



Continuous Gravitational Waves

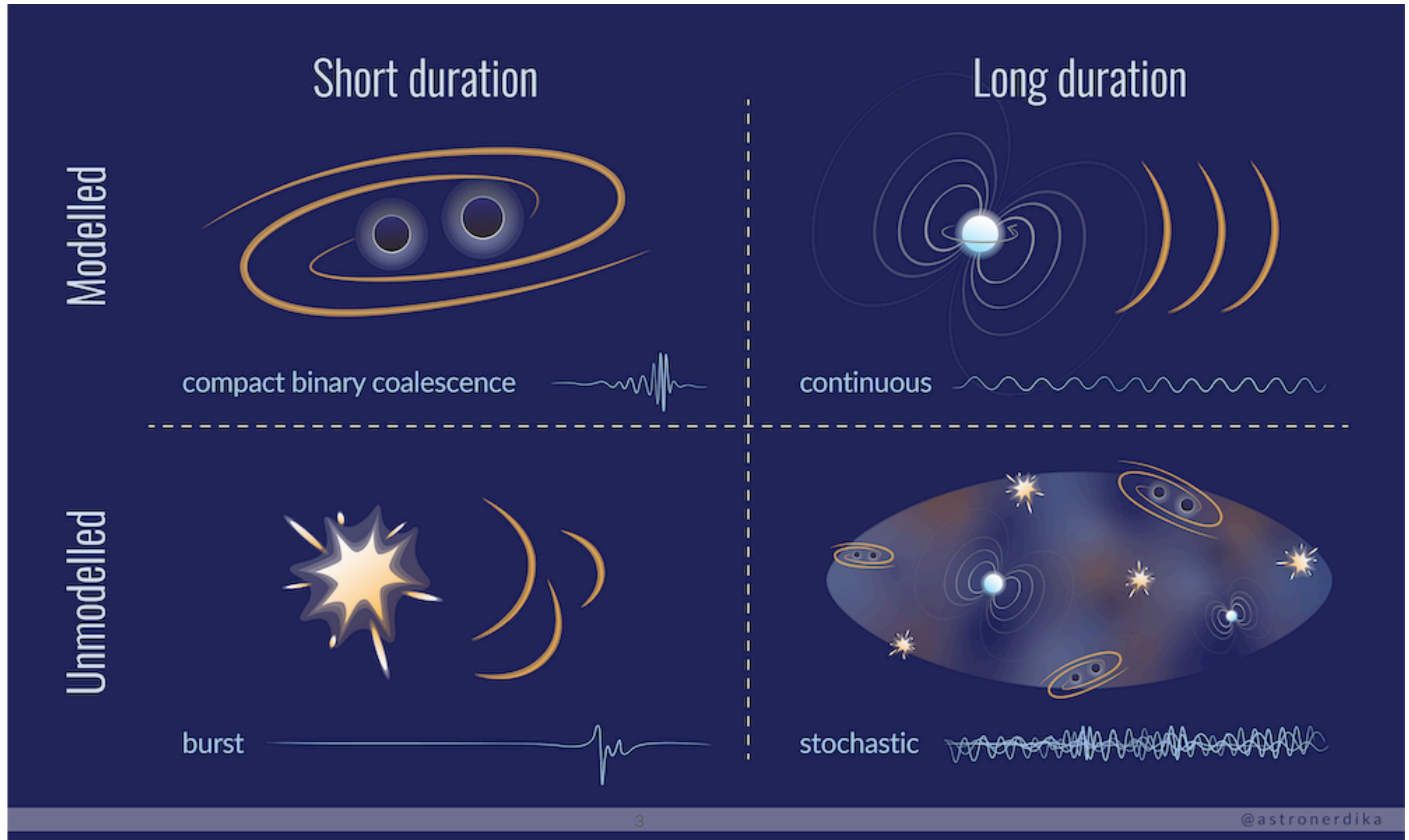
Takahiro S. Yamamoto (RESCEU U. Tokyo, Japan)



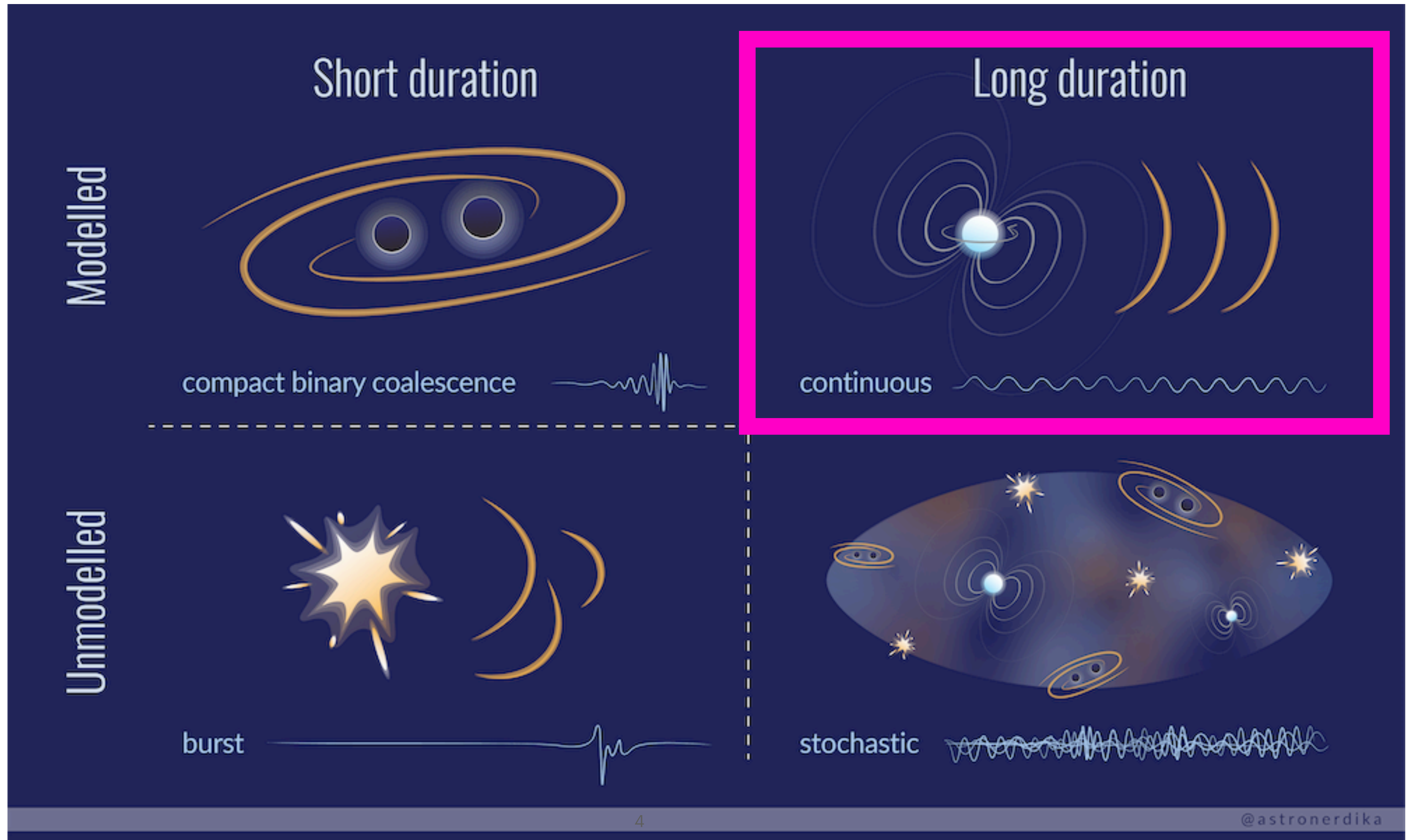
GW Open Data Workshop #7, April 18-20, 2024 @ Taichung, Taiwan

