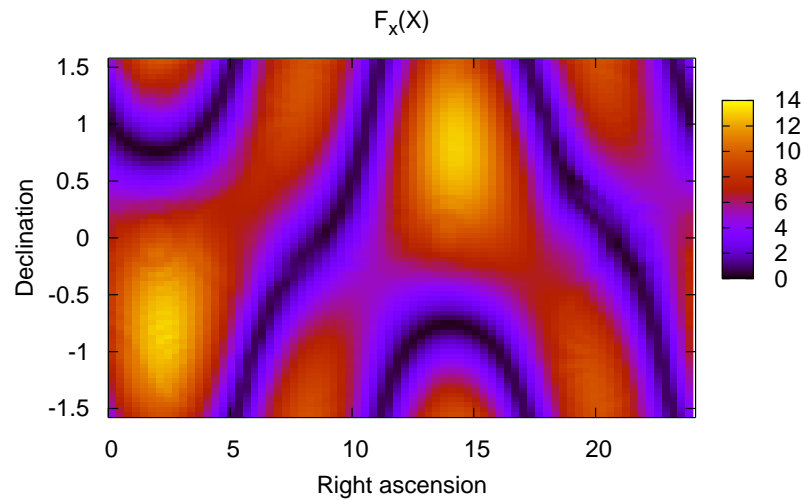
ORF

Response functions

Stochastic GW

Network.c (2)

Noise projection





Primordial.c

BBO

Network.c (1)

Orbits.c

Detector.c

Response.c

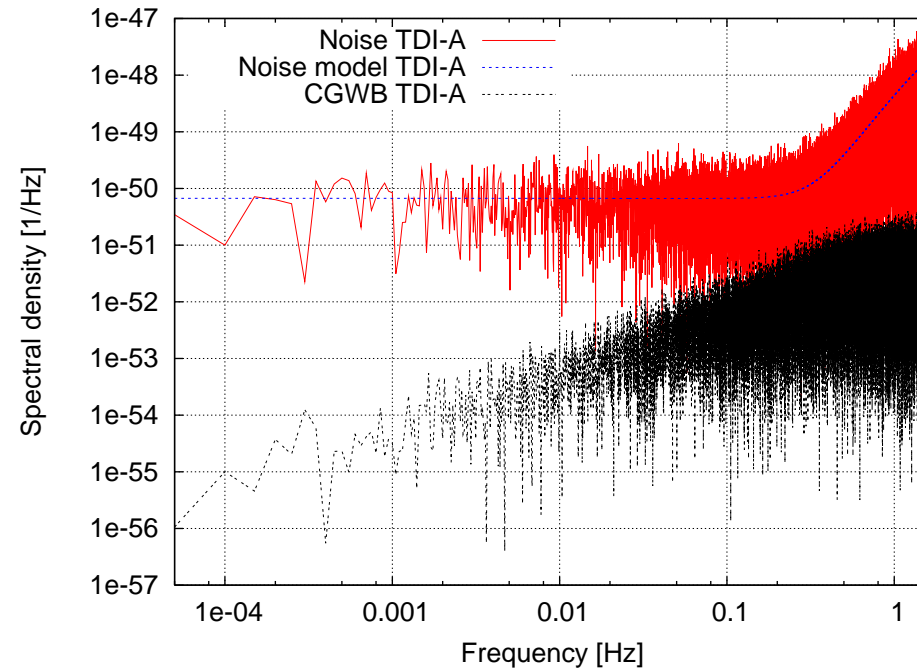
Stochastic GW

Primordial.c

CrossCorr.c

Network.c (2)

Noise projection



$$\tilde{y}_1^h = \sqrt{\frac{T \cdot S_{\text{gw}}}{2}} \gamma_{11} (n_1 + i n_2)$$

$$\tilde{y}_2^h = \tilde{y}_1^h \frac{\gamma_{12}}{\gamma_{11}} + \sqrt{\frac{T \cdot S_{\text{gw}}}{2}} \sqrt{\gamma_{22} - \frac{|\gamma_{12}|^2}{\gamma_{11}}} (n_3 + i n_4)$$



CrossCorr.c

BBO

Network.c (1)

Orbits.c

Detector.c

Response.c

Stochastic GW

Primordial.c

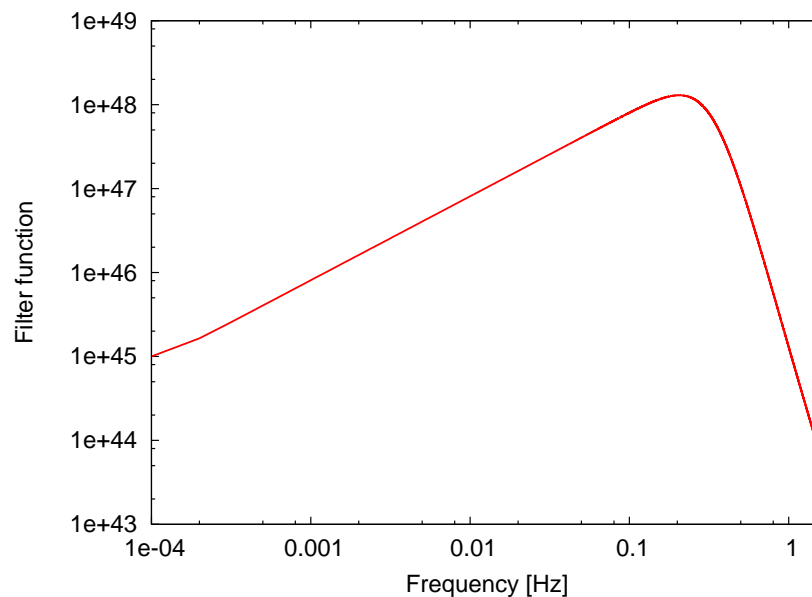
CrossCorr.c

Network.c (2)

