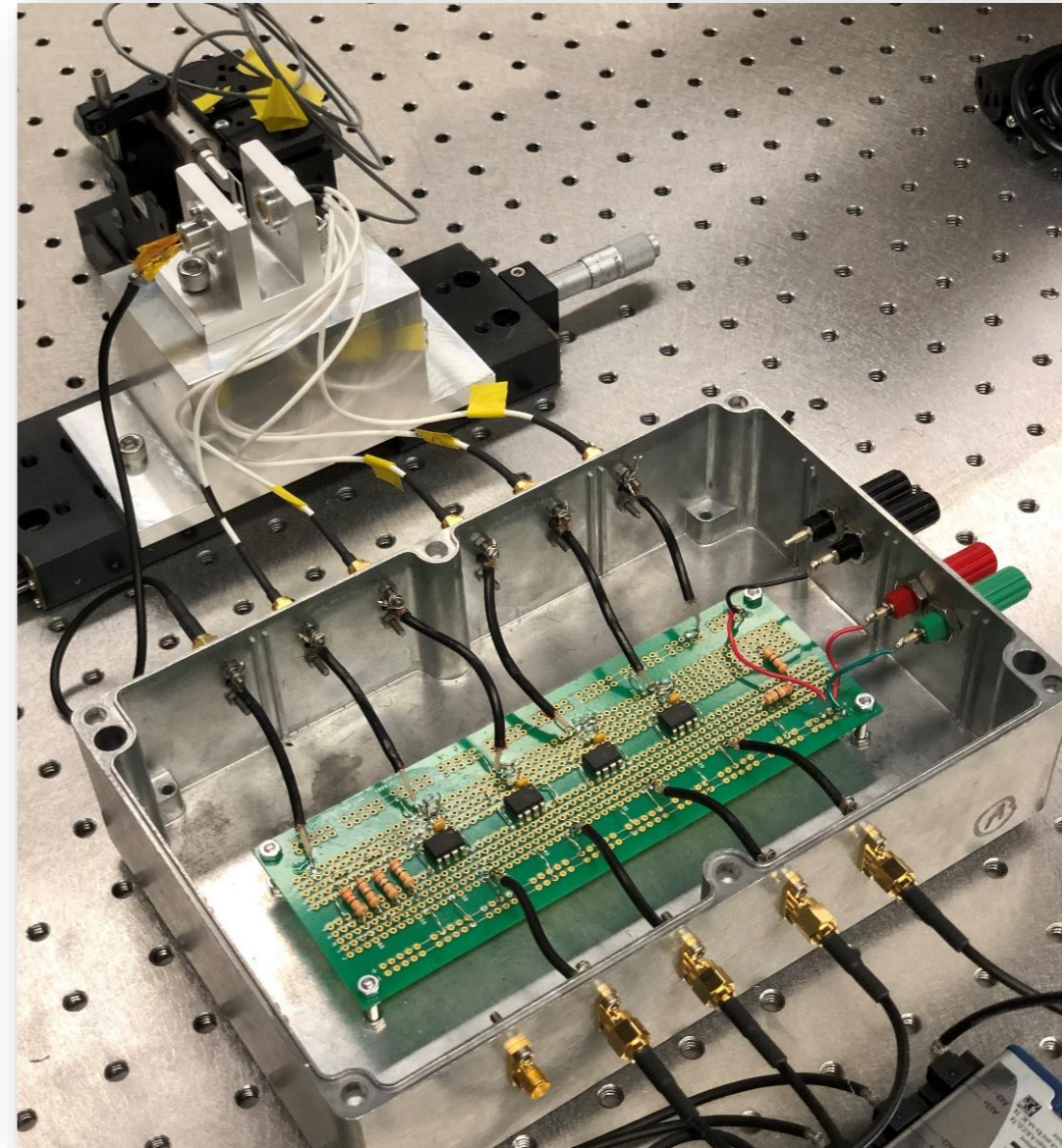


Progress in Developing a Differential OSEM (DOSEM)

