



LIGO Data Analysis and Simulation Summary

7th Meeting of the LIGO PAC

Cambridge, Massachusetts

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Albert Lazzarini

LIGO Laboratory Caltech



E2E Development Status

- Schedule is ~ 4 months behind plan
 - Discovered an architectural issue in simulation engine- e.g. difficulty in dealing with servo loops
 - Miscellaneous code improvements along the way
 - Debugging of code elements more difficult than expected
 - Scientist and Programmer shortage
 - ♦ Lost one programmer;
- Goal for next 6 months
 - Catch up to hardware configuration - 2k FP or short Michelson
 - Improve mechanical simulation (add realism)
 - Greater LSC participation



LDAS Development Status

- Implementation is behind plan
 - » $\alpha 1$, $\alpha 2$ releases will be combined to a single α release, ~6 month delay
 - » β released still planned for end of 2000
- Reasons
 - » Staffing ramp-up slower than expected
 - Learning curve
 - Programming staff retention (lost 3, looking for 2)
 - » Development of infrastructure is a front-loading activity
 - Extensive core API module development
 - C++ frame library development (1/2 m-yr)
 - C++ code standardization to ANSI specification (egcs -> gnu 2.95.1 transition took ~ 2 months)
 - » Early investment of time to develop tools to leverage lean staff'
 - Developed www page online resources to assist new programmers
 - Extensive use of cfengine scripting utility to enforce OS installation configuration control across remote sites from Caltech



LDAS Development Status

- Reasons
 - » Early investment of time to develop tools to leverage lean staff
 - Extensive use of autoconfig/automake unix utilities to compile, build code releases
 - ◆ Difficult learning curve to implement well, correctly
 - ◆ Long term labor saver to permit automated code builds, releases, along with automated documentation generation (html)
 - ◆ Permits uniform code environment to be enforced across all LIGO sites, remotely managed from Caltech
- Solutions
 - » Add 2 senior programmers
 - Access to existing LIGO programmers coming off other work
 - Offloading existing programmer from system administration load
 - New hire
 - » Development of new modules reuses much of code foundation



Laboratory - LSC Coordination

- LSC White Paper on Data Analysis
 - » Co-authored by Tom Prince
 - » Draft released 27 October 1999, pending LSC review, adoption

- Draft specification for algorithm library software drafted, released for review
 - » LLAL: LIGO/LSC Algorithm Library
 - » C code implementation
 - » Interface to on-site & off-site analysis pipelines
 - » Test of specification through prototype code development



Laboratory - LSC Coordination

- **LSC Software Coordinator**
 - » Role identified in white paper, no candidate identified
 - » Interim role filled by committee appointed by LSC Spokesman, LIGO Director
 - S. Anderson (Chair, LIGO Lab), L. S. Finn (PSU), M. A. Papa (GEO/AEI Potsdam) , T. Prince (LIGO Lab), A. Wiseman (UWM)
 - Charter:
 - ♦ Review/approve LLAL S/W specification
 - ♦ Coordinate SW development schedule with Lab.
 - ♦ Define code acceptance, validation criteria
 - ♦ Coordinate code archive with Laboratory
- **International data analysis working group**
 - » Reports to GWIC regarding coordination of data analysis among major international programs
 - » Joint Lab, LSC representation
 - » 1st meeting scheduled for Rome on 4 Dec 1999