Noise projection

$$\text{Cross correlation: } \langle S \rangle = \frac{1}{N} \left| \sum_{i=0}^N \frac{\tilde{y}_1(f_i) [\tilde{y}_2(f_i)]^*}{T} \tilde{Q}(f_i) \right|$$

$$\text{Optimal filter: } \tilde{Q}(f_i) = \frac{\gamma_{12}(f_i) S_{\text{gw}}(f_i)}{S_1^n(f_i) S_2^n(f_i)}$$



Sensitivities with respect to stochastic backgrounds:

✓ LISA: $\Omega \gtrsim 10^{-12}$
(needs to be checked)

✓ BBO: $\Omega \gtrsim 10^{-17}$



Complete Pipeline

BBO

Network.c (1)

Orbits.c

Detector.c

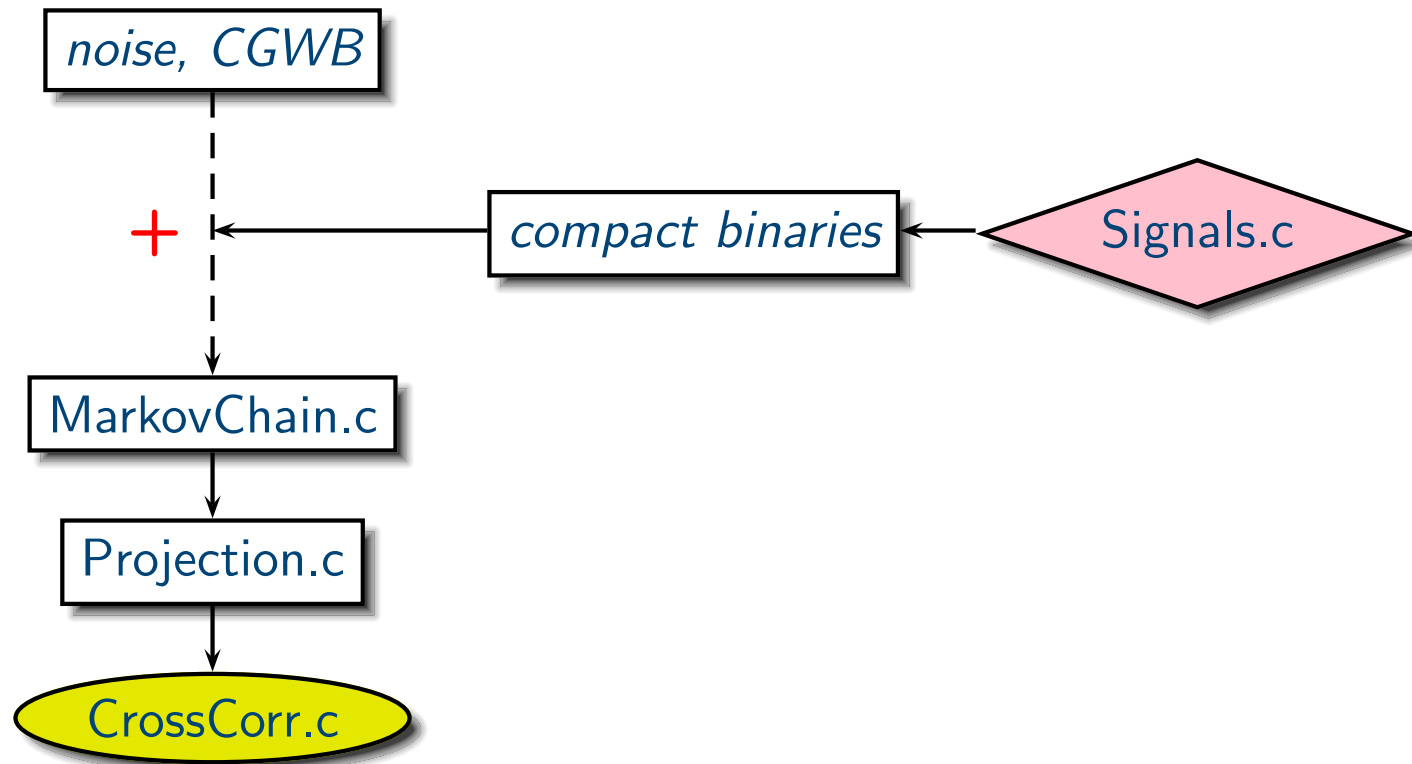
Response.c

Stochastic GW

Network.c (2)

Complete Pipeline

Noise projection





Projection.c

BBO

Network.c (1)

Orbits.c

Detector.c

Response.c

Stochastic GW

Network.c (2)

Noise projection

FisherMatrix.c

Projection.c

1. Generate best fits: $\hat{\lambda}^\alpha = \Gamma_N^{\alpha\beta} \langle n | \partial_\beta h \rangle$
2. Subtract best fits from data: $\delta s = s - \hat{h}$, with $\hat{h} = h(\hat{\lambda})$
3. Project residual data: $\delta s_\perp = \delta s - \Gamma^{\alpha\beta} \langle \delta s | \partial_\alpha h \rangle \cdot \partial_\beta h$