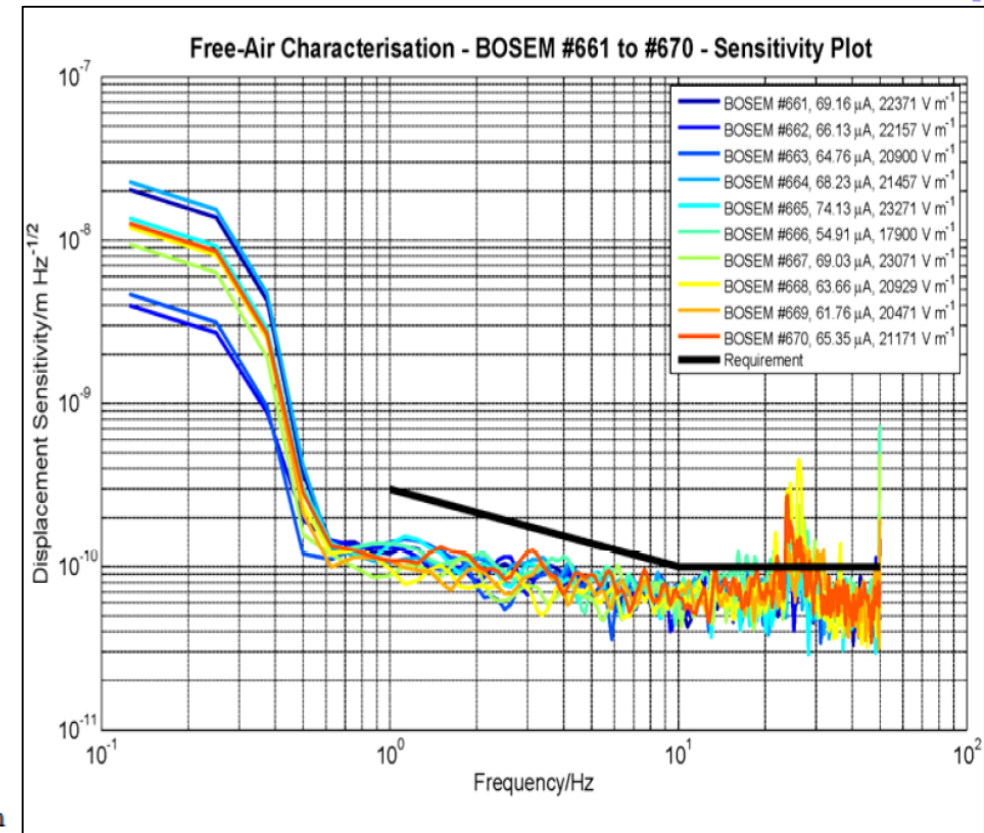
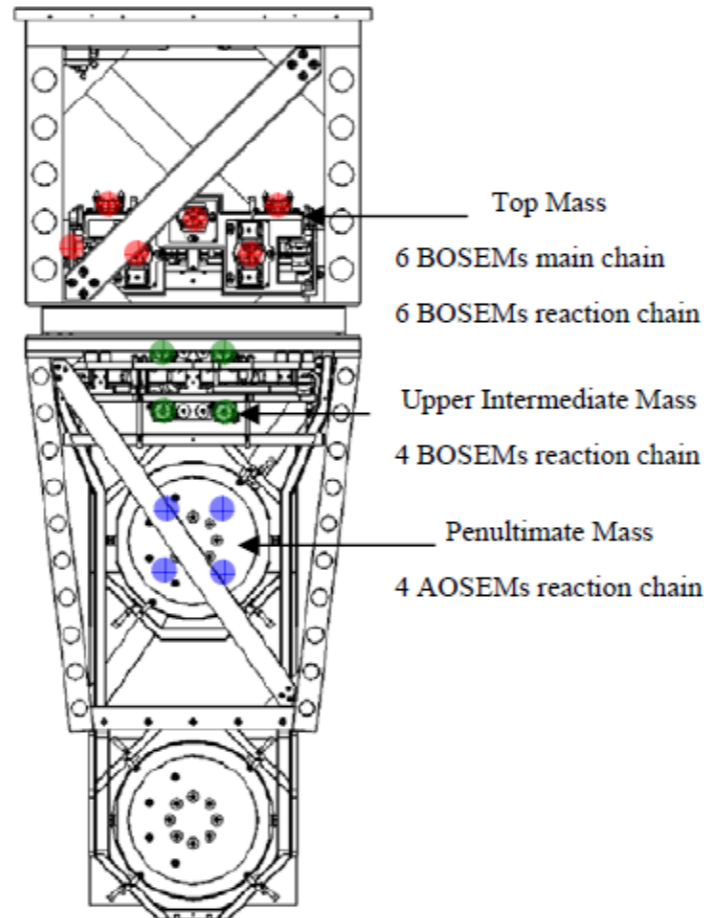
John W. Conklin, Deep Jariwala,
Thida Preschari, Henri Inchauspe,
Paul Fulda, David Tanner

LIGO-G1900464-v1



OSEMs & Motivation

- Optical Sensor and Electro-Magnetic actuators (OSEMs)
 - Measures, actuates multiple DOF of Top Mass, UIM, PUM
- As-installed performance of BOSEMs (thanks Arnaud)
 - 30-200 pm/Hz^{1/2} @ 10 Hz
 - 150-2000 pm/Hz^{1/2} @ 1 Hz
- May limit low frequency performance of aLIGO via control system
- Goal: Improve sensitivity and reduce systematics

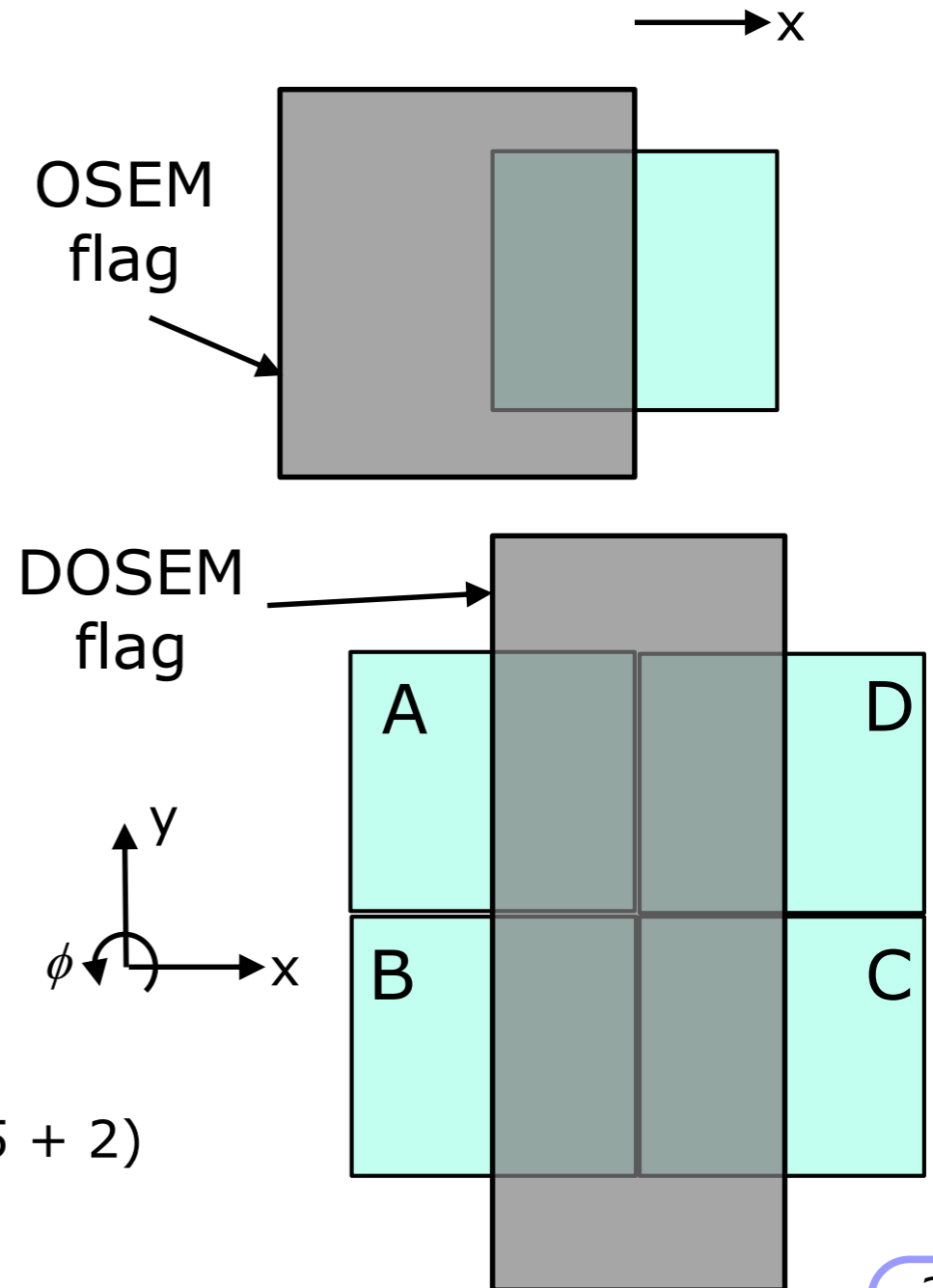


[SM Aston 2011]