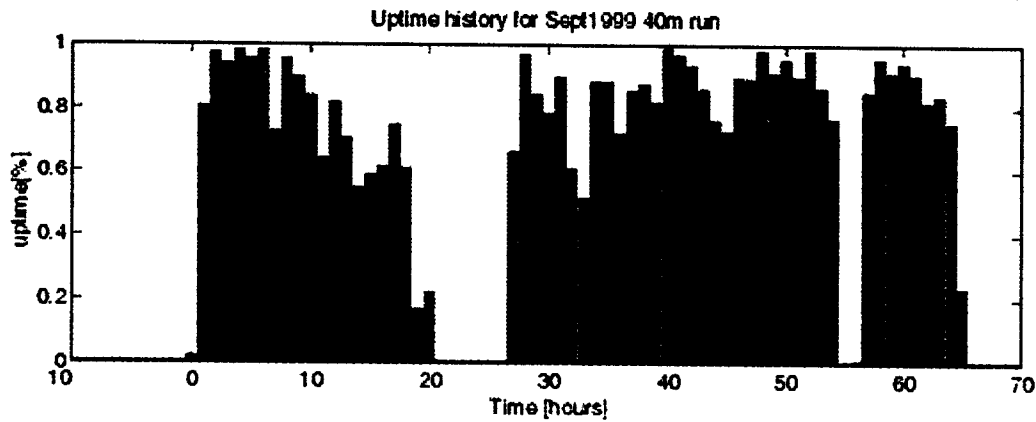


Laboratory - LSC Coordination

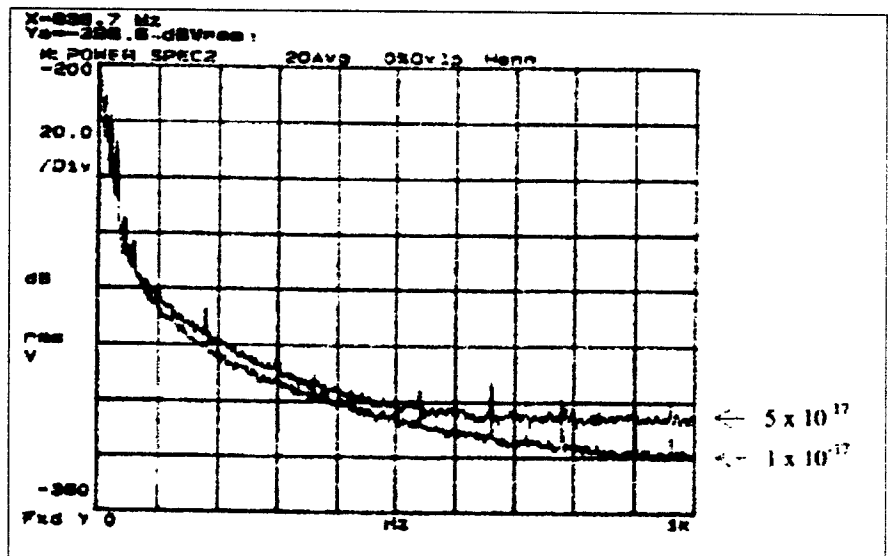
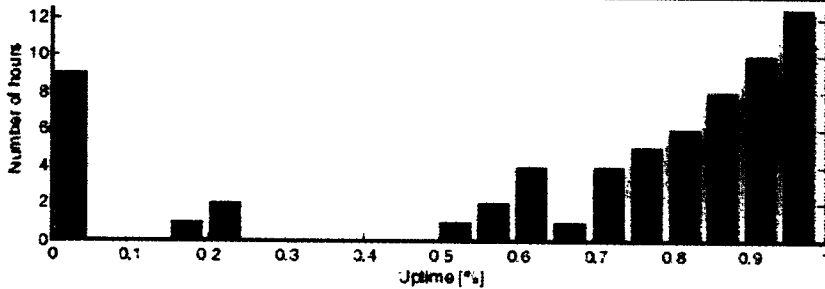
- Mock data challenges
 - » LSC-led effort to organize a simulated 2-interferometer analysis of 40m data (split run into two segments, shift second in time)
 - Reprocess data set for binary chirps
 - Develop event list
 - Use LDAS metadata tables to log events, perform queries, sorts
 - Pending announcement of proposed activity to LSC
 - ◆ Open to interested participants
 - » 40m + TAMA coincidence run
 - 3-day run coincided with TAMA run;
 - Coordinated at Caltech by University of Michigan and LIGO
 - ◆ Data transmission/storage to HPSS (900GB, 99.9+% availability; no lost data)



40m - TAMA Run Summary



Tama LOCKED
 Tama UNLOCKED





CACR Collaboration with LIGO

- Mass data storage technology for LIGO I
 - » Use of HPSS for LIGO prototype tests
 - Performance evaluation - bandwidth, reliability, sizing for LIGO I
 - Direct (real time) archival of 40m datastream
 - LSC access to existing 40m databases
 - » Use of existing HPSS infrastructure for LIGO I
 - Space in CACR StorageTek robotic silo (100+TB, 2000 cassettes*)
 - Site license
 - Direct connection to Calren2, LIGO Caltech WAN
 - Enhancements by LIGO Laboratory for LIGO/LSC specific use
 - ◆ Robotic arm upgrade (?)
 - ◆ 4 tape heads (StorageTek 9840 tape drives)
 - ◆ SP2 nodes to control tape heads
 - ◆ High Perf. Gateway Node for communication
 - ◆ Intermediate disk cache (SSA, ~400+GB)
 - » 1 LIGO FTE to support LIGO HPSS operations



CACR Collaboration with LIGO

- Cluster computing
 - » Access to CACR expertise in prototyping beowulf (linux cluster) at LIGO
 - » Site of LIGO I production beowulf under review (CACR vs. LIGO Lab)

- Supercomputing
 - » LSC access to CACR supercomputers
 - » LIGO Laboratory provides interface for LSC members to CACR
 - User accounts (includes HPSS databases)
 - Block time allocation

- Software development of user (www)interfaces
 - » Prototype of GUIs to view frame, xml data
 - » Write data to Matlab files for analysis



LDAS Procurement Approach

- All items commercial, off-the-shelf
 - » Multiple vendor quotes, catalog items, etc.
- Flexible, extensible
- Tests on prototypes, loaners, etc.

- Networking/switching technology
 - » ATM (OC3/OC12) using LANE
 - LAN
 - Server-server connections
 - » Ethernet (100BT/1000BT)
 - Server connections to LAN
 - PC cluster interconnections



LDAS Procurement Approach

- CPUs & workstations
 - » SUN
 - For licensed applications, databases
 - ♦ HPSS (v 4.2)
 - ♦ DB2 (IBM)
 - LDAS APIs
 - » Intel Pentium
 - Linux
 - LDAS APIs

- Mass storage technology
 - » Robotic tape systems
 - Large scale system for Caltech archive
 - ♦ HPSS (IBM or SUN)
 - ♦ 100+TB in campus StorageTek Silo
 - ♦ 4 9840 drives



LDAS Procurement Approach

- Mass storage technology
 - » Robotic tape systems
 - Medium volume system at each site for near term look-back (~20TB)
 - ◆ StorageTek Timberwolf with 9840 drives compatible with HPSS at Caltech
 - Small volume system for (few) tapes for experimenters at each site
 - ◆ AIT-2 (SONY/Cybernetics) technology
 - ◆ 10 - 20 cassette robot
 - » Disk systems
 - Serverless RAID system (e.g., Network Appliances 760) for on-site data cache
 - ◆ ~1 TB for Hanford
 - ◆ Robust
 - ◆ High performance throughput
 - ◆ Does not need server
 - SSA (IBM) intermediate disk cache for HPSS (400+ GB)