

# Simulating the Advanced LIGO Interferometer Using the Real Control Code

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# Acknowledgments

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## Mentor

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# What can be done?

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Implementing a real-time simulation of the hardware that communicates to the control code will generate a practical troubleshooting technique.

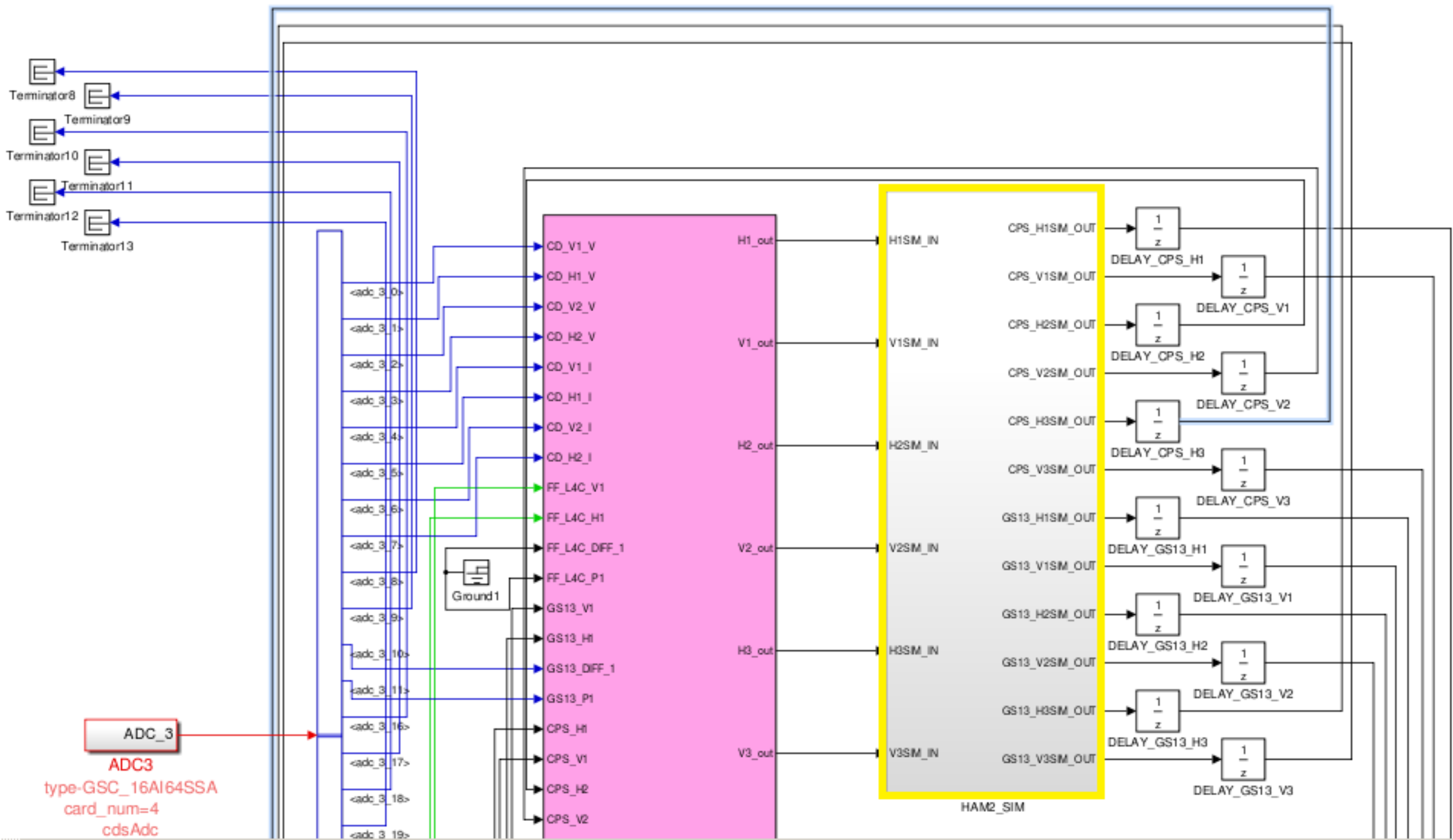
# Things to Keep in Mind

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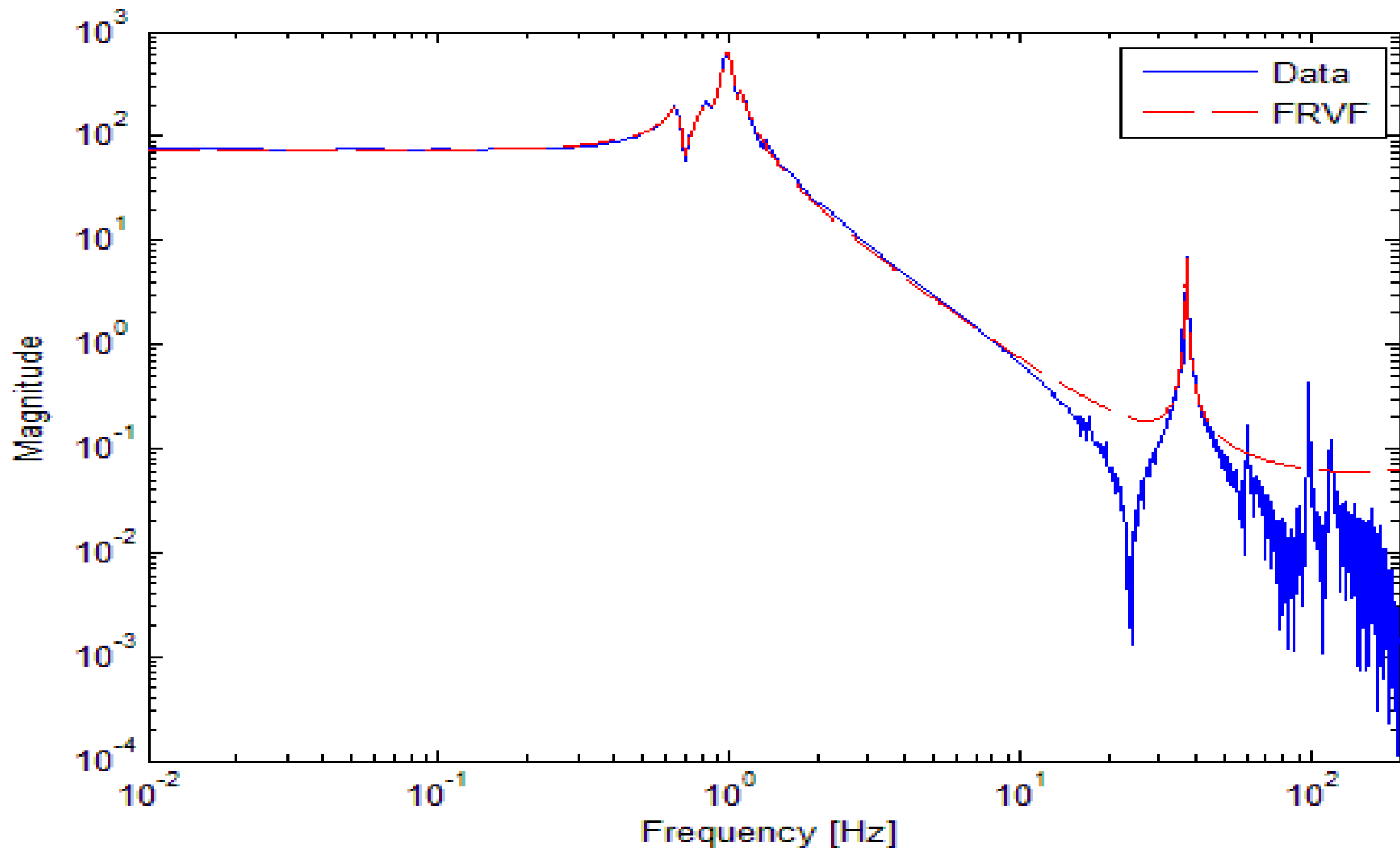
How do we develop a simulation?