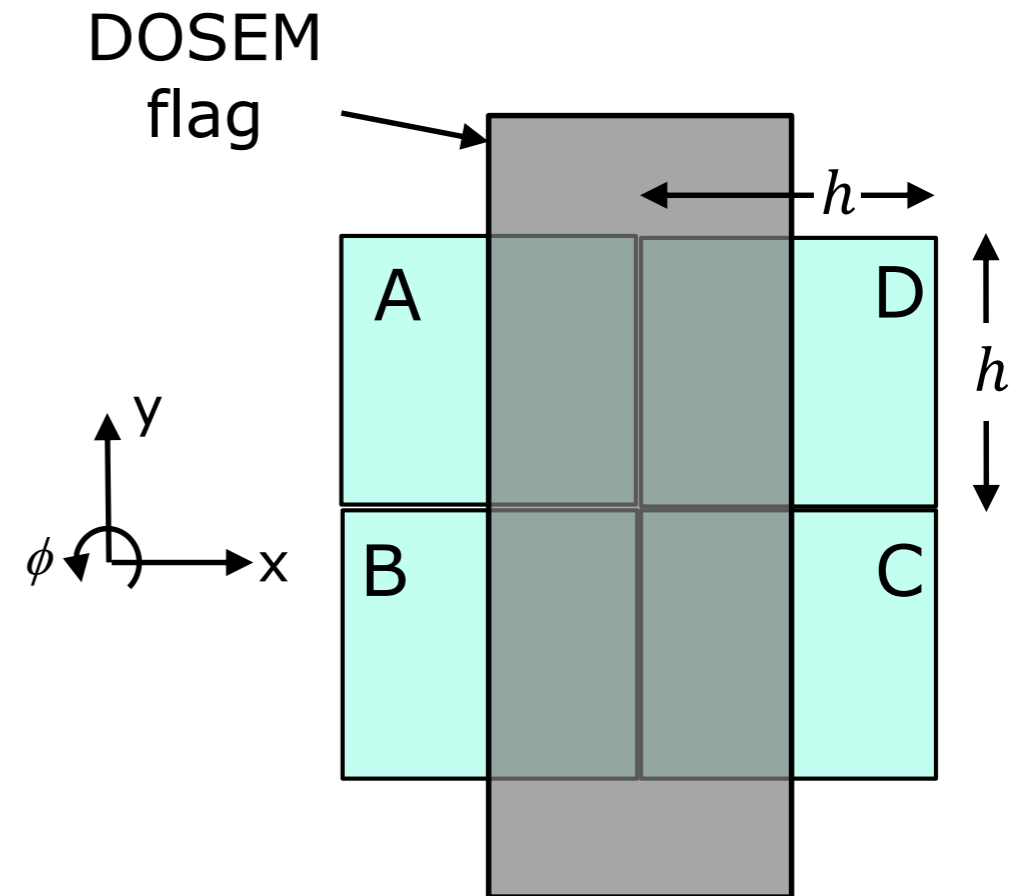
Basic idea behind DOSEM

- Replace BOSEM photodiode with a quadrant photodiode
- Replace BOSEM flag with one with a thin vertical plate
- Keep everything else the same
- **Advantages**
 - Increases sensitivity (could be 4x)
 - Eliminates some systematics via common mode rejection (more important)
 - Improved linearity
- **Disadvantages**
 - More complex flag (machined one at UF fairly easily)
 - Four vac feedthrough wires (2 + 2) → Seven wires (5 + 2)



(over)Simplified Sensor Model

- Output voltage for quadrant i
 - $V_i = g_i P_i(x) + b_i$
 - $g_i = \text{gain}$, $P_i(x) = \text{integrated power}$, $b_i = \text{bias}$
- For perfectly uniform light distribution, optimal flag width = $h + \text{gap}$ and
 - $P_i(x) = P_0 h \left(\frac{1}{2} h \pm x \right)$
- Then, can model output voltage as
 - $V_i = \pm A_i x + B_i$
- After calibration (fitting for A_i, B_i)
 - Construct $s_i = (V_i - B_i)/A_i$
 - $x = \frac{(s_A + s_B) - (s_C + s_D)}{s_A + s_B + s_C + s_D}$
- This combination insensitive to fluctuations in g_i, P_0, b_i



Emitter and Detector

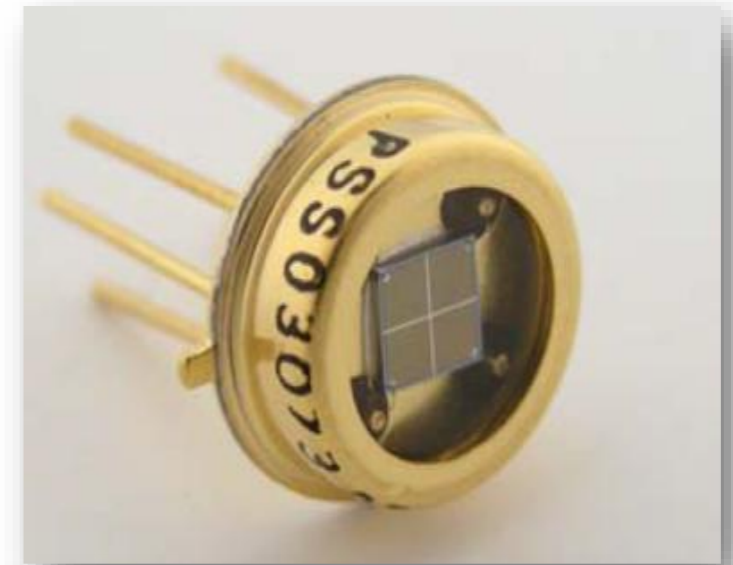
- **Quadrant photodiode: First Sensor GP5-6 TO**