Introduction

Various types of GWs

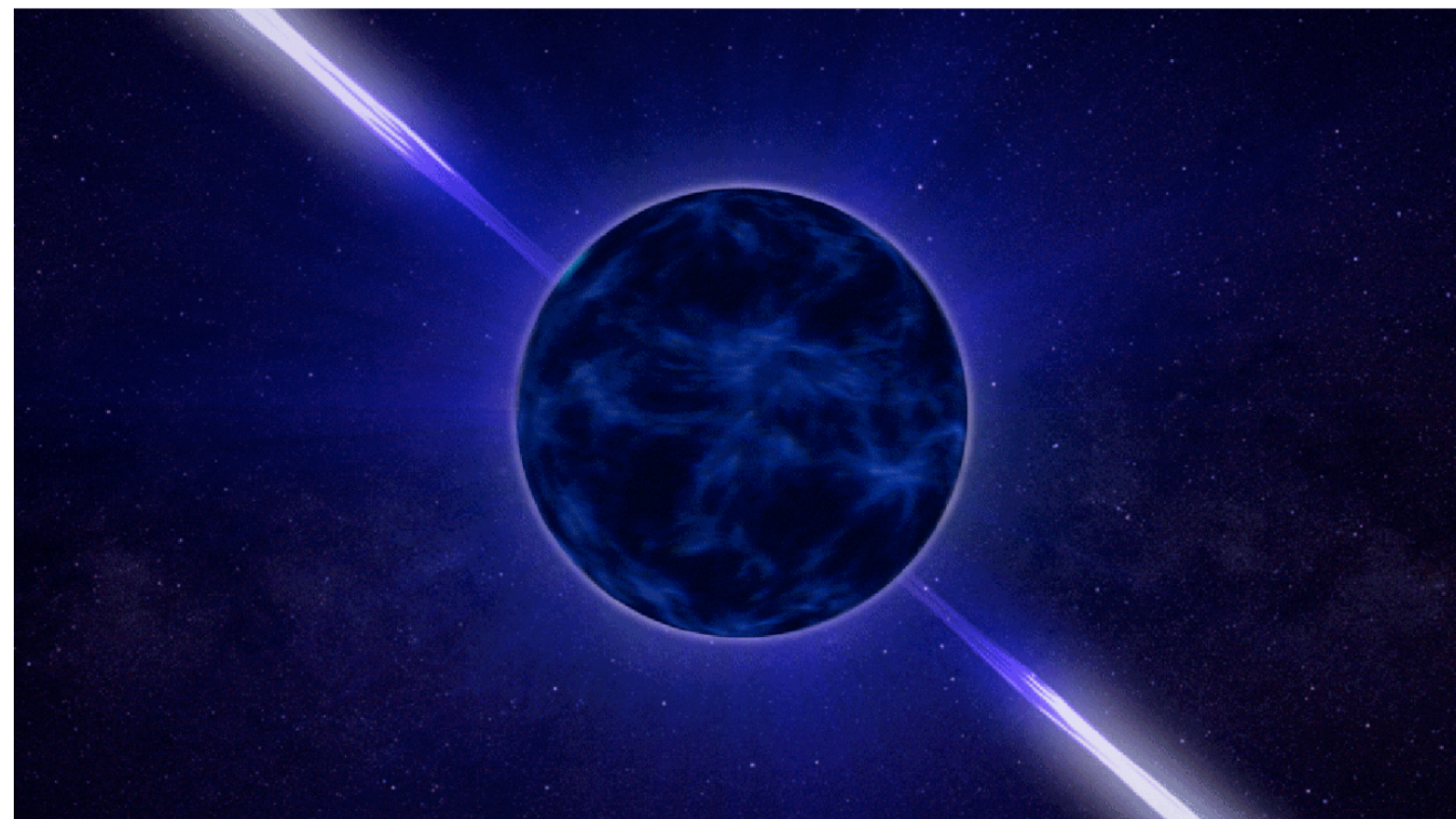


Various types of GWs



Sources of CGWs for ground based detectors

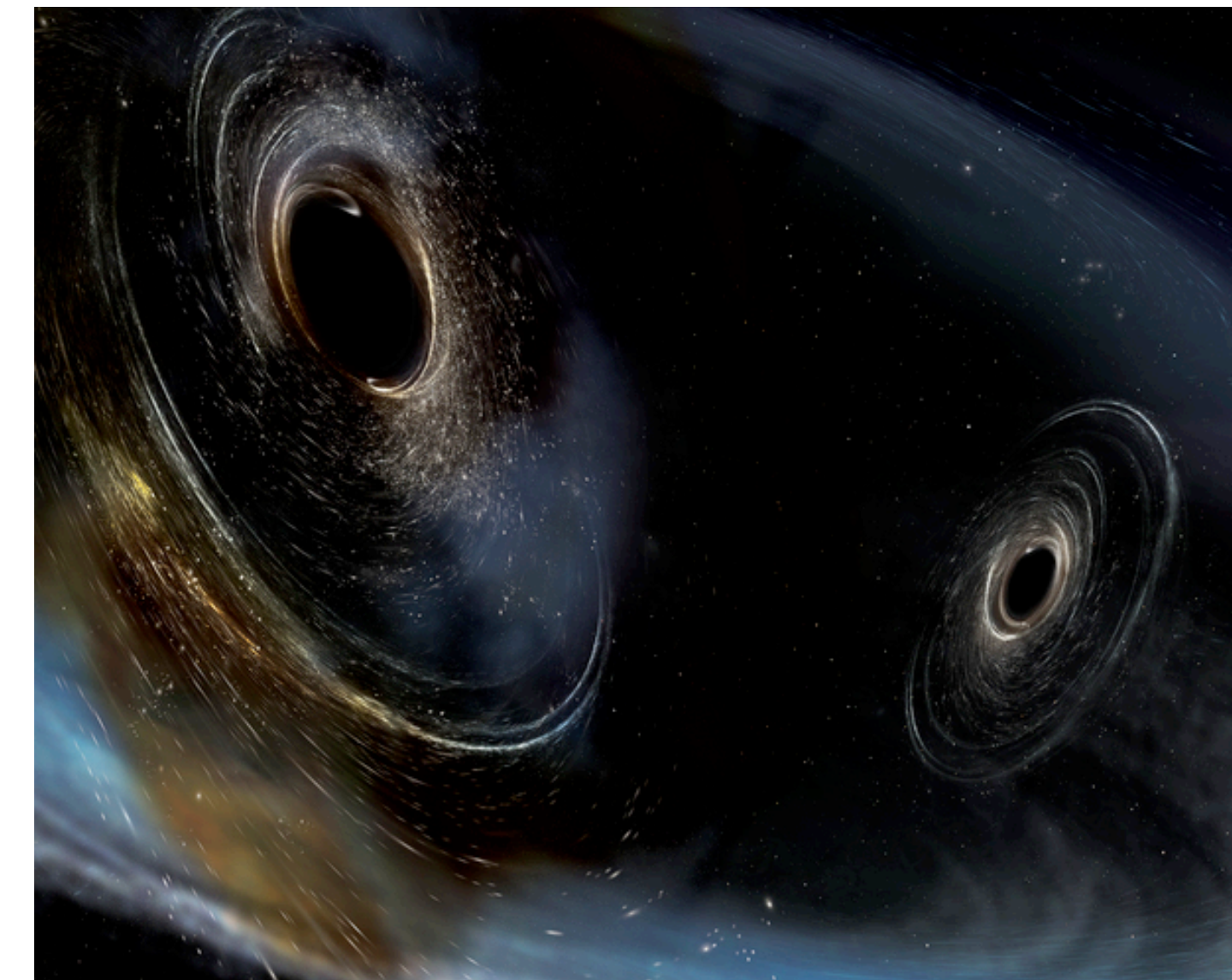
Rotating, distorted neutron stars
(pulsars)



An artist's impression of a pulsar/neutron star.
Credits: NASA's Goddard Space Flight Center

→ **Astrophysics,
nuclear physics**

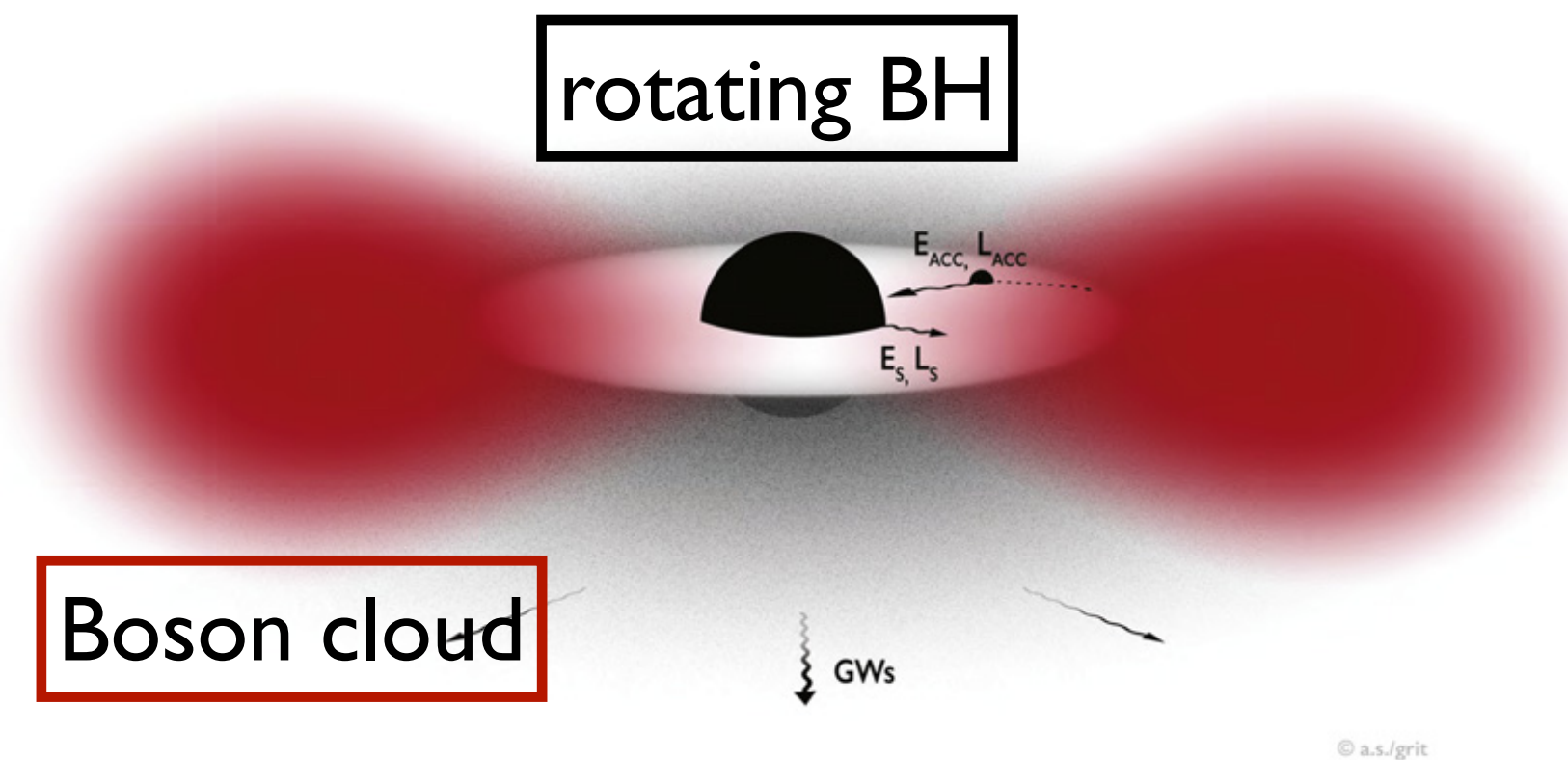
Planetary mass primordial BHs
(cosmological origin)



Sasaki *et al.*, *Class. Quantum Grav.* 35, 063001 (2018)
as a review of PBH

→ **Cosmology**

Boson cloud around rotating BHs



Arvanitaki *et al.*, *PRD* 81, 123530 (2010)
Brito *et al.*, *Class. Quantum Grav.* 32, 134001 (2015)

→ **Particle physics**

Continuous gravitational waves (CGWs)

- **Persistent, quasi-monochromatic** signals
- Amplitude is **very weak**.