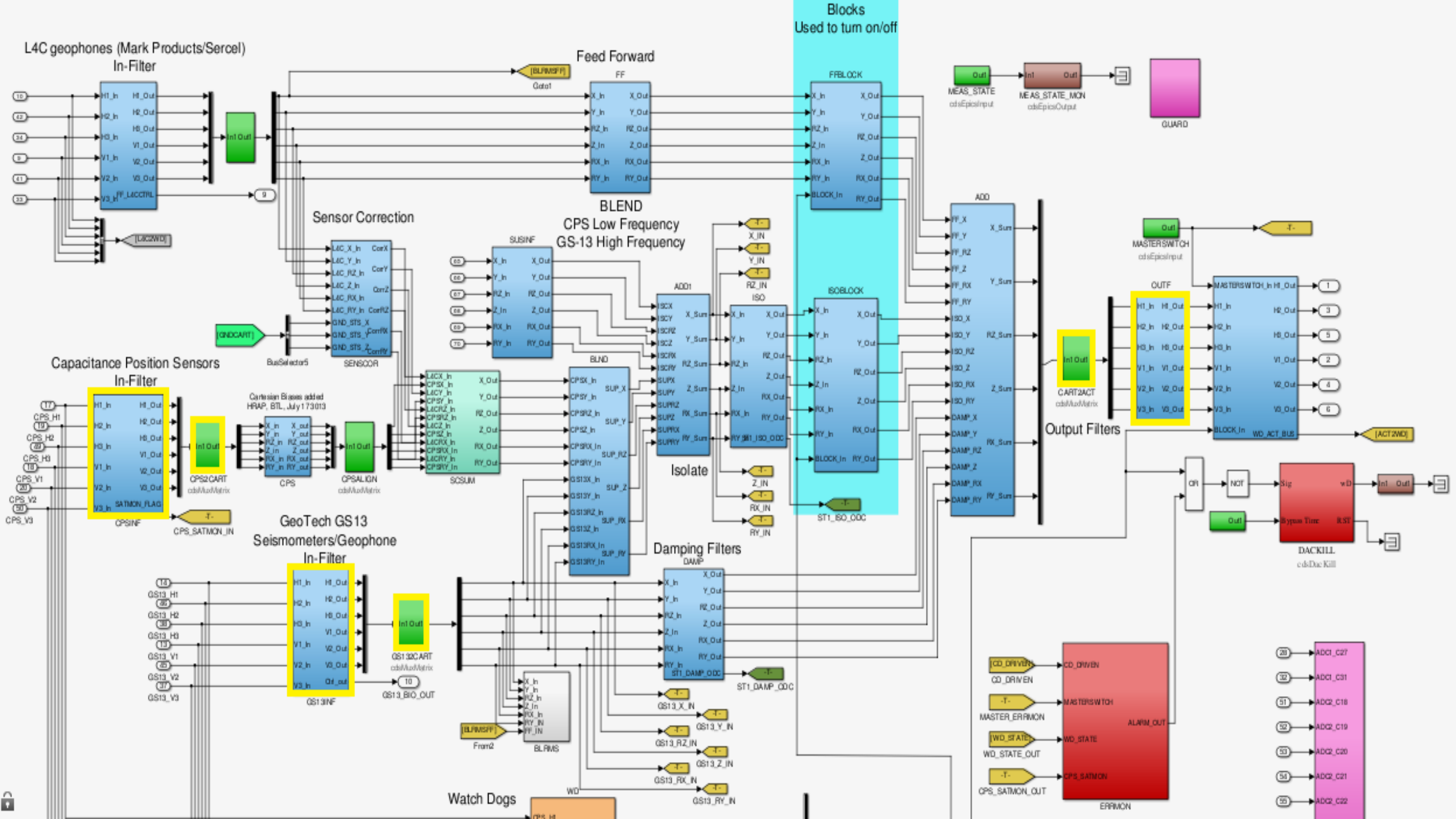
What is noise and how do we simulate it?