	QPD GP5-5 TO (DOSEM)	BPX65 (BOSEM)
Active area side length	1.10 mm square + 0.024 mm gap	1.0 mm square
Responsivity @ 900nm	0.64 A/W	0.55 A/W
Dark current	0.2 nA	5 nA
Package (diam)	TO5 (8.1 mm)	TO-46 (4.7 mm)
Cost	\$35	cheap

- **LED emitter: OP232 (same as BOSEM)**

- TO-46 can
- Max forward current 100 mA (35 nominal)

- **Procured and testing alternate LEDs: OPT132**



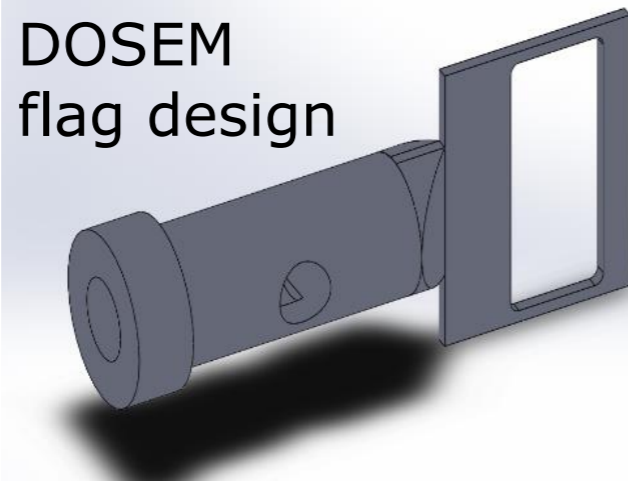
BOSEM LED (left), PD (right)
[SM Aston 2011]

