# Status Update of the aLIGO lock acquisition simulation

# General Status:

- Set up Linux environment
- Started building Model from scratch
- Finished setting up the interferometer part
- Began checking the open IFO response
- Not yet closed any of the locking loop
- Phone-based simulation support by Hiro

### Motivation is to answer the questions such as

#### Can we lock the full IFO?

#### How exactly are we going to lock the IFO?

We know the big picture e.g. 3f locking for central part and ALS for the arm

#### How do we hand-off the CARM from the ALS control to infrared?

ALS guarantees sub-nm stability while CARM line width ~ 10 pm.

#### How do we offload the CARM offset?

### How are we going to automate the locking progression?

Guardian script? Some kind of fast switch? Beckoff synchronization?

### What was done in the past and what will be done

### L. Barsotti (2008 ?) did an E2E simulation:

- Demonstrated usefulness of 3f lock in aLIGO configuration
- Various way of CARM signal extraction when offsetted Assuming ALS provides a super stable arm motion
- Reflective SRM T = ??? %
- Parallel EOM modulation. No SBs on SBs.

### We (2013) will do an E2E simulation:

- Locking with the up-to-date aLIGO parameters.
  - => seismic noise, ALS stability, control functionality, signal extraction scheme.
- Transmissive SRM T = 37 %
- Serial EOM modulation. SBs on SBs.

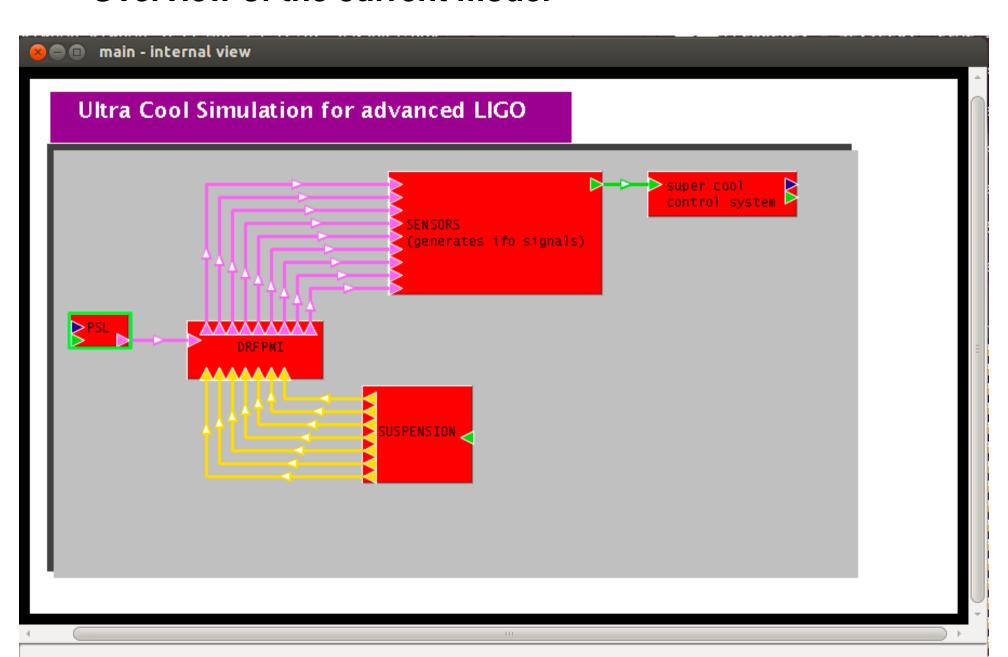
# **Configuration at the beginning (Proposed)**

- \* No radiation pressure
- \* No sophisticated suspension (instead a digital filter plist white noise)
- \* Serial EOM modulation
- \* Transmissive SRM
- \* no electronics noise
- \* Realistic seismic noise and ALS stablity

# Plan in the upcoming two weeks:

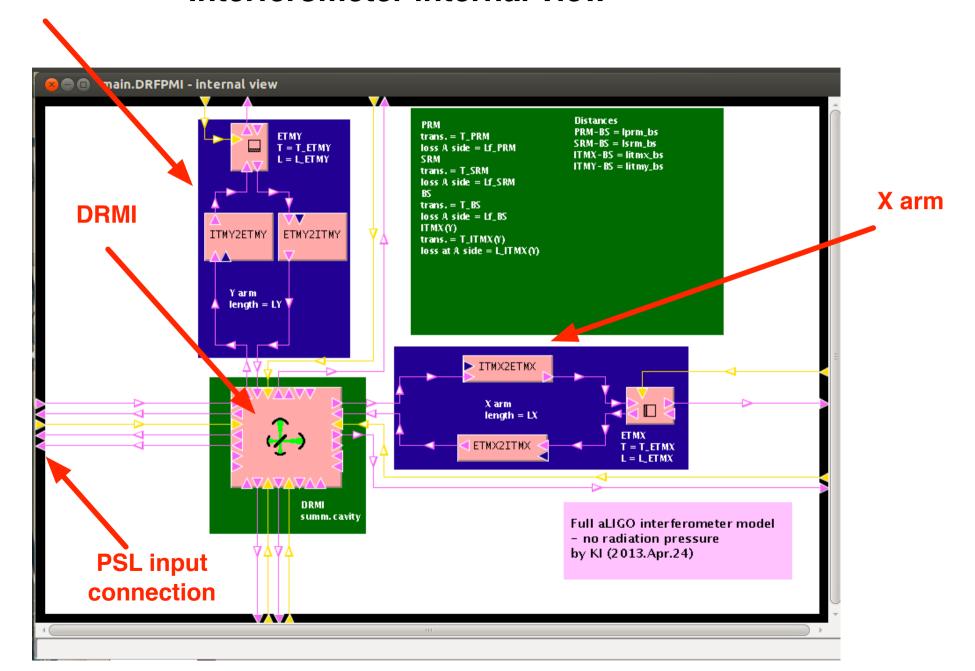
- \* Finish verifying the IFO response (comparison with Optickle)
- \* Hopefully Start closing the loops

### Overview of the current model



#### Y arm

### Interferometer internal view



## PSL internal view