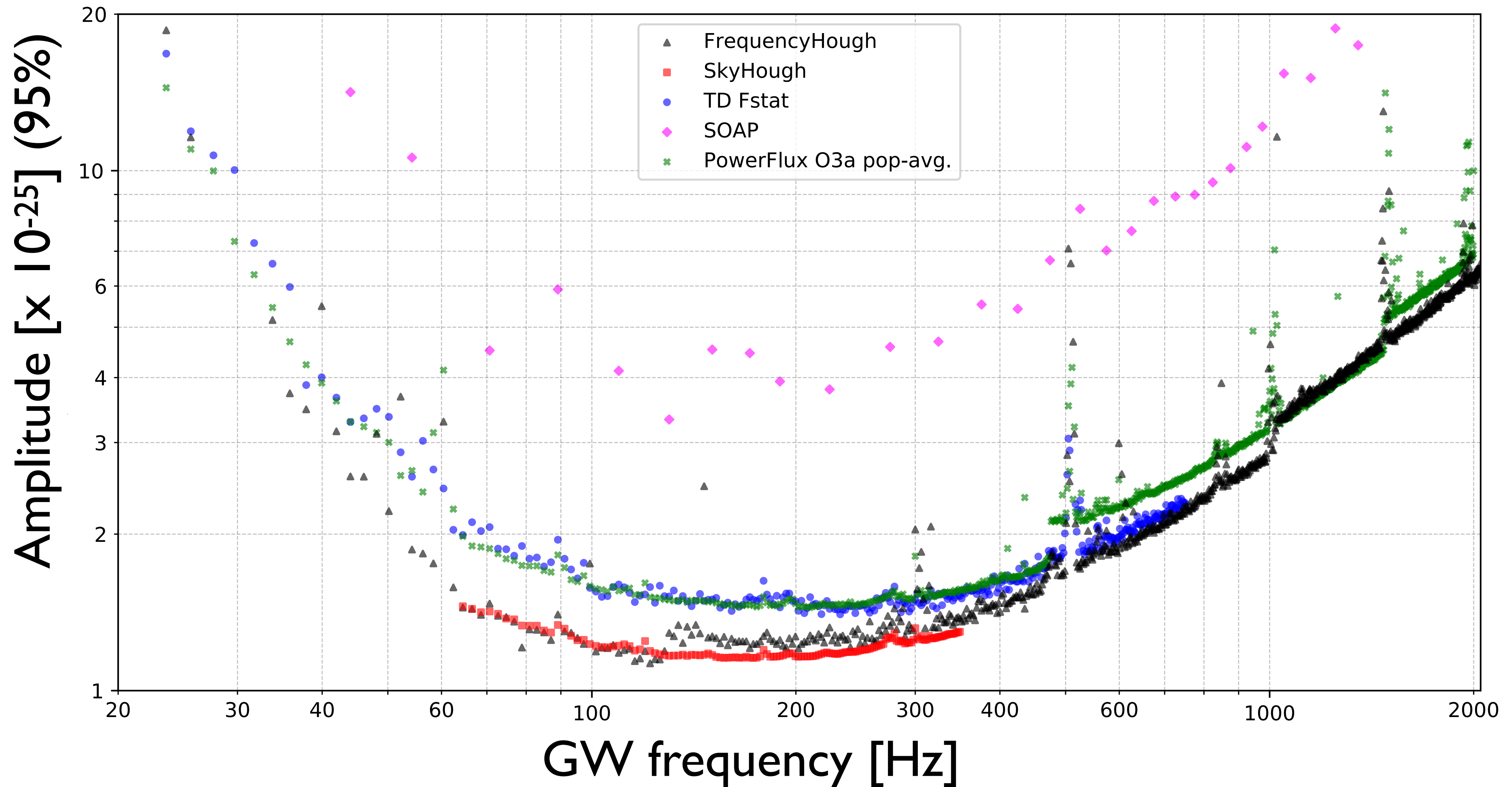
- e.g. spinning deformed NS
$$h_0 = \frac{4\pi^2 G}{c^4} \frac{I_3 f_{GW}^2 \epsilon}{d} = 4.2 \times 10^{-26} \left(\frac{\epsilon}{10^{-6}} \right) \left(\frac{P}{10 \text{ ms}} \right)^{-2} \left(\frac{d}{1 \text{ kpc}} \right)^{-1}$$

ϵ : ellipticity, P : pulse period, d : distance

- We need to accumulate O(yr)-long strain data to detect CGWs.
- We have not detected CGWs yet.

Constraint from LIGO-Virgo O3 data

Fig. LVK collaboration, arXiv:2201.00697



Waveform model of CGWs

in source frame

τ : time when wavefront reaches at SSB (solar system barycenter)

Two polarizaion of GWs $h_+(\tau) = h_0 \cos[\Phi(\tau) + \Phi_0], h_\times(\tau) = h_0 \sin[\Phi(\tau) + \Phi_0]$

Phase of GWs
$$\Phi(\tau) = 2\pi \sum_{k=0}^s \frac{f^{(k)}}{(k+1)!} (\tau - \tau_{\text{ref}})^{k+1}$$

Frequency parameters $f^{(k)} := \frac{d^k f}{d\tau^k}$

At emission, the model of CGWs is simpler than those of CBCs.

Detector motion makes it complicated.

Waveform model of CGWs

in detector frame

1. Inclination angle

Amplitudes of +, x modes $h_+ \rightarrow h_0 \frac{1 + \cos^2 \iota}{2}, h_\times \rightarrow h_0 \cos \iota$

2. Detector's antenna patterns

$$F_+(t; \alpha, \delta, \psi) = \sin \zeta [a(t; \alpha, \delta) \cos(2\psi) + b(t; \alpha, \delta) \sin(2\psi)] \quad \psi : \text{polarization}$$
$$F_\times(t; \alpha, \delta, \psi) = \sin \zeta [b(t; \alpha, \delta) \cos(2\psi) - a(t; \alpha, \delta) \sin(2\psi)] \quad \zeta : \text{Angle btw arms, } \pi / 2 \text{ for LVK}$$

3. Doppler modulation due to the detector motion

$$\tau = t - \frac{\mathbf{r}(t) \cdot \mathbf{n}(\alpha, \delta)}{c}$$

τ : SSB time, t : detector time

$\mathbf{r}(t)$: detector location with respect to SSB

$\mathbf{n}(\alpha, \delta)$: unit vector pointing from SSB to the source

What we will observe is

$$h(t) = F_+(t; \alpha, \delta, \psi) h_0 \frac{1 + \cos^2 \iota}{2} \cos [\Phi(t) + \Phi_0] + F_\times(t; \alpha, \delta, \psi) h_0 \cos \iota \sin [\Phi(t) + \Phi_0]$$

Frequency modulation

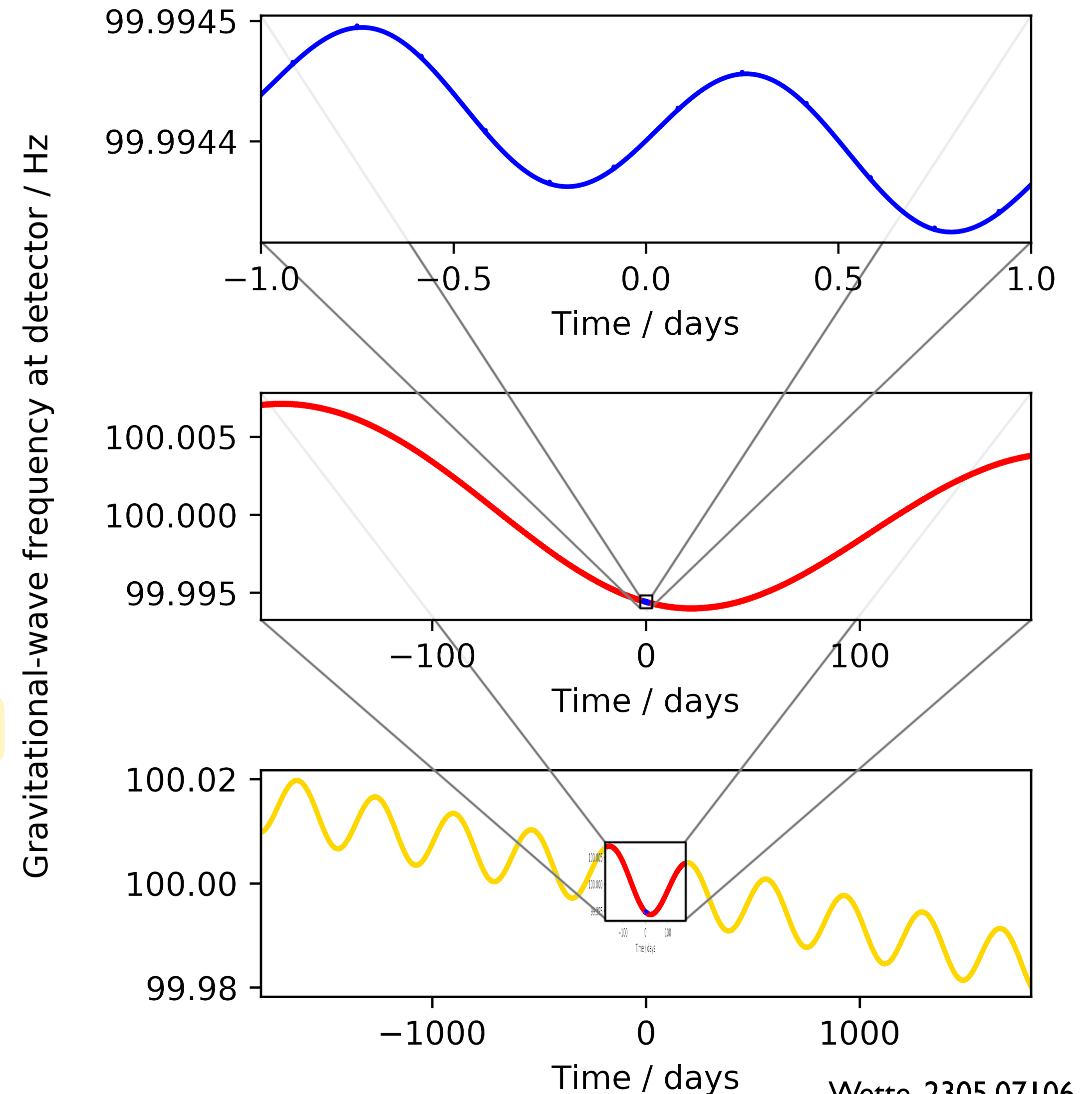
$$\Phi(\tau) = 2\pi \sum_{k=0}^s \frac{f^{(k)}}{(k+1)!} (\tau - \tau_{\text{ref}})^{k+1}$$

$$\tau = t - \frac{\mathbf{r}(t) \cdot \mathbf{n}(\alpha, \delta)}{c}$$

$$f(t) = \frac{1}{2\pi} \frac{d\Phi}{dt}$$

$$\sim (f^{(0)} + f^{(1)}t + \dots) \times \left(1 + \frac{\mathbf{r}(t) \cdot \mathbf{n}}{c}\right)$$

\sim daily oscillation + yearly oscillation + intrinsic evolution



Difficulties in CGW searches

- **Non-Gaussian detector noise**

There are two types of non-Gaussian detector noise; glitches and lines. They can affect the sensitivity by increasing the false-alarm rate and elevating the noise PSD.

- **Computational cost**

Due to the long duration and the detector motion, CGW searches are quite sensitive to the small difference in the signal parameters. It leads to heavy computational cost.