DOSEM Sensor Testbed

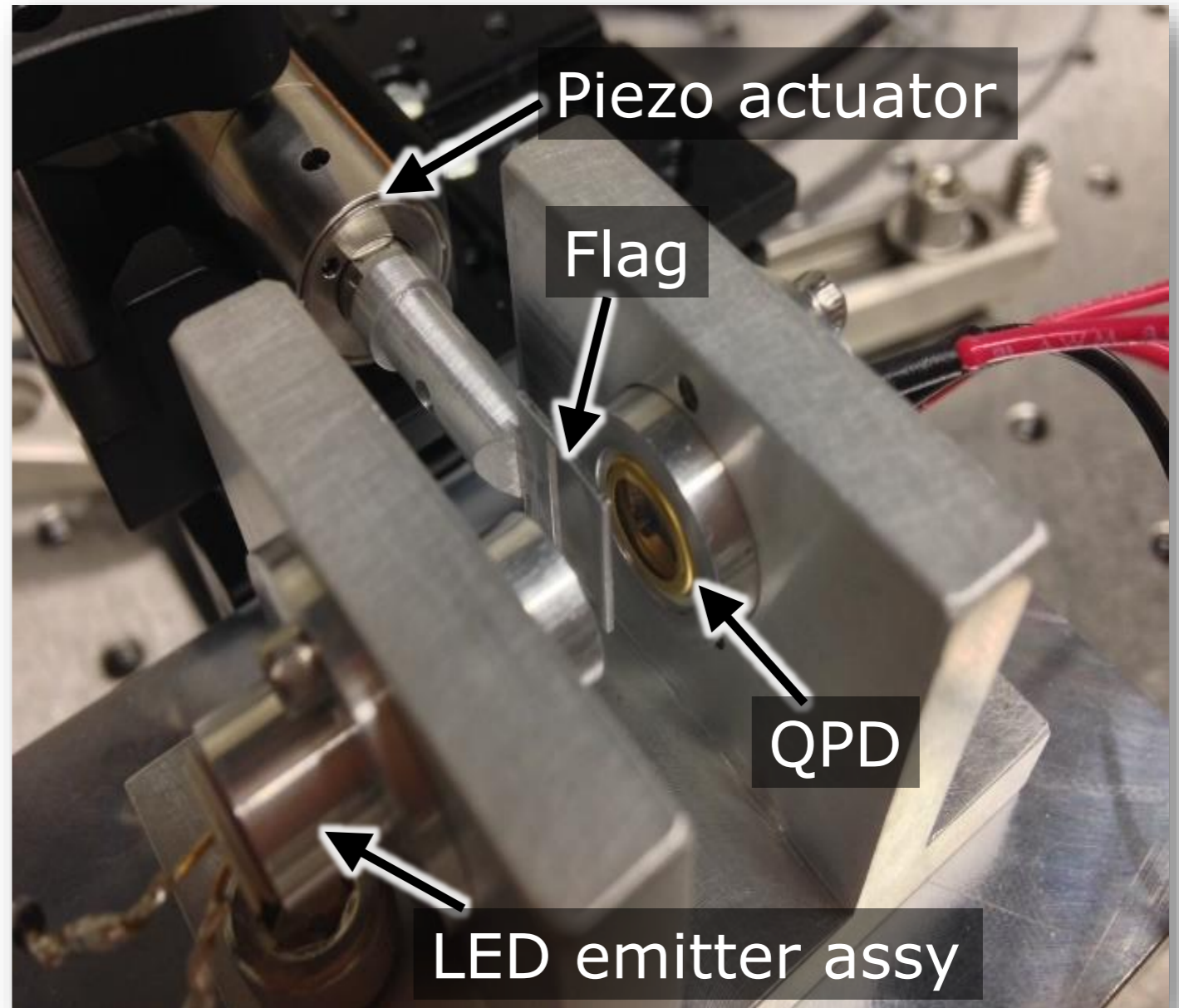
BOSEM
flag



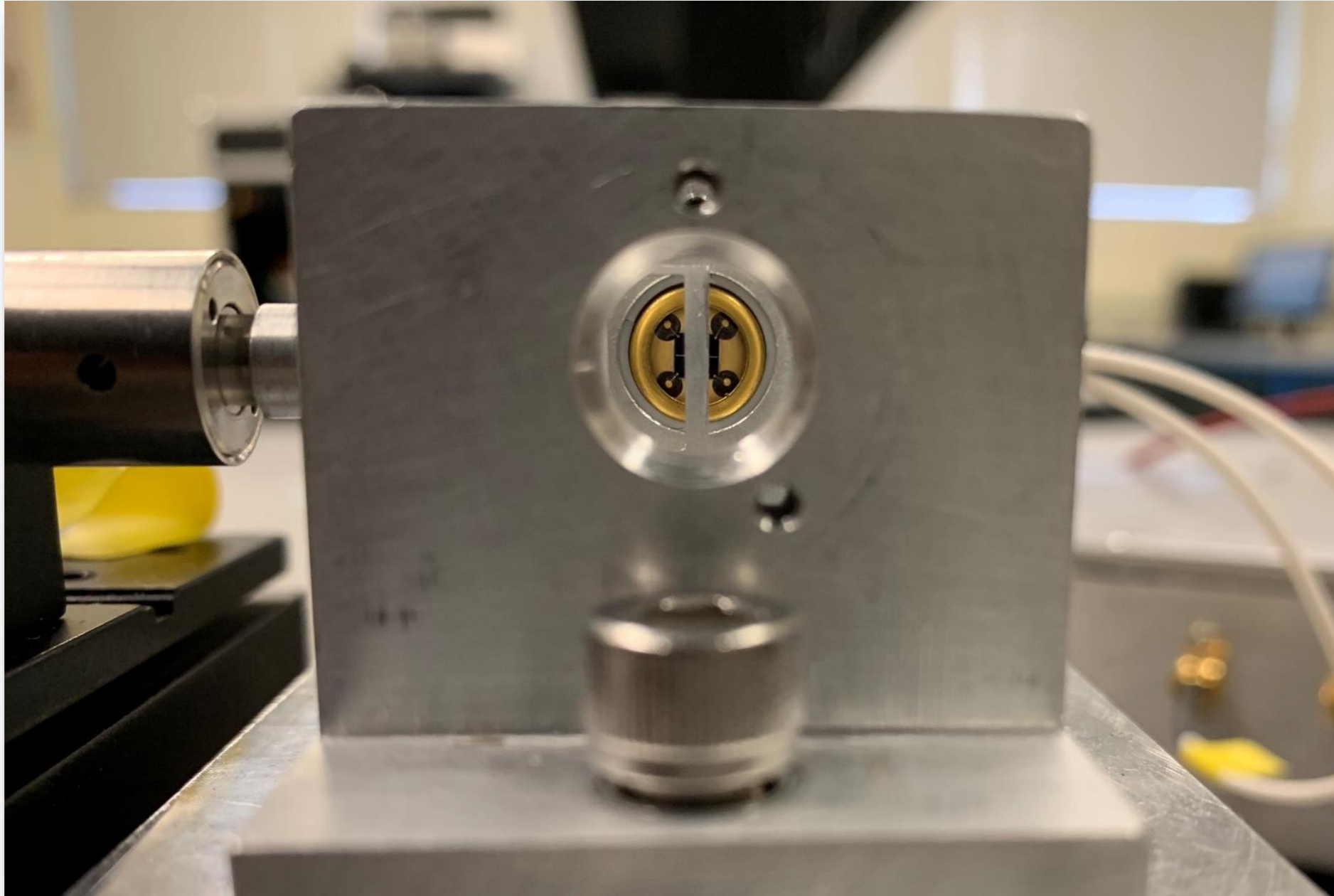
DOSEM
flag design



- **Mount side of flag same as BOSEM**
 - Mounted to piezo stage on top of 3-axis micrometer stage
- **Aluminum mount holds LED & QPD with spacing equal to that of BOSEM**
- **LED holder same as BOSEM**
- **QPD holder is modified BOSEM design (larger diameter)**

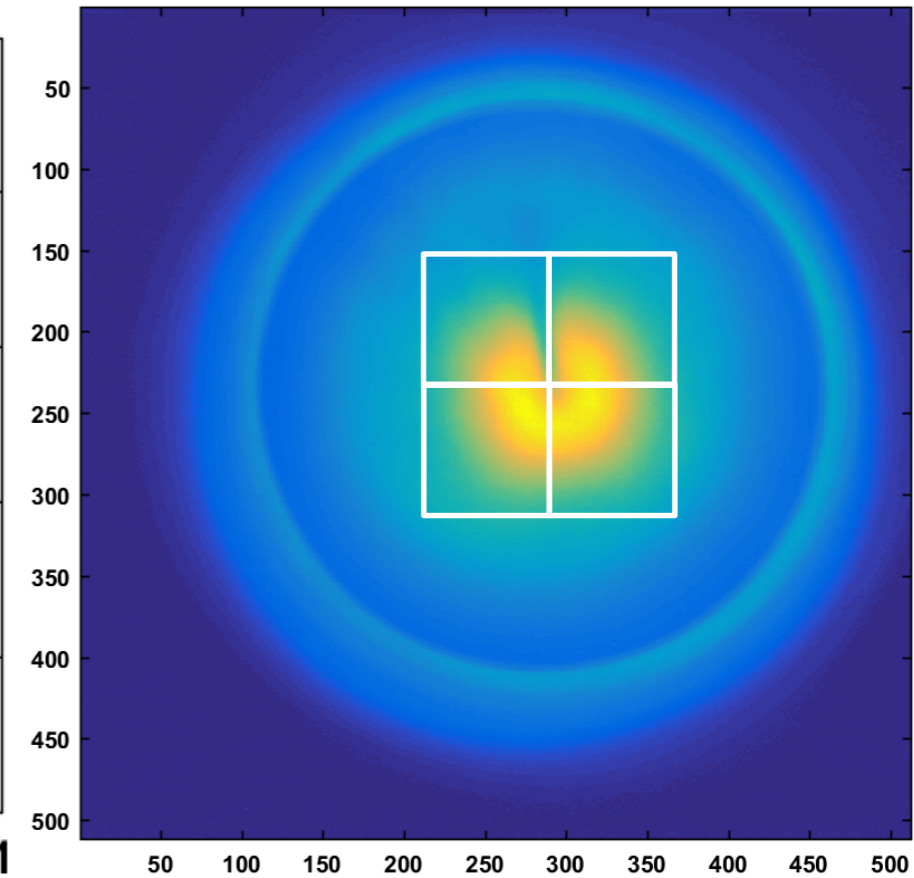
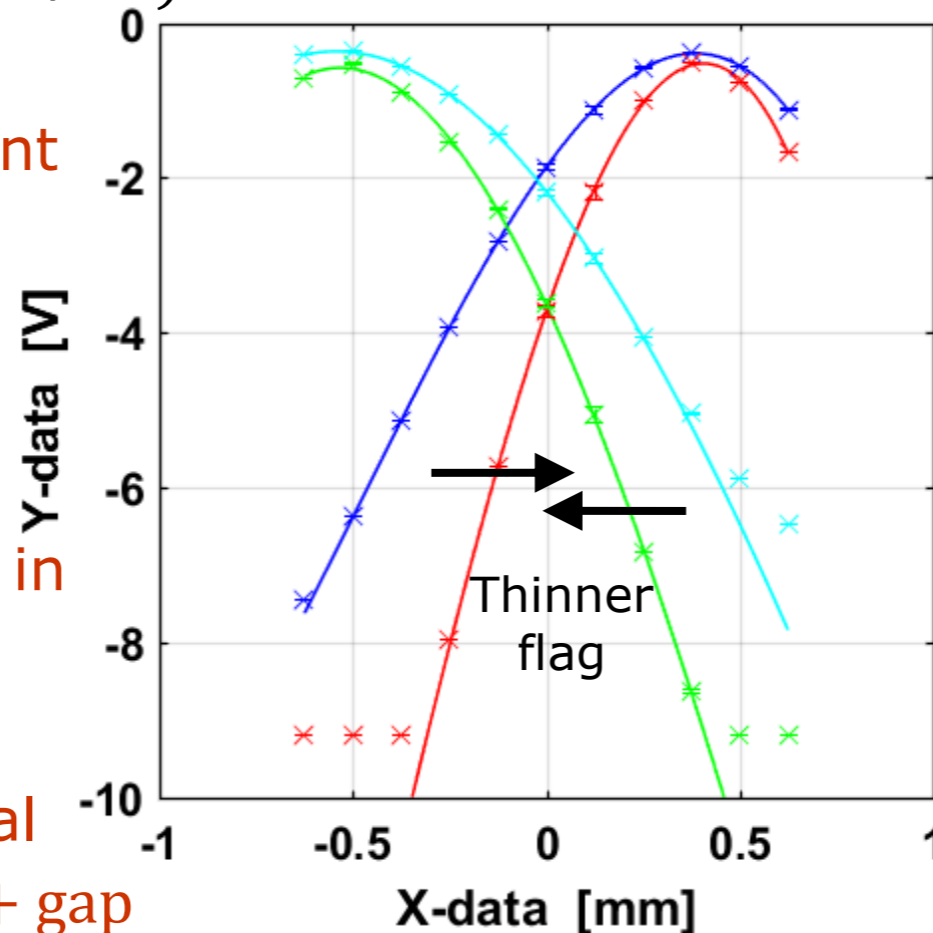