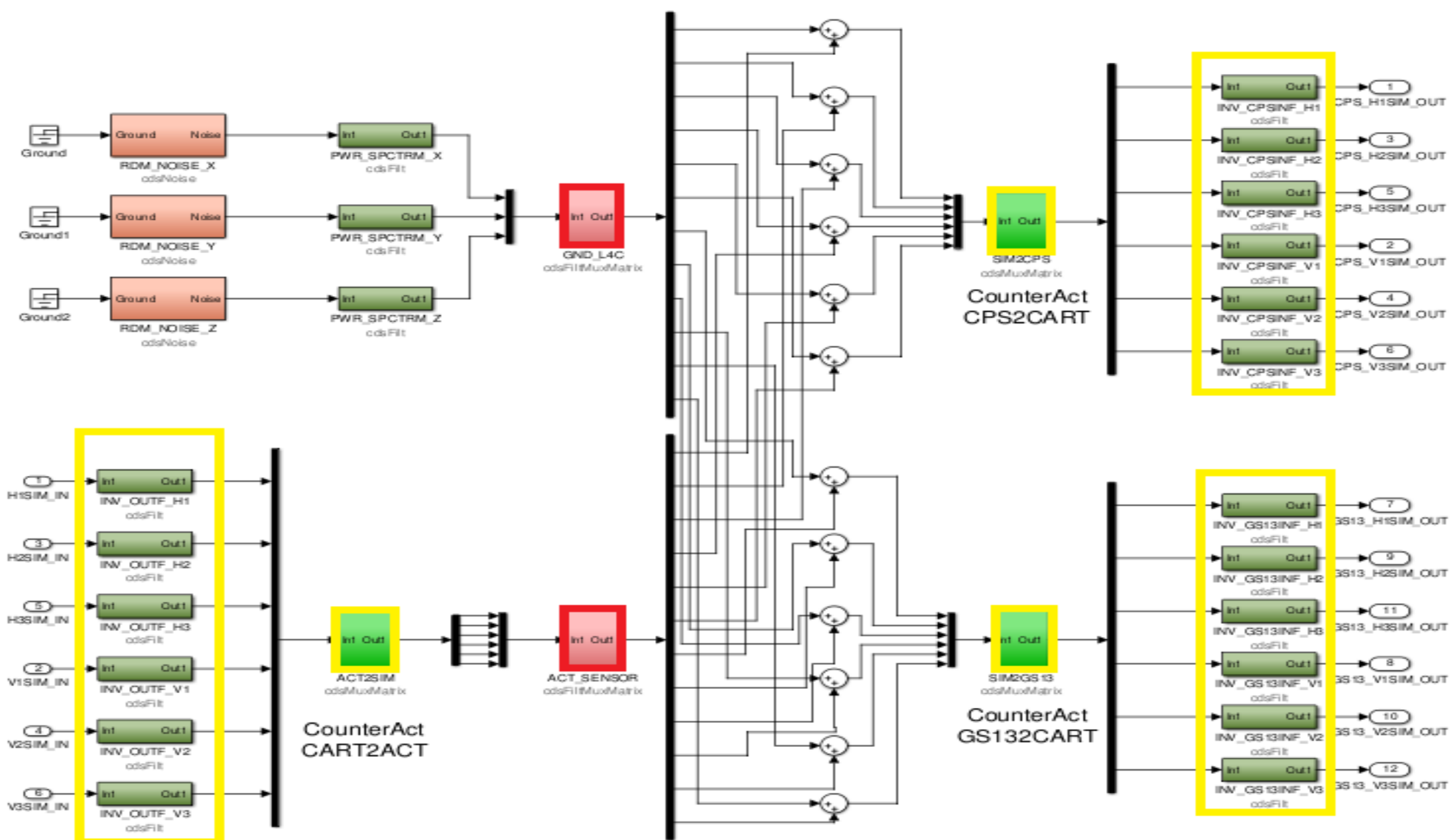
What have we learned during this process?