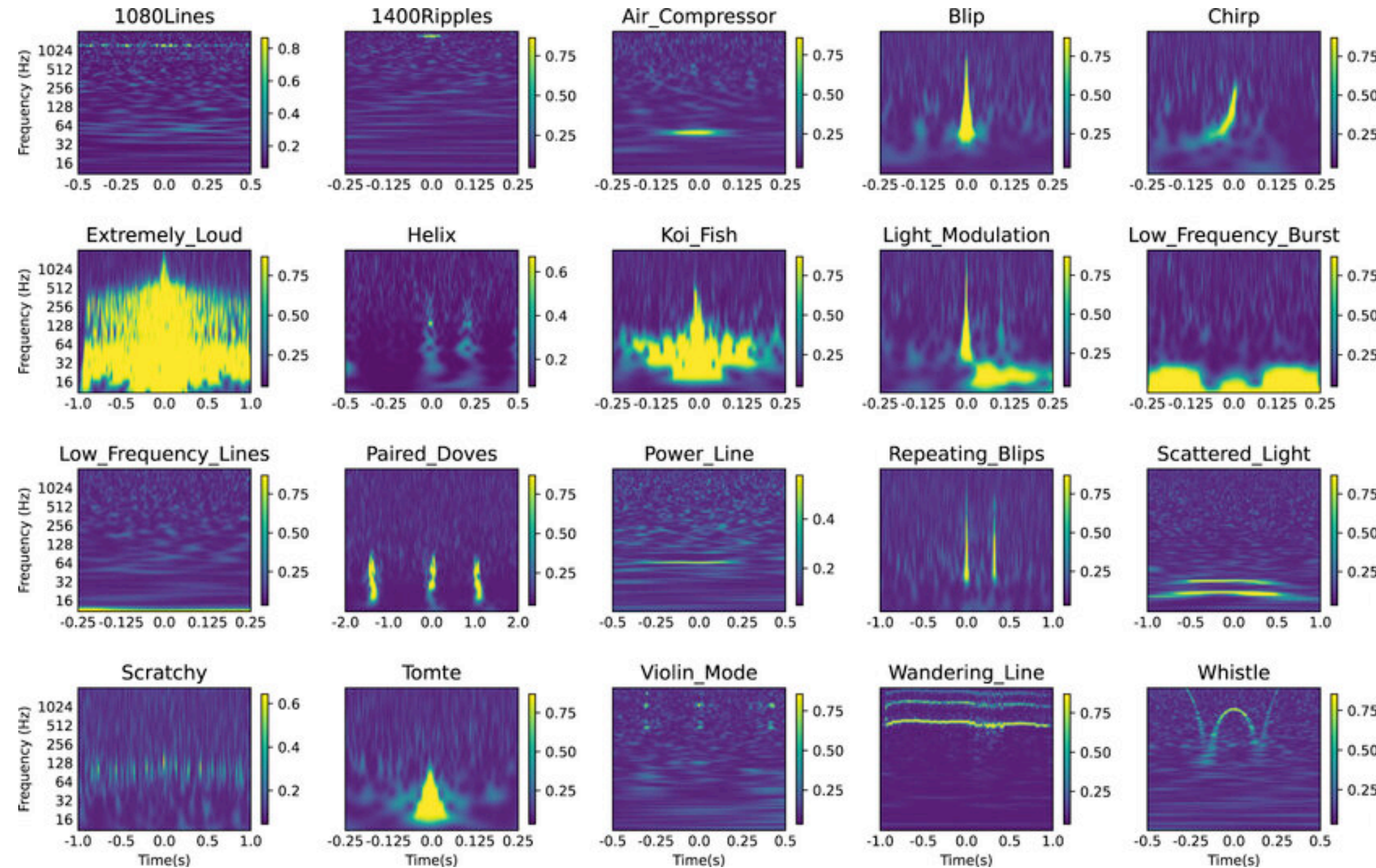
Glitches

Glitches

= burst-like disturbances

Unlike CBC searches, glitches cannot be the sources of confusion with CGWs.

But, it affects the estimation of PSD by increasing noise floor.



Instrumental lines

Instrumental lines

= narrow band, persistent artifacts

Sources:

- 60Hz power line harmonics,
- Violin modes of suspension
- Environmental disturbances, etc...

Instrumental lines can degrade the CW search sensitivity because they share the similar features with CGWs leading the increase of the false-alarm rate. Also, lines much affect on the PSD estimation.

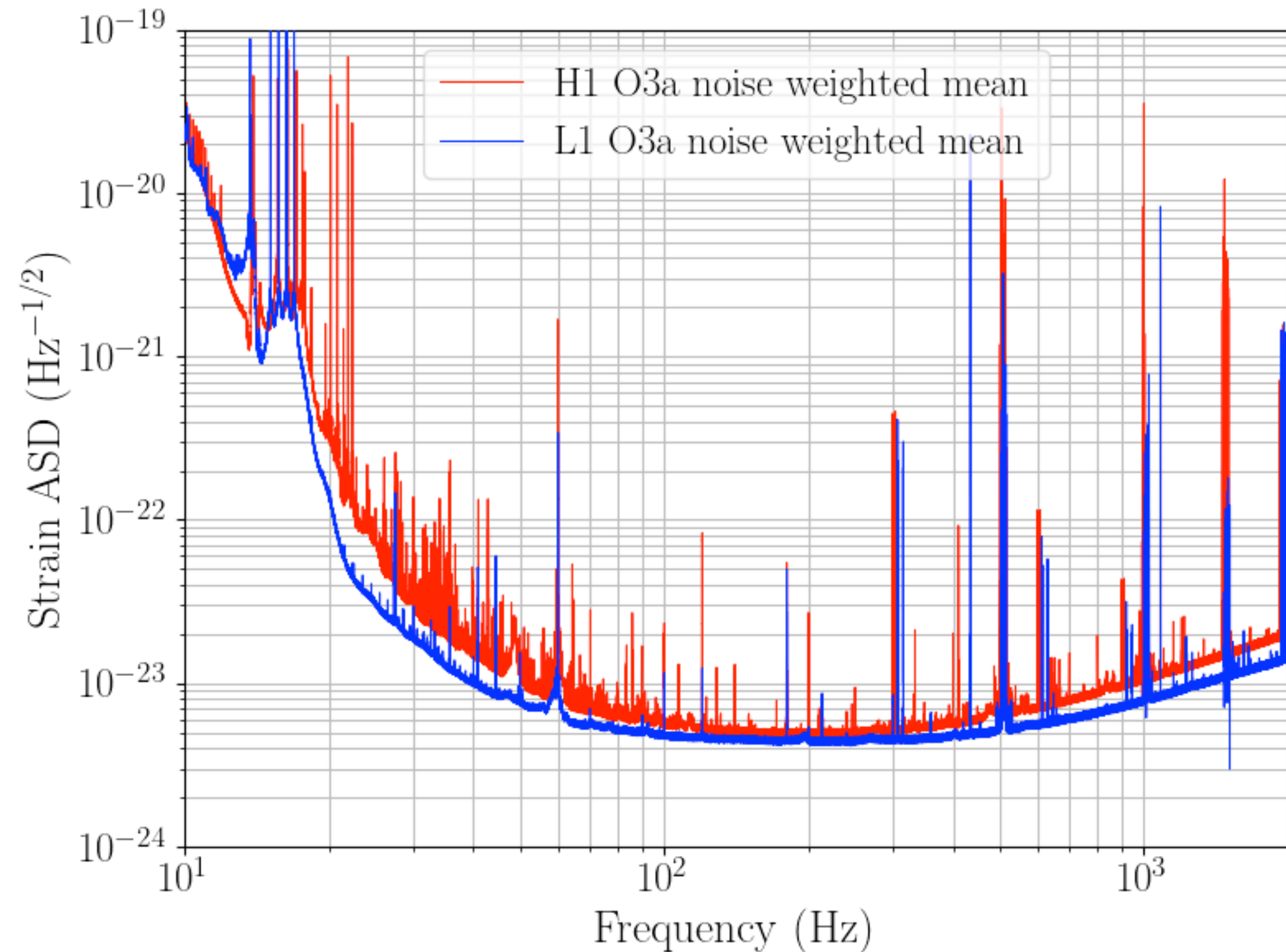


Fig: <https://gwosc.org/O3/o3speclines/>

T_{obs} dependency of computational cost

Idea: **difference in frequency should be smaller than $(T_{\text{obs}})^{-1}$**

Resolutions $\Delta f^{(0)} \sim T_{\text{obs}}^{-1}$ $\Delta\alpha \sim \Delta\delta \sim \left(f^{(0)} \frac{v}{c}\right)^{-1} \cdot T_{\text{obs}}^{-1}$

$$\Delta f^{(1)} \sim T_{\text{obs}}^{-2}$$

$$\text{Doppler modulation} \simeq f^{(0)} \frac{v \cdot n}{c}$$

$$\text{Small deviation} \sim f^{(0)} \frac{v}{c} \Delta\alpha \lesssim T_{\text{obs}}^{-1}$$

Volume of the parameter space each grid covers $\Delta V_{\text{grid}} \sim (T_{\text{obs}})^{-5}$

Computational cost \sim (# of grids) \times (comp. cost per grid) $\sim (T_{\text{obs}})^6$

Long observational time leads to the rapid increase of the computational cost.

Semi-coherent searches

- Coherently processing entire observational data is not feasible. So, we divide it into short segments, process each segment coherently, and integrate them.
Typically, $T_{\text{coh}} = 1800$ sec. But, it can be longer.
- The sensitivity is degraded comparing with the fully-coherent search. But, with the computational resource limitation, semi-coherent searches show better sensitivity than the coherent searches.
- Each algorithm returns candidates which satisfies the criteria and is followed by the follow-up search to confirm whether the candidates are astrophysical signals or detector artifacts.

Various types of CGW search

- The more knowledge we have, the better sensitivity & the more efficient the search is.
- **Blind (all-sky) searches** are the most expensive task in GW astronomy.
- In this talk, we focus all-sky searches.

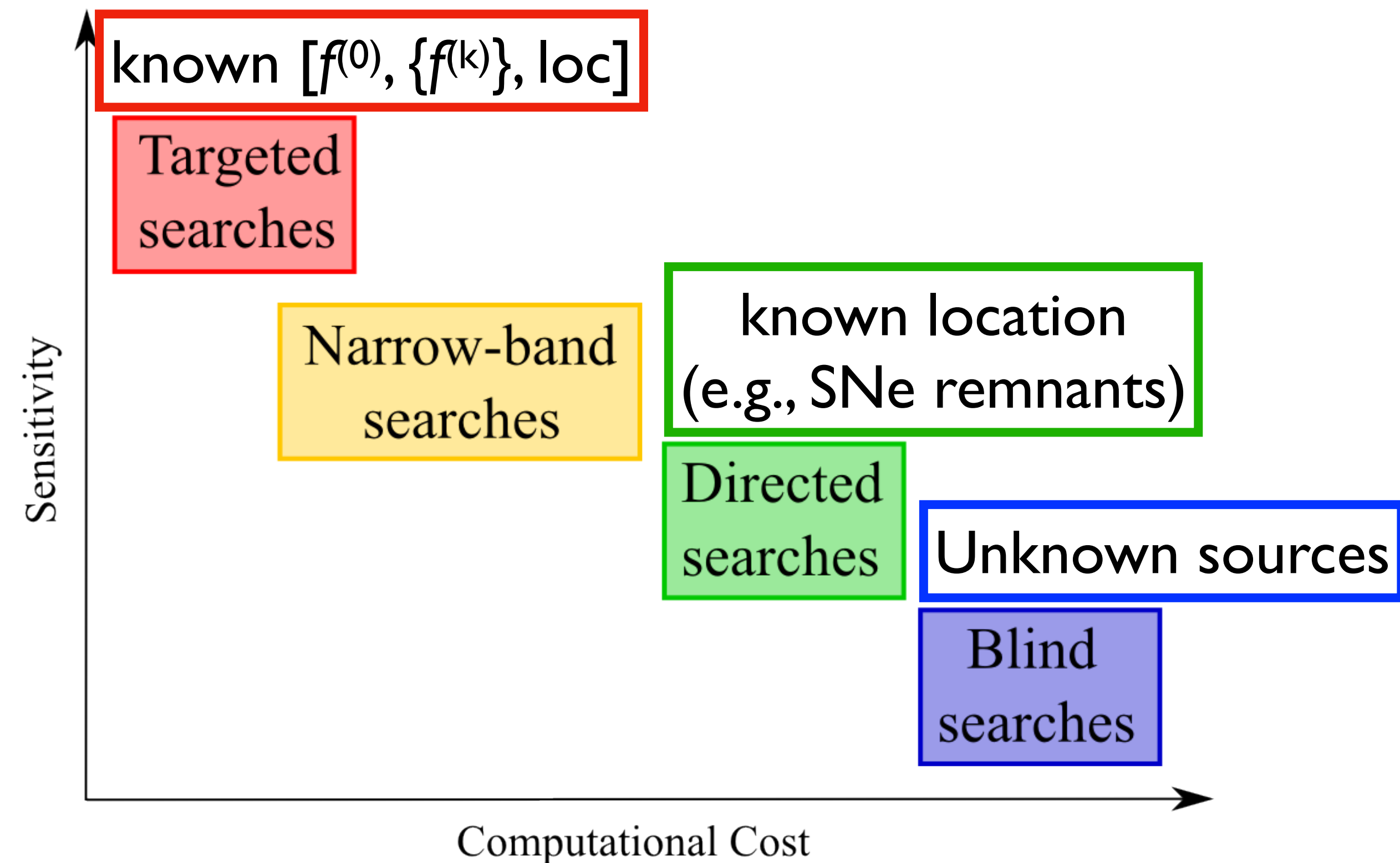


Fig. Sieniawska & Bejger, Universe 5(11), 217 (2019) [modified]

Search pipelines employed in O3 all-sky searches

LVK collaboration, arXiv:2201.00697

- **Time-domain F-statistic**

Maximum likelihood based approach.

- **Frequency Hough, sky Hough**

Hough transform. Frequency Hough makes Hough map in $(f^{(0)}, f^{(1)})$ plane while sky Hough makes it in (α, δ) plane.

- **PowerFlux**

Adding SFT powers normalized by noise PSD and antenna pattern functions.

- **SOAP-CNN**

Combining Viterbi algorithm, machine learning technique to find the likely frequency track, and a convolutional neural network.

Search pipelines employed in O3 all-sky searches

- **Time-domain F-statistic**

Maximum likelihood based approach.

Hands-on

- **Frequency Hough, sky Hough**

Hough transform. Frequency Hough makes Hough map in $(f^{(0)}, f^{(1)})$ plane while sky Hough makes it in (α, δ) plane.

- **PowerFlux**

Adding SFT powers normalized by noise PSD and antenna pattern functions.

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Combining Viterbi algorithm, machine learning technique to find the likely frequency track, and a convolutional neural network.

F-statistic

reference

Jaranowski, Królak, and Schutz, Phys.Rev.D58, 063001 (1998)

Matched filter

Notation $s(t)$: strain data, $h(t)$: GW waveform, $n(t)$: detector noise

Assumption: detector noise is stationary and Gaussian with zero mean

Likelihood of $s(t)$ $P(s|0) \propto \exp \left[-\frac{1}{2} (s|s) \right]$ In the absence of signal

$P(s|h) \propto \exp \left[-\frac{1}{2} (s-h|s-h) \right]$ In the presence of signal

noise-weighted inner product

$$(a|b) = 2 \int_{-\infty}^{\infty} df \frac{\tilde{a}(f)\tilde{b}^*(f)}{S_n(f)}$$

Log likelihood ratio

$$\ln \Lambda = \ln \frac{P(s|h)}{P(s|0)} = (s|h) - \frac{1}{2} (h|h)$$

noise power spectral density (PSD)

$$\langle \tilde{n}(f)\tilde{n}^*(f') \rangle = \frac{1}{2} S_n(f)\delta(f-f')$$

Rewrite signal model

- Parameters = $\{f^{(0)}, \{f^{(k)}\}, \alpha, \delta, h_0, \iota, \psi, \Phi_0\}$ 7+s parameters are too heavy.

Frequency evolution Amplitude

$$h(t) = F_+(t; \alpha, \delta, \psi) h_0 \frac{1 + \cos^2 \iota}{2} \cos [\Phi(t) + \Phi_0] + F_\times(t; \alpha, \delta, \psi) h_0 \cos \iota \sin [\Phi(t) + \Phi_0]$$

Antenna pattern functions

$$F_+(t) = \sin \zeta [a(t; \alpha, \delta) \cos(2\psi) + b(t; \alpha, \delta) \sin(2\psi)]$$

$$F_\times(t) = \sin \zeta [b(t; \alpha, \delta) \cos(2\psi) - a(t; \alpha, \delta) \sin(2\psi)]$$

$$h(t) = \sum_{\mu=1}^4 \mathcal{A}^\mu(h_0, \iota, \psi, \Phi_0) h_\mu(t; f^{(0)}, \{f^{(k)}\}, \alpha, \delta)$$

F-statistic = likelihood ratio maximized over A^μ

Likelihood ratio can be rewritten by

$$\ln \Lambda = A^\mu x_\mu - \frac{1}{2} A^\mu \mathcal{M}_{\mu\nu} A^\nu \quad \text{with} \quad x_\mu = (s|h_\mu), \quad \mathcal{M}_{\mu\nu} = (h_\mu|h_\nu)$$

Easily maximized over $\{A^\mu\}$ *Depending only on $\{f^{(0)}, \{f^{(k)}\}, \alpha, \delta\}$*

F-statistic

$$2\mathcal{F} := \max_A [\ln \Lambda] = x_\mu \mathcal{M}^{\mu\nu} x_\nu$$

$\mathcal{M}^{\mu\nu}$: inverse matrix of $\mathcal{M}_{\mu\nu}$

Using F-statistic, we can reduce the dimension of the parameter space by 4.

Statistics of F-statistic

F-statistic $2\mathcal{F} = x_\mu \mathcal{M}^{\mu\nu} x_\nu \sim Z_1^2 + Z_2^2 + Z_3^2 + Z_4^2$

In the absence of signal, $2F$ follows χ^2 distribution with 4 d.o.f

$$\mathbb{E}[2\mathcal{F}|0] = 4, \quad \text{Var}[2\mathcal{F}|0] = 8$$

If signal exists, $2F$ follows non-central χ^2 distribution with 4 d.o.f and non-centrality of $(h|h)$

$$\mathbb{E}[2\mathcal{F}|h] = 4 + (h|h), \quad \text{Var}[2\mathcal{F}|h] = 8 + 4(h|h)$$

$$\text{SNR} = \frac{\mathbb{E}[2\mathcal{F}|h] - \mathbb{E}[2\mathcal{F}|0]}{\sqrt{\text{Var}[2\mathcal{F}|0]}} = \frac{(h|h)}{2\sqrt{2}}$$

Semi-coherent F-statistic

Divide data into N segments and sum all F-statistics over all segments

$$2\mathcal{F}_{\text{tot}} = \sum_{\ell=1}^N 2\mathcal{F}_{\ell}$$

In the absence of signal, $2F$ follows χ^2 distribution with $4N$ d.o.f

$$\mathbb{E}[2\mathcal{F}_{\text{tot}}|0] = 4N, \quad \text{Var}[2\mathcal{F}_{\text{tot}}|0] = 8N$$

If signal exists, $2F$ follows non-central χ^2 distribution with $4N$ d.o.f and non-centrality of $(h|h)$

$$\mathbb{E}[2\mathcal{F}_{\text{tot}}|h] = 4N + (h|h), \quad \text{Var}[2\mathcal{F}_{\text{tot}}|h] = 8N + 4(h|h)$$

$$\text{SNR}_{\text{semi}} = \frac{\mathbb{E}[2\mathcal{F}_{\text{tot}}|h] - \mathbb{E}[2\mathcal{F}_{\text{tot}}|0]}{\sqrt{\text{Var}[2\mathcal{F}_{\text{tot}}|0]}} = \frac{(h|h)}{2\sqrt{2N}} = \text{SNR} \cdot \frac{1}{\sqrt{N}}$$

This is another explanation why semi-coherent search lose sensitivity.

Frequency Hough

reference

Antonucci *et al.*, *Class.Quant.Grav.*25:184015,2008 (2008)

Astone *et al.*, *Phys.Rev.D*90, 042004 (2014)

Peak map

First of all, we make a periodogram and normalize it by noise PSD.

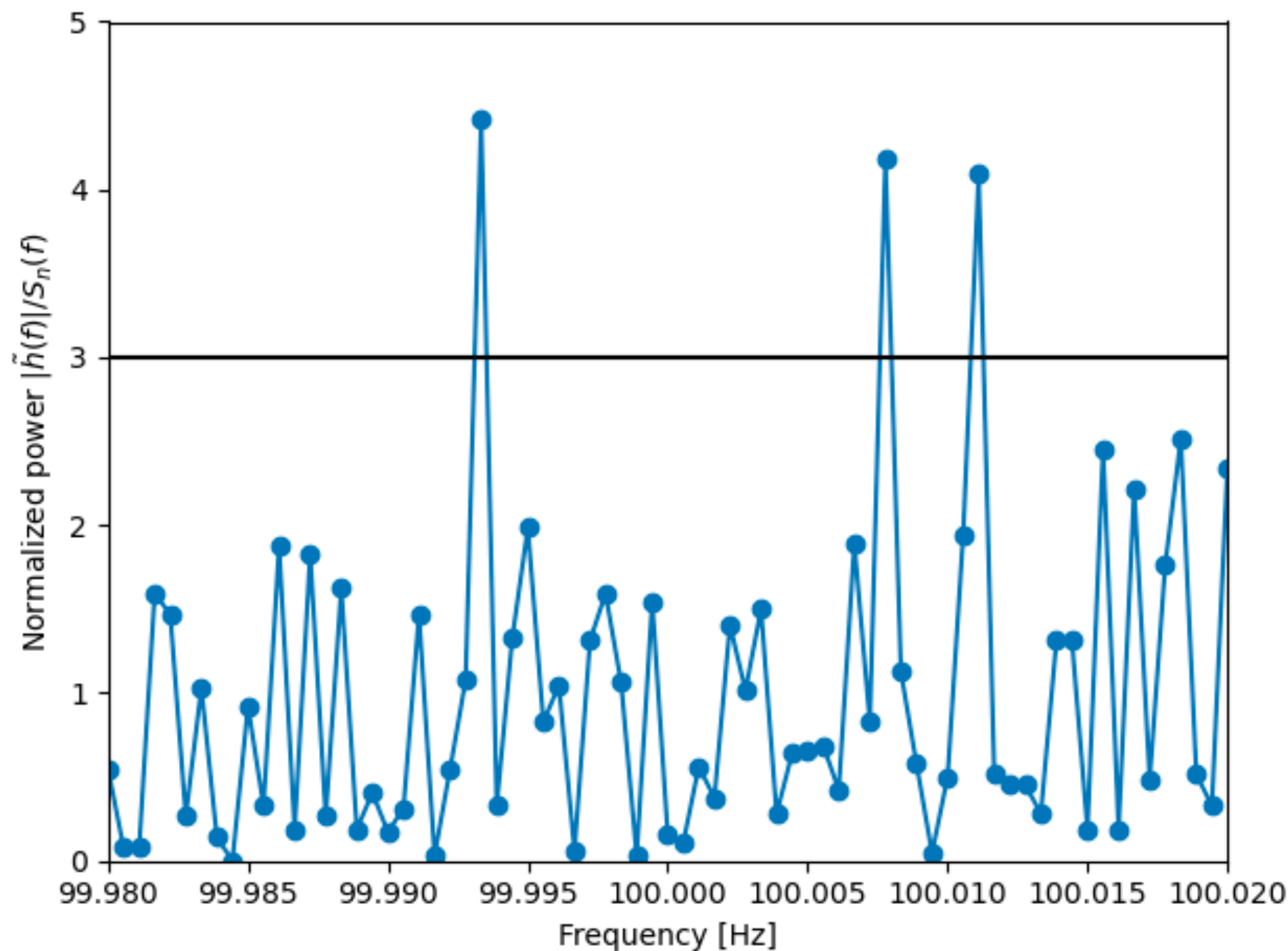
A pixel of the normalized periodogram is classified as a peak if a pixel satisfies two criteria:

(1) the power exceeds the given threshold, and (2) it is a local maxima.

Each pixel in a peak map has a value $\{0, 1\}$.

(Only noise)

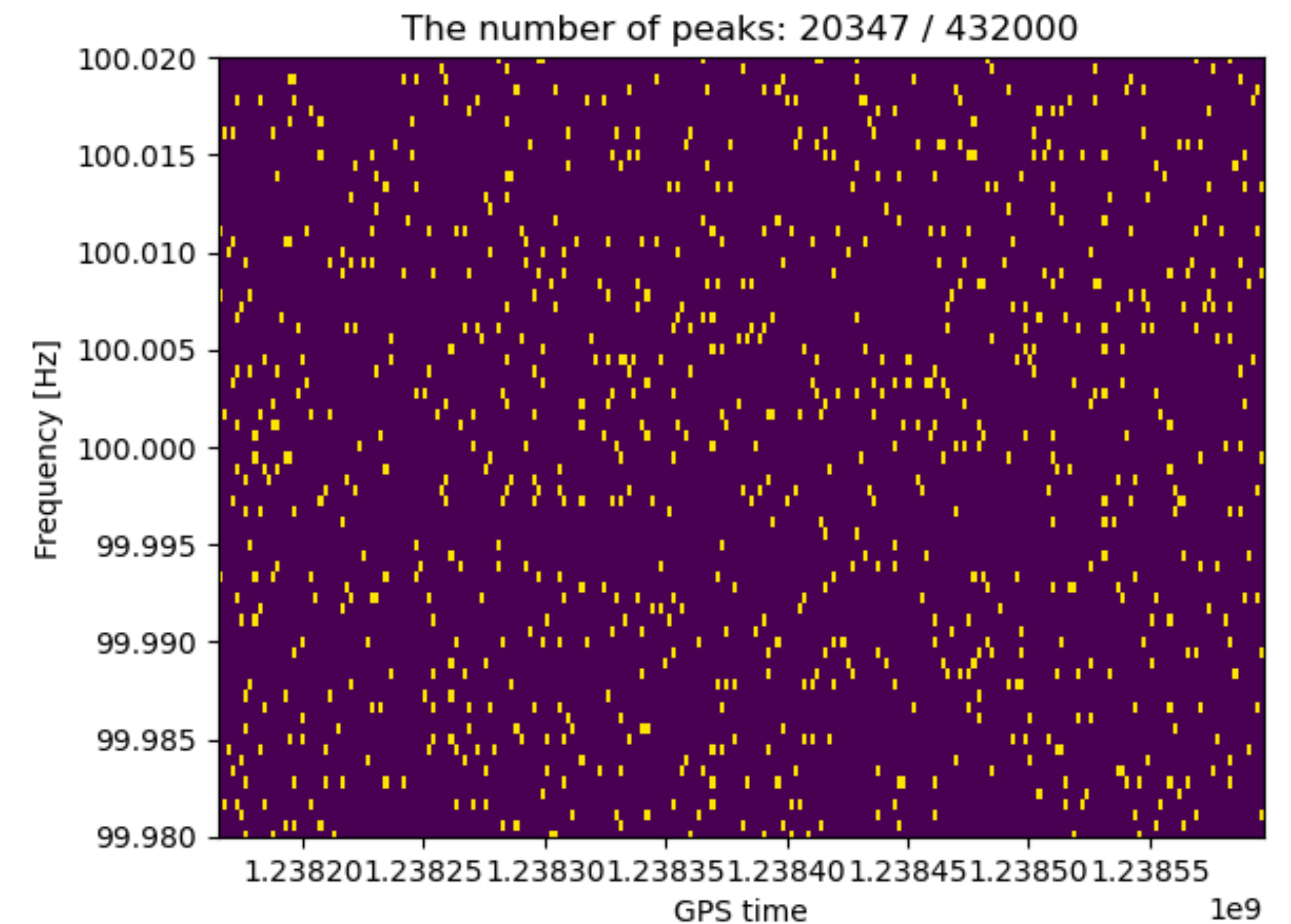
Normalized power
for one SFT segment



Peak map

Yellow: 1

Purple: 0



Hough transform

Assuming the relation between the input plane M and the parameter space Σ ,
Hough transform converts each point in M into a set of points in Σ .
If a point in Σ is consistent to a point in M , it is incremented by one.

For each grid in Σ ,

$$n = \sum_{i=1}^{N_{\text{SFT}}} n_i \quad n_i \in \{0, 1\}$$

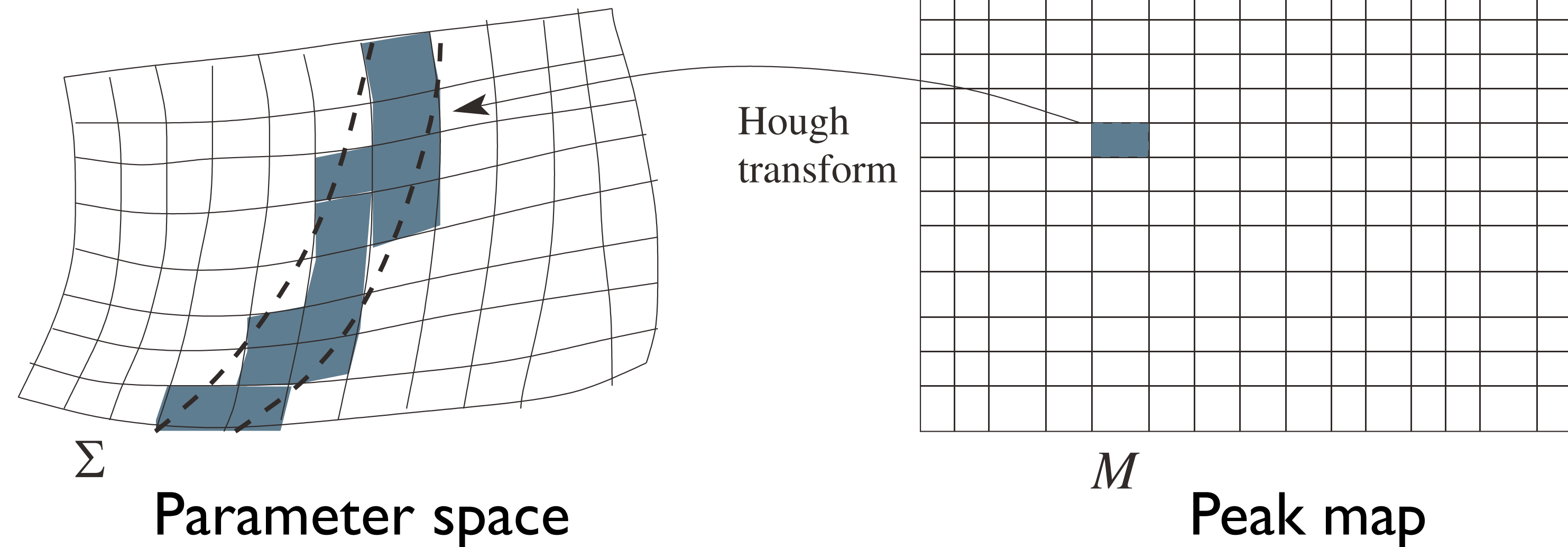
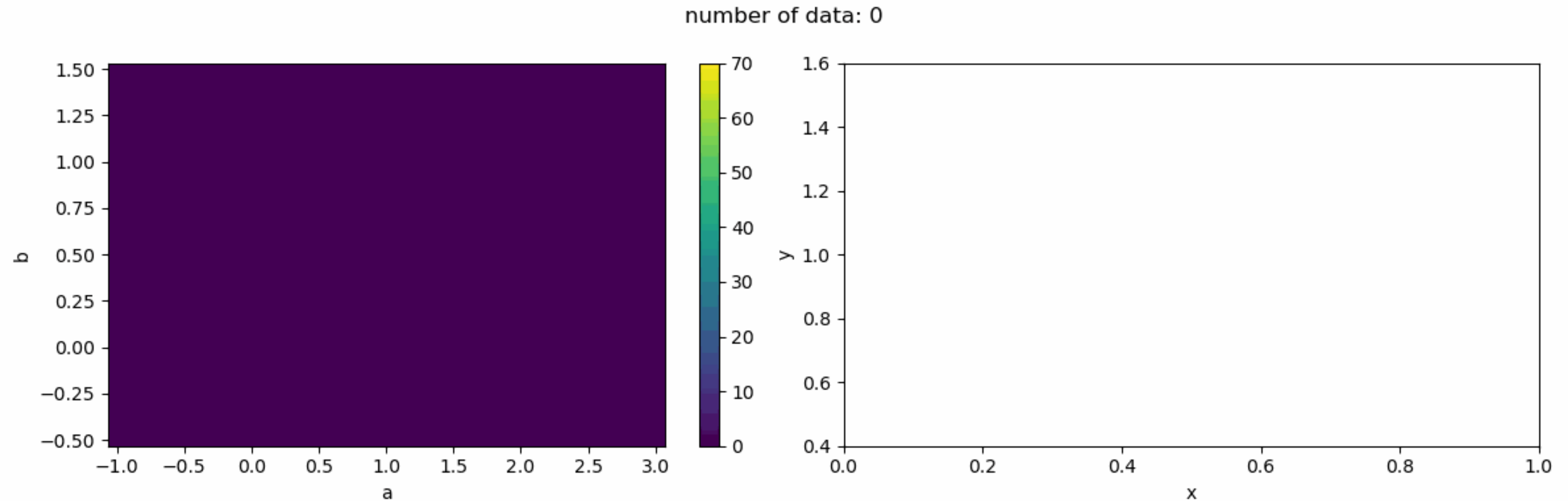


Fig: Krishnan *et al.*, PRD70, 082001

Example: linear function + noise

Data $\{(x_i, y_i)\}$ ($i=1,2,\dots,100$), $y_i = 1.0 * x_i + 0.5 + n_i$, $n_i \sim N(0,0.02)$

We assume the model $y = a * x + b$ and estimate (a, b) .

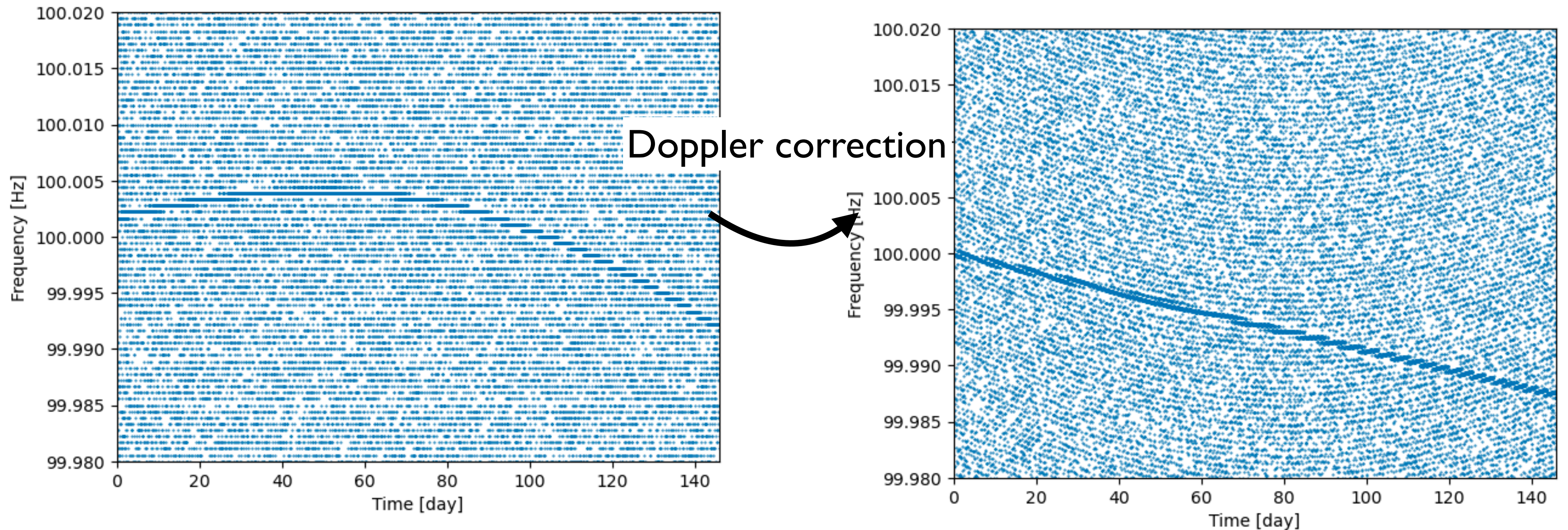


Hough map (parameter space)

Input plane

Doppler correction for peak map

For each grid on the sky, we shift the peak map to demodulate the frequency and make a Hough map. Therefore, we have a Hough map for each grid on the sky.



Hough map

After the Doppler correction $f = f^{(0)} + f^{(1)}(t - t_{\text{ref}}) \Rightarrow f^{(1)} = -\frac{1}{t - t_{\text{ref}}} f^{(0)} + \frac{f}{t - t_{\text{ref}}}$ Straight line in $(f^{(0)}, f^{(1)})$ plane

Accounting the frequency resolution, each peak is transformed into a stripe in parameter space.

For each grid in Σ ,

$$n = \sum_{i=1}^{N_{\text{SFT}}} n_i \quad n_i \in \{0, 1\}$$

Sum is taken over the frequency track consistent with the grid in Σ .

Calculating n for every grids in Σ , we get a Hough map.

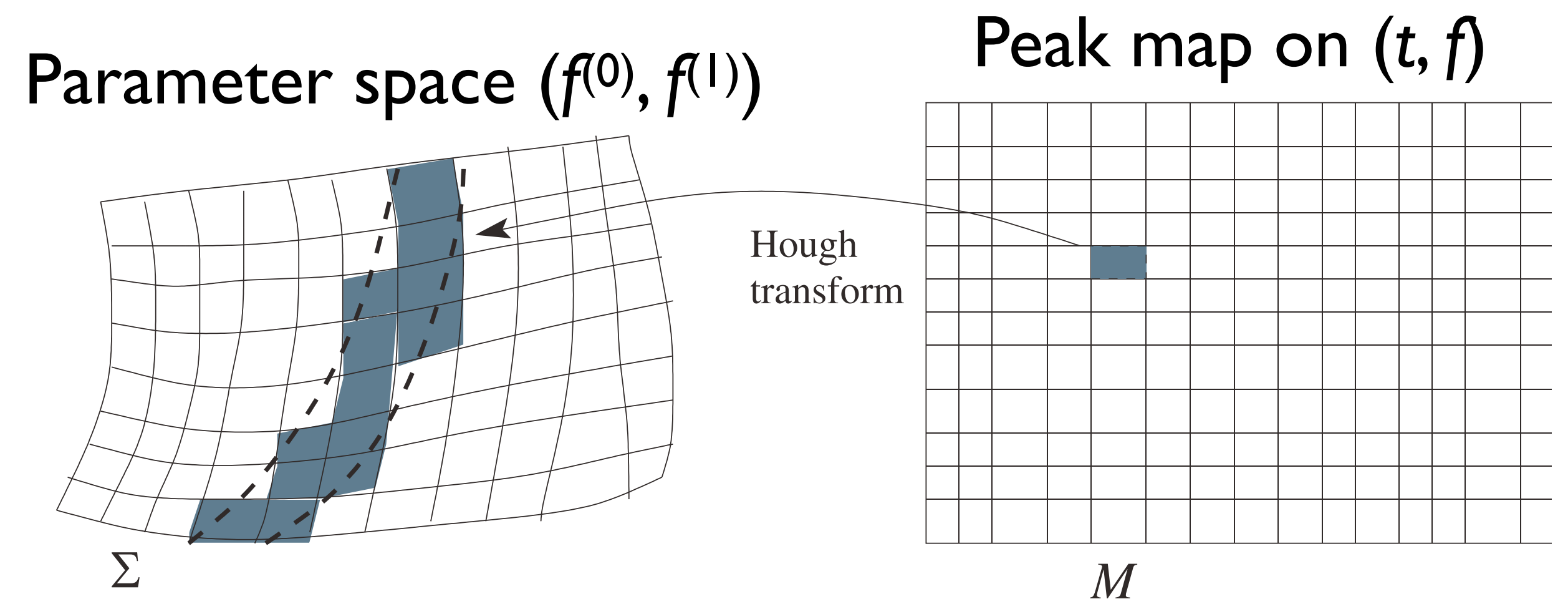


Fig: Krishnan *et al.*, PRD70, 082001

Summary

Summary

- CGWs will provide us with the fruitful information about astrophysics, particle physics, and cosmology.
- Searches for CGWs are challenging due to the computational cost and non-Gaussian noise.
- Various semi-coherent searches are employed to detect CGWs. F-statistic and Hough transform are powerful tools.

I didn't talk the following:

- Targeted, narrow band, and directed searches
- Sophisticated techniques (grid placement, hierarchical algorithm, etc)
- Pre-processing (gating, line cleaning, making SFT database, etc)
- Post-processing (clustering, coincidence, vetos, etc) and follow-up stage
- Many apps in lalsuite
- Machine learning & deep learning approaches

References

- Review articles (recent)

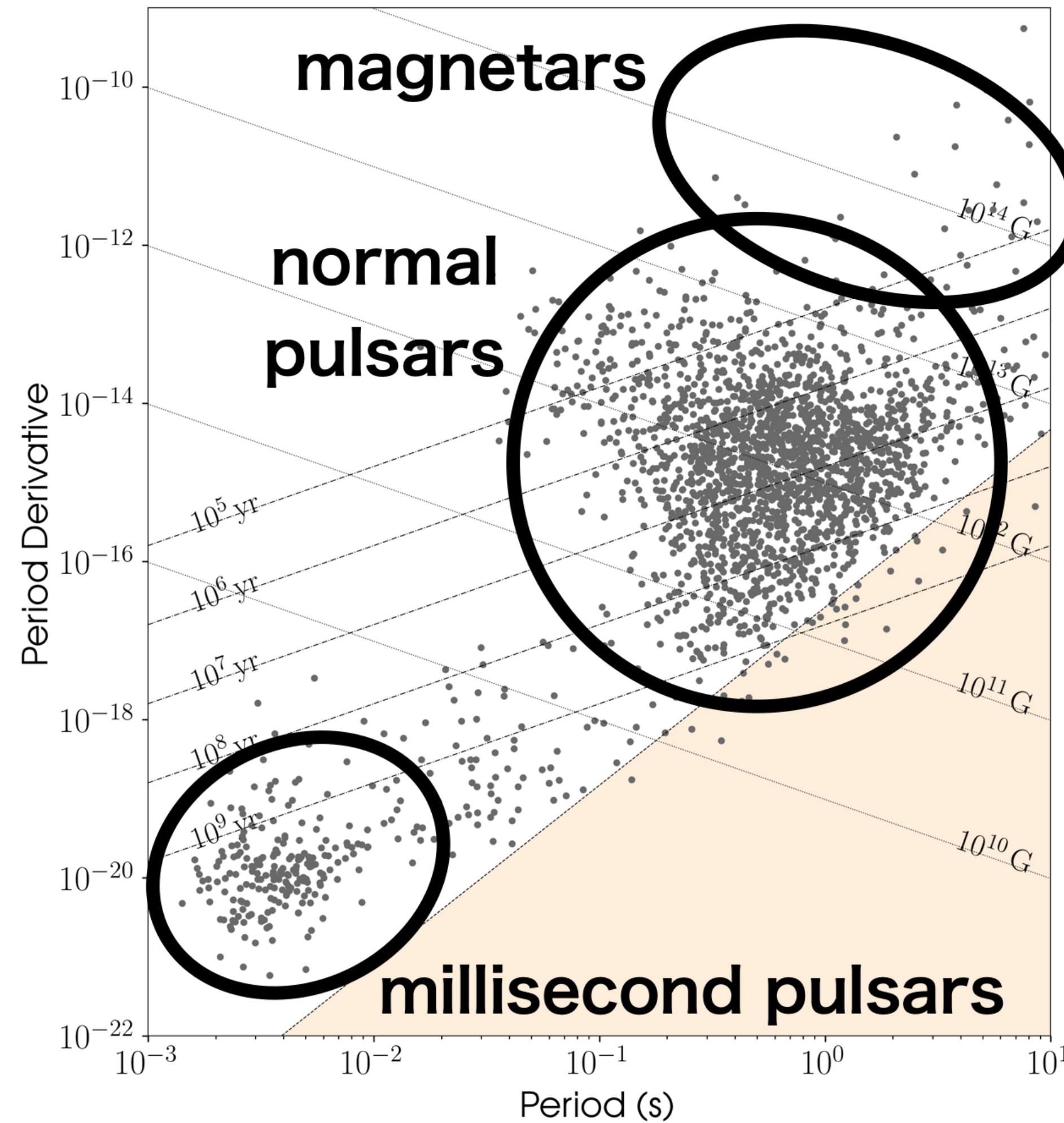
- Sieniawska & Bejger, Universe 2019, 5(11), 217 , arXiv: 1909.12600 [CGWs and neutron stars]
- Tenorio, Keitel & Sintès, Universe 2021, 7(12), 474 , arXiv: 2111.12575 [All-sky searches & post-processing]
- Piccinni, Galaxies 2022, 10(3), 72 , arXiv: 2202.01088 [Sources and search results including DM candidates]
- Wette, Astroparticle Physics 153 (2023) 102880 , arXiv: 2305.07106 [Summary of CGW search results]
- Riles, Living Reviews in Relativity (2023) 26:3 , arXiv: 2206.06447 [Search methods for CGWs]

- Tutorials and slides

- LIGO India Scientific Collaboration (LISC) workshop, YouTube (Jones (1, 2), Wette, Keitel)
- PyFstat, <https://github.com/PyFstat/PyFstat>
- Tutorial on Frequency Hough by Andrew Miller, <https://andrew-l-miller.github.io/post/tutorial/>

Backup

ex. Rotating distorted NS



$$h_0 \simeq 10^{-26} \left(\frac{Q_z}{1.1 \times 10^{45} \text{ g cm}^2} \right) \left(\frac{r}{1 \text{ kpc}} \right)^{-1} \times \left(\frac{f_{\text{gw}}}{100 \text{ Hz}} \right)^2 \left(\frac{\epsilon}{10^{-6}} \right)$$

$$\text{ellipticity } \epsilon := \frac{Q_y - Q_x}{Q_z}$$

current upper lim. $\sim 2 \times 10^{-25}$

$$\begin{aligned} \dot{f}_{\text{gw}} &\sim f_{\text{gw}}^2 |\dot{P}| \\ &\sim 10^{-16} \text{ Hz/sec} \left(\frac{|\dot{P}|}{10^{-20} \text{ sec/sec}} \right) \left(\frac{f_{\text{gw}}}{10^2 \text{ Hz}} \right)^2 \end{aligned}$$

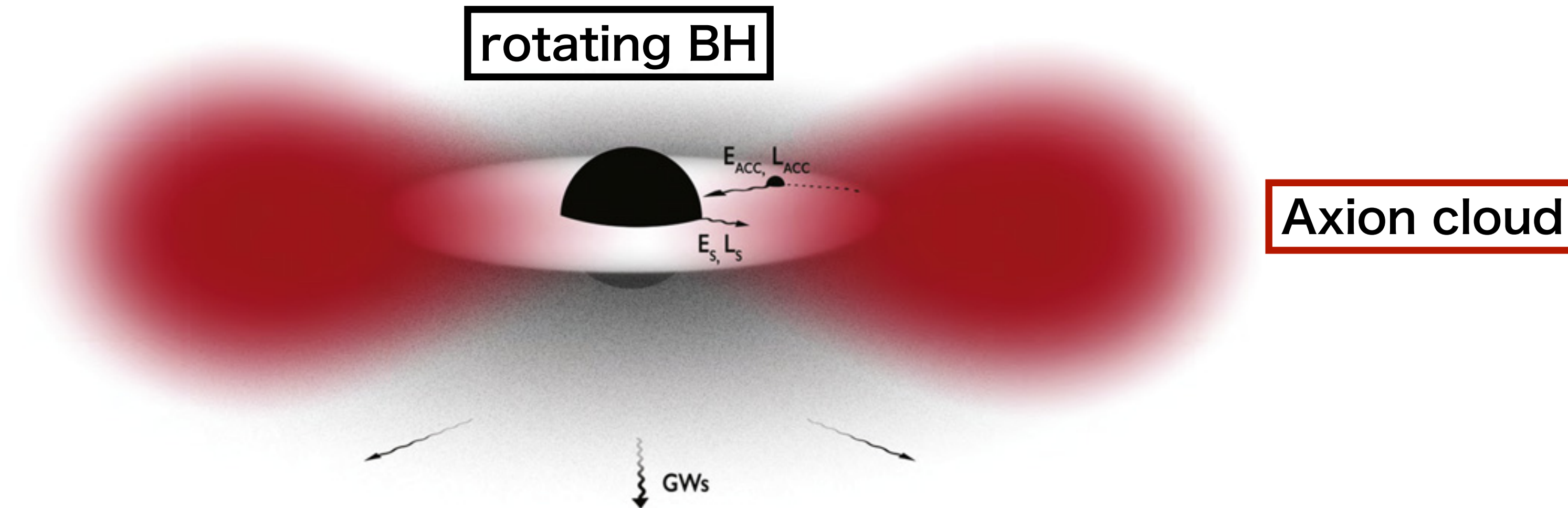
<https://www.atnf.csiro.au/research/pulsar/psrcat/>

Plotted by psrqpy

ex. Axion clouds around BH

Arvanitaki *et al.*, PRD 81, 123530 (2010)

Brito *et al.*, Class. Quantum Grav. 32, 134001 (2015)



$$h_0 \sim 2.1 \times 10^{-25} \left(\frac{\alpha}{0.075} \right)^7 \left(\frac{M_{\text{BH}}}{10M_{\odot}} \right) \left(\frac{1\text{kpc}}{r} \right)$$

$$\alpha := \frac{R_{\text{Sch}}}{\lambda_{\text{axion}}}$$

$$f_{\text{gw}} \sim \frac{2m_{\text{axion}}c^2}{h} \sim 2.5 \times 10^2 \text{ Hz} \left(\frac{m_{\text{axion}}}{10^{-12} \text{ eV}} \right)$$

$$\tau_{\text{GW}} \sim \frac{M_{\text{cloud}}c^2}{\mathcal{L}_{\text{GW}}} \sim 1.9 \times 10^{11} \text{ sec} \left(\frac{\alpha}{0.075} \right)^{-15} \left(\frac{M_{\text{BH}}}{10M_{\odot}} \right)$$

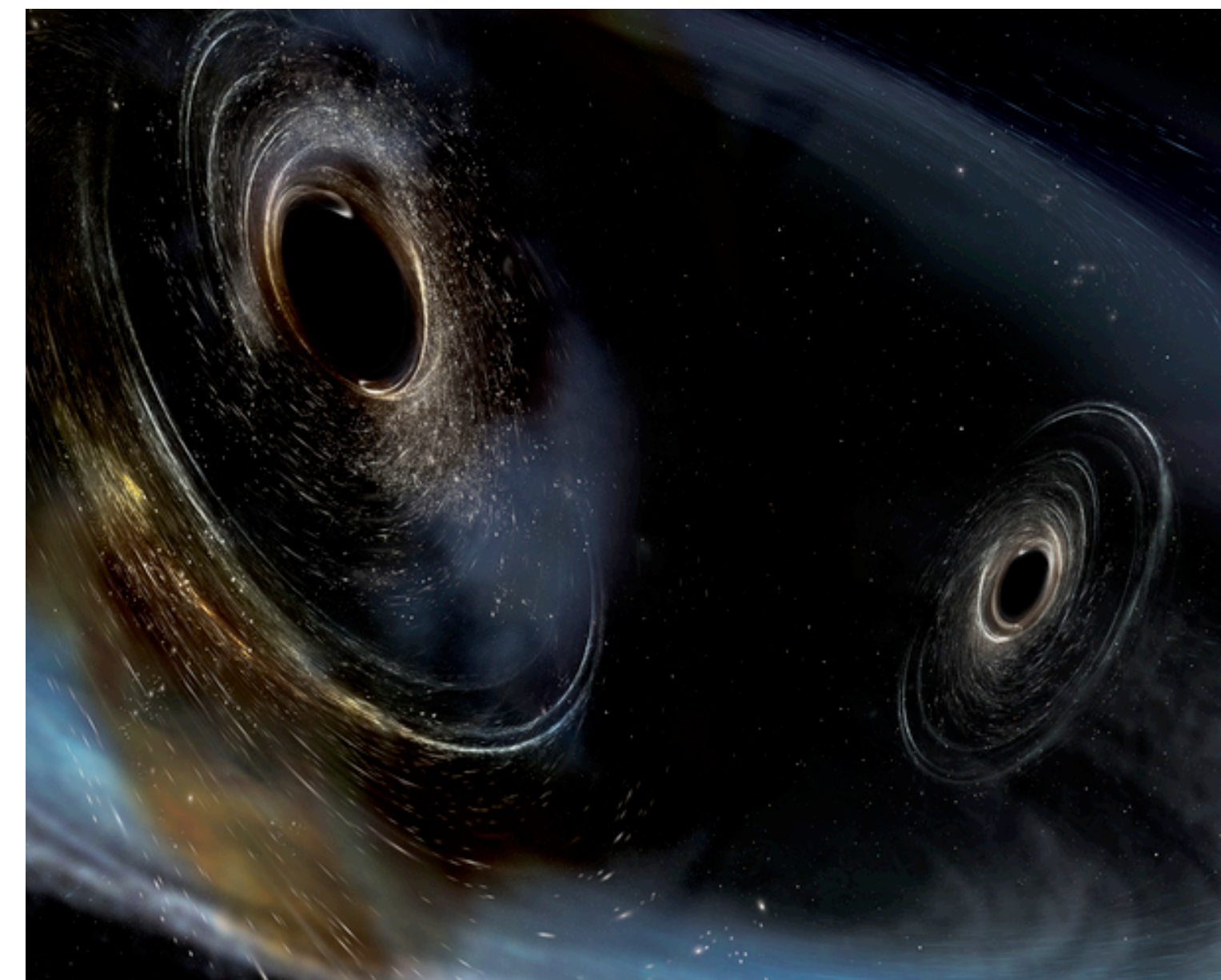
ex. Small mass PBH binaries

of PBHs in our Galaxy (assuming DM consists of PBHs)

$$M_{\text{DM}} \sim 1.7 \times 10^{15} M_{\odot} \left(\frac{R}{3\text{Mpc}} \right) \left(\frac{v}{1500\text{km/s}} \right)$$

$$N_{\text{PBH}} \lesssim \frac{f_{\text{PBH}} M_{\text{DM}}}{m_{\text{PBH}}} \sim 1.7 \times 10^{20} \left(\frac{m_{\text{PBH}}}{10^{-6} M_{\odot}} \right)^{-1}$$

$$n_{\text{PBH}} \lesssim \frac{N_{\text{PBH}}}{R^3} \sim 6\text{pc}^{-3}$$



if PBHs form a binary,

$$h_0 \sim 2 \times 10^{-25} \left(\frac{\mathcal{M}_c}{10^{-6} M_{\odot}} \right)^{5/3} \left(\frac{f_{\text{gw}}}{100\text{Hz}} \right)^{2/3} \left(\frac{r}{1\text{pc}} \right)^{-1}$$

$$\dot{f}_{\text{gw}} \sim 10^{-9} \text{ Hz/sec} \left(\frac{\mathcal{M}_c}{10^{-6} M_{\odot}} \right)^{5/3} \left(\frac{f_{\text{gw}}}{100 \text{ Hz}} \right)^{11/3}$$

Fig: LIGO