View from LED



Dealing with Non-uniform Light Distribution

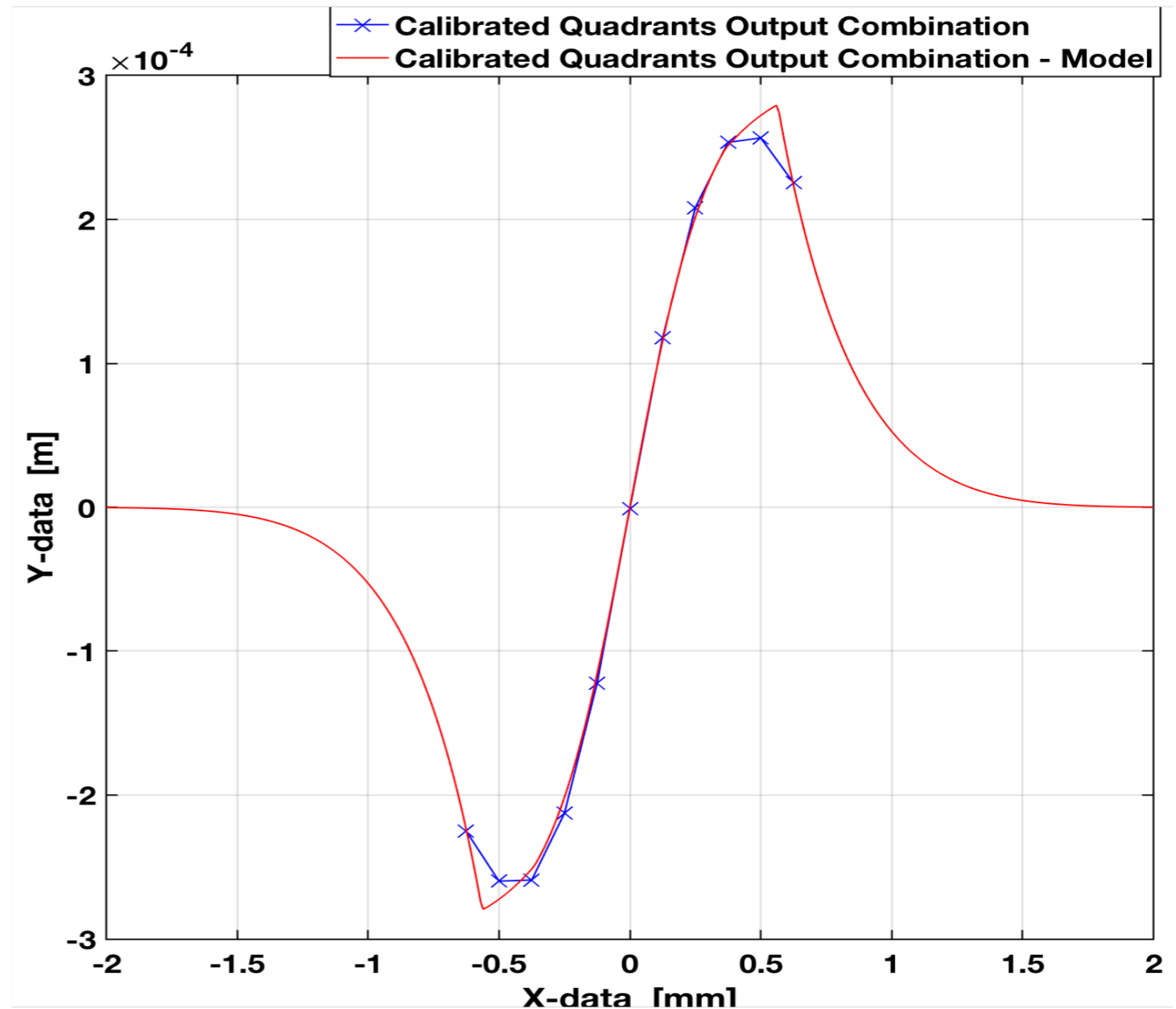
- LED power on QPD is non-uniform, leads to polynomial model for integrated power
 - $P_i(x) = P_0(a_0 + a_1x + a_1x^2 + \dots)$
- Calibration involves fitting polynomials for each quadrant
- x channel combination still insensitive fluctuations in
 - LED power, PD gain & bias
 - Axisymmetric LED distribution
- Still sensitive to fluctuations in
 - Right-left beam deflection
 - Right-left asymmetric dist.
- For \sim Gaussian beam, optimal flag width is thinner than $h + \text{gap}$



Beam profile with QPD overlay (approx)

Modeled x Channel Signal

- Differential signal naturally reduces nonlinearity
 - Nonlinearity could be removed in digital output
- Linear range: $\sim \pm 0.4$ mm
- Equivalent sensitivity $\sim 80\text{kV/m}$ (calibrated combined signal is unitless)



Three output channels

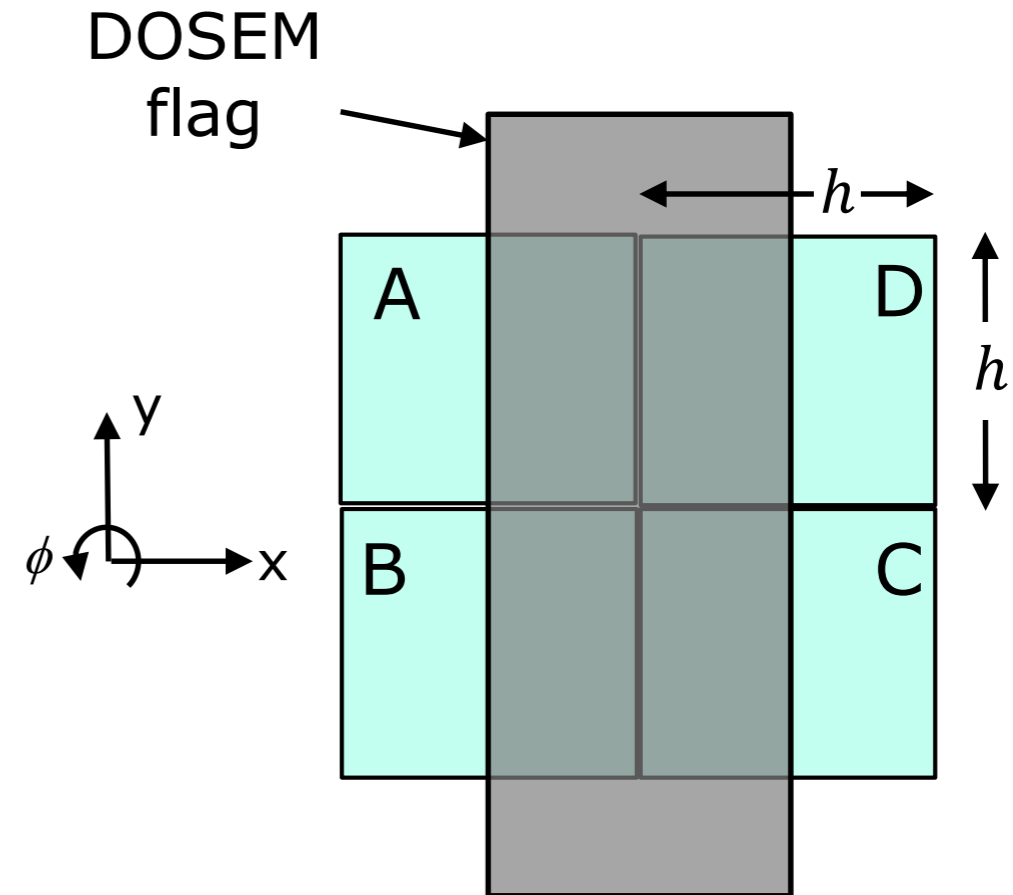
- Calibrated quadrant outputs can be combined to produce three channels

- $x = \frac{(s_A + s_B) - (s_C + s_D)}{s_A + s_B + s_C + s_D}$

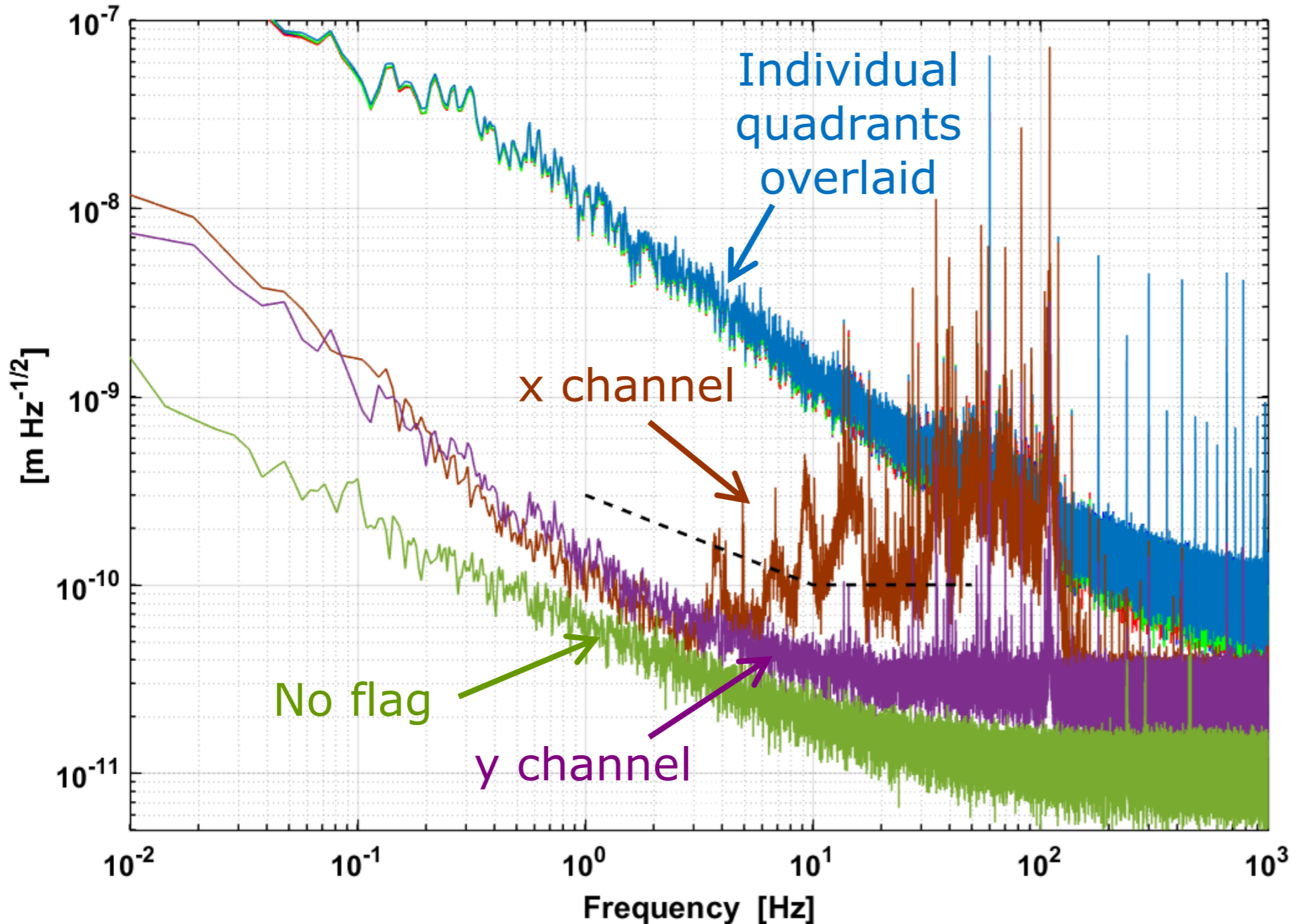
- $y = \frac{(s_B + s_C) - (s_A + s_D)}{s_A + s_B + s_C + s_D}$

- $\phi = \frac{(s_B + s_D) - (s_A + s_C)}{s_A + s_B + s_C + s_D}$

- y and ϕ channels are useful for:
 - Noise characterization
 - Alignment



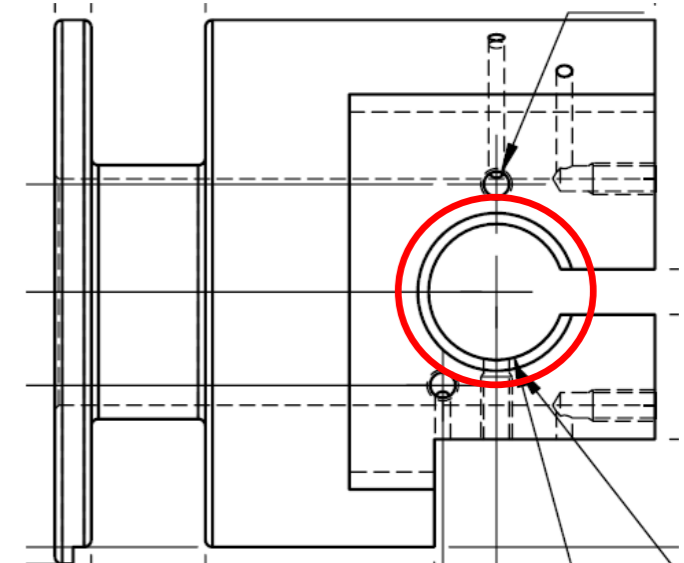
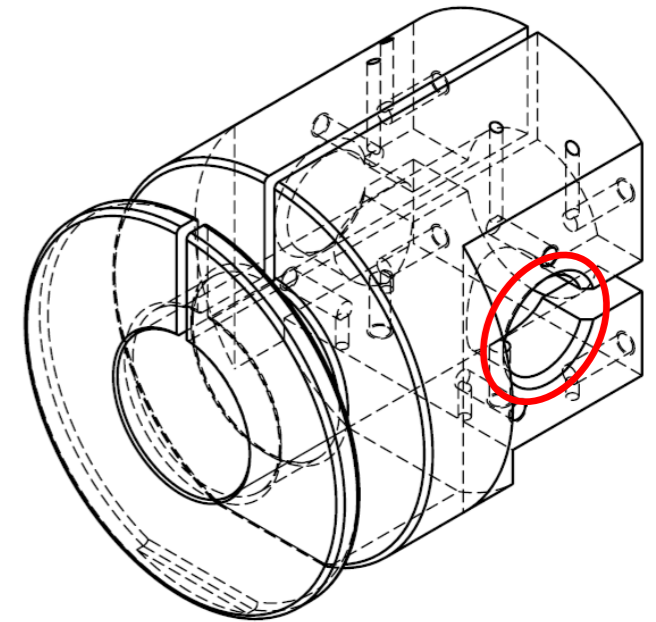
Early Results



- **Single quad sensitivity**
 $\sim 1 \text{ nm}/\text{Hz}^{1/2}$ @ 10 Hz
(10x worse than BOSEM)
- **Combined sensitivity**
 $\sim 40 \text{ pm}/\text{Hz}^{1/2}$ @ 10 Hz
 $\sim 150 \text{ pm}/\text{Hz}^{1/2}$ @ 10 Hz
- **Common mode rejection**
 $\sim 30x$ @ 10 Hz
- **X channel signal**
(3 Hz to 100 Hz) above y channel is likely flag motion
- **Shot noise appears to be limit** above few Hz

Future Prospects

- **Pathways to increase sensitivity:**
 - Optimize flag width (reduce by ~ 0.2 mm)
→ $\sim 2x$ increase in sensitivity (based on calibration slope)
 - Minimize vibration, air currents → vac chamber + vibe isolation
 - Improve analog electronics: Protoboard → PCB
 - Optimize light distribution on QPD: LED current, optics
- **Work in progress:**
 - Moving testbed to vacuum chamber (ion pump) on vibration isolation table (old LIGO HAM table)
- **Future Work**
 - Examine impact on BOSEM design; both for the sensor head, and analog/digital electronics
 - Seek out SWG interest, advice in DOSEM development
- **Happy to evaluate alternate LEDs as part of this project**





I arrive at LVC meeting in Wisconsin tomorrow night,
depart Thursday afternoon

Happy to discuss further! – J.W. Conklin