ADC3  
 type-GSC\_16A164SSA  
 card\_num=4  
 cdsAdc

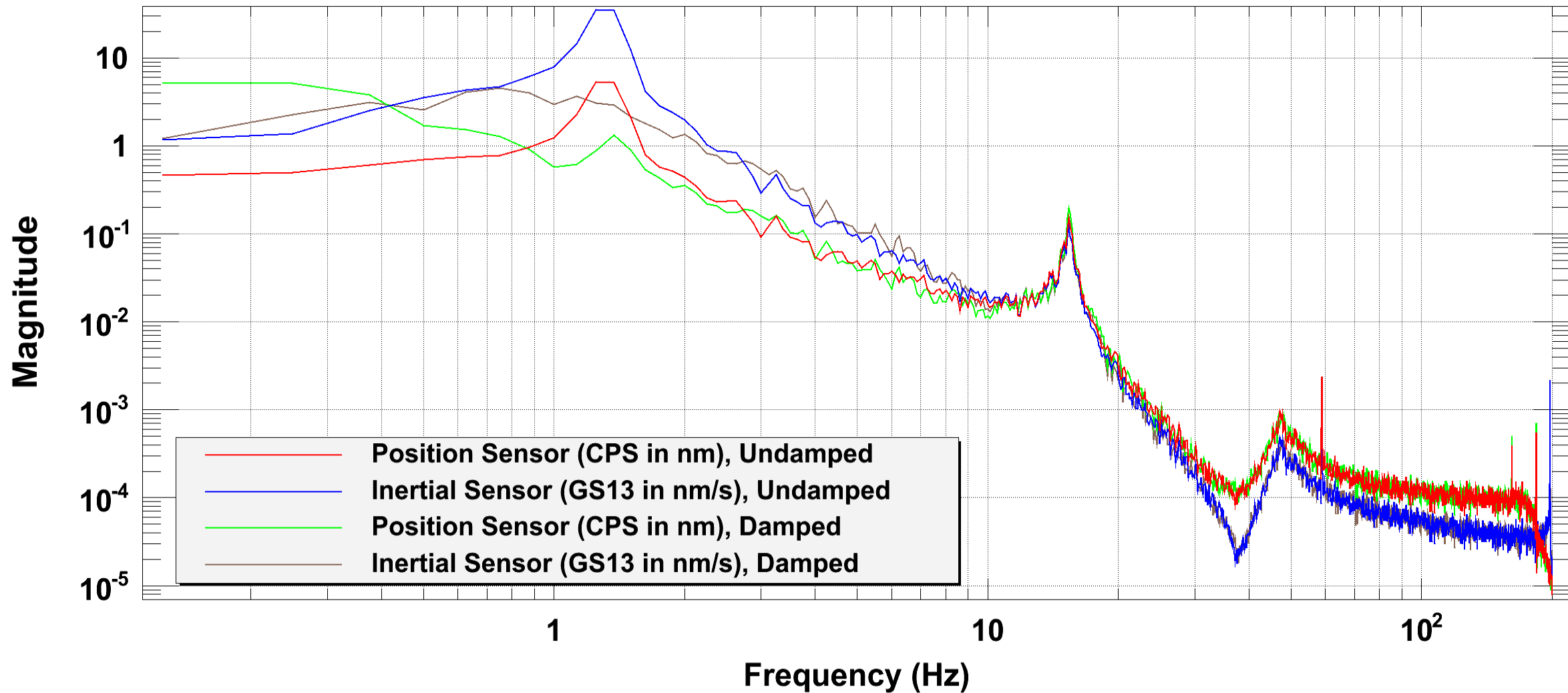








# Power spectrum



— Position Sensor (CPS in nm), Undamped  
— Inertial Sensor (GS13 in nm/s), Undamped  
— Position Sensor (CPS in nm), Damped  
— Inertial Sensor (GS13 in nm/s), Damped

**\*T0=20/08/2013 17:20:38**

**Avg=11**

**BW=0.1875**

# OVERVIEW

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Learned about noise and filters

Discussed framework of simulation

Explained how to interpret and